Fundamentals of Artificial Intelligence Chapter 12: **Knowledge Representation**

Roberto Sebastiani

DISI, Università di Trento, Italy - roberto.sebastiani@unitn.it http://disi.unitn.it/rseba/DIDATTICA/fai_2022/

Teaching assistant: Mauro Dragoni - dragoni@fbk.eu http://www.maurodragoni.com/teaching/fai/

M.S. Course "Artificial Intelligence Systems", academic year 2022-2023

Last update: Friday 2nd December, 2022, 14:48

Copyright notice: Most examples and images displayed in the slides of this course are taken from [Russell & Norwig, "Artificial Intelligence, a Modern Approach", 3rd ed., Pearson], including explicitly figures from the above-mentioned book, so that their copyright is detained by the authors. A few other material (text, figures, examples) is authored by (in alphabetical order): Pieter Abbeel, Bonnie J. Dorr, Anca Dragan, Dan Klein, Nikita Kitaev, Tom Lenaerts, Michela Milano, Dana Nau, Maria Simi, who detain its copyright.

These slides cannot be displayed in public without the permission of the author.

Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

- how do we organize such content?
- how do we represent facts about the world?
- A whole Al field: Knowledge Representation, KR
 - often combined with Automated Reasoning on KB
 - ⇒ Knowledge Representation & Reasoning, KRR
- KR: use FOL to represent the most important aspects of the real world, such as: action, space, time, knowledge, belief
- Topics:
 - ontologies and ontological engineering
 - objects and categories, composite objects, measurements, ...
 - actions and change, events, temporal intervals, ...
 - reasoning about knowledge & beliefs
 - reasoning about categories
 - default reasoning
 - .

- how do we organize such content?
- how do we represent facts about the world?
- A whole Al field: Knowledge Representation, KR
 - often combined with Automated Reasoning on KB
 - ⇒ Knowledge Representation & Reasoning, KRR
- KR: use FOL to represent the most important aspects of the real world, such as: action, space, time, knowledge, belief
- Topics:
 - ontologies and ontological engineering
 - objects and categories, composite objects, measurements, ...
 - actions and change, events, temporal intervals, ...
 - reasoning about knowledge & beliefs
 - reasoning about categories
 - default reasoning
 - .

- how do we organize such content?
- how do we represent facts about the world?
- A whole Al field: Knowledge Representation, KR
 - often combined with Automated Reasoning on KB
 - ⇒ Knowledge Representation & Reasoning, KRR
- KR: use FOL to represent the most important aspects of the real world, such as: action, space, time, knowledge, belief
- Topics:
 - ontologies and ontological engineering
 - objects and categories, composite objects, measurements, ...
 - actions and change, events, temporal intervals, ...
 - reasoning about knowledge & beliefs
 - reasoning about categories
 - default reasoning
 - .

- how do we organize such content?
- how do we represent facts about the world?
- A whole Al field: Knowledge Representation, KR
 - often combined with Automated Reasoning on KB
 - ⇒ Knowledge Representation & Reasoning, KRR
- KR: use FOL to represent the most important aspects of the real world, such as: action, space, time, knowledge, belief
- Topics:
 - ontologies and ontological engineering
 - objects and categories, composite objects, measurements, ...
 - actions and change, events, temporal intervals, ...
 - reasoning about knowledge & beliefs
 - reasoning about categories
 - default reasoning
 - ..

Knowledge Engineering

- The activity to formalize a specific problem or task domain
- Relevant questions to be addressed:
 - What are the relevant facts, objects, relations ... ?
 - Which is the right level of abstraction?
 - What are the queries to the KB (inferences)?

- The activity to build general-purpose ontologies
- In non trivial domains, received.
- simulations of the second
- Several attempts to build general-purpose ontologies
 - GYC, DBpedia, TextRunner, .
 - not very successful so far

Knowledge Engineering

- The activity to formalize a specific problem or task domain
- Relevant questions to be addressed:
 - What are the relevant facts, objects, relations ... ?
 - Which is the right level of abstraction?
 - What are the queries to the KB (inferences)?

- The activity to build general-purpose ontologies
 - should be applicable in any special-purpose domain (with the addition of domain-specific axioms)
 - In non trivial domains, reasoning and problem solving could involve several areas of knowledge simultaneously
 - ⇒ different areas of knowledge must be combined
- Several attempts to build general-purpose ontologies
 - CYC, DBpedia, TextRunner, ...
 - not very successful so far

Knowledge Engineering

- The activity to formalize a specific problem or task domain
- Relevant questions to be addressed:
 - What are the relevant facts, objects, relations ... ?
 - Which is the right level of abstraction?
 - What are the queries to the KB (inferences)?

- The activity to build general-purpose ontologies
 - should be applicable in any special-purpose domain (with the addition of domain-specific axioms)
 - In non trivial domains, reasoning and problem solving could involve several areas of knowledge simultaneously
 - different areas of knowledge must be combined
- Several attempts to build general-purpose ontologies
 - CYC, DBpedia, TextRunner, ...
 - not very successful so far

Knowledge Engineering

- The activity to formalize a specific problem or task domain
- Relevant questions to be addressed:
 - What are the relevant facts, objects, relations ... ?
 - Which is the right level of abstraction?
 - What are the queries to the KB (inferences)?

- The activity to build general-purpose ontologies
 - should be applicable in any special-purpose domain (with the addition of domain-specific axioms)
 - In non trivial domains, reasoning and problem solving could involve several areas of knowledge simultaneously
 - ⇒ different areas of knowledge must be combined
- Several attempts to build general-purpose ontologies
 - CYC, DBpedia, TextRunner, ...
 - not very successful so far

Knowledge Engineering

- The activity to formalize a specific problem or task domain
- Relevant questions to be addressed:
 - What are the relevant facts, objects, relations ... ?
 - Which is the right level of abstraction?
 - What are the queries to the KB (inferences)?

- The activity to build general-purpose ontologies
 - should be applicable in any special-purpose domain (with the addition of domain-specific axioms)
 - In non trivial domains, reasoning and problem solving could involve several areas of knowledge simultaneously
 - ⇒ different areas of knowledge must be combined
- Several attempts to build general-purpose ontologies
 - CYC, DBpedia, TextRunner, ...
 - not very successful so far

Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

- KR requires the organisation of objects into categories
 - interaction at the level of the object
 - reasoning at the level of categories
 - ex: typically we want to buy a basketball, rather than a particular basketball instance
- Categories play a role in predictions about objects
 - agent infers the presence of certain objects from perceptual input
 - infers category from the perceived properties of the objects,
 - uses category information to make predictions about the objects
- Categories can be represented in two ways by FOL
 - predicates (ex Basketball(x)): relations
 - reification of categories into objects (ex Basketballs): sets
 - ⇒ allows categories to be argument of predicates/functions
- Membership of a category as set membership
 - ex: Member(b, Basketballs) (abbr. $b \in Basketballs$)
- Subcategories (aka subclasses) are (strict) subsets
 - ex: Subset(Basketballs, Balls) (abbr. Basketballs ⊂ Balls)

- KR requires the organisation of objects into categories
 - interaction at the level of the object
 - reasoning at the level of categories
 - ex: typically we want to buy a basketball, rather than a particular basketball instance
- Categories play a role in predictions about objects
 - agent infers the presence of certain objects from perceptual input
 - infers category from the perceived properties of the objects,
 - uses category information to make predictions about the objects
- Categories can be represented in two ways by FOL
 - predicates (ex Basketball(x)): relations
 - reification of categories into objects (ex Basketballs): sets
 - allows categories to be argument of predicates/functions
- Membership of a category as set membership
 - ex: Member(b, Basketballs) (abbr. $b \in Basketballs$)
- Subcategories (aka subclasses) are (strict) subsets
 - ex: Subset(Basketballs, Balls) (abbr. Basketballs ⊂ Balls)

- KR requires the organisation of objects into categories
 - interaction at the level of the object
 - reasoning at the level of categories
 - ex: typically we want to buy a basketball, rather than a particular basketball instance
- Categories play a role in predictions about objects
 - agent infers the presence of certain objects from perceptual input
 - infers category from the perceived properties of the objects,
 - uses category information to make predictions about the objects
- Categories can be represented in two ways by FOL
 - predicates (ex Basketball(x)): relations
 - reification of categories into objects (ex Basketballs): sets
 - ⇒ allows categories to be argument of predicates/functions
- Membership of a category as set membership
 - ex: Member(b, Basketballs) (abbr. $b \in Basketballs$)
- Subcategories (aka subclasses) are (strict) subsets
 - ex: Subset(Basketballs, Balls) (abbr. Basketballs ⊂ Balls)

- KR requires the organisation of objects into categories
 - interaction at the level of the object
 - reasoning at the level of categories
 - ex: typically we want to buy a basketball, rather than a particular basketball instance
- Categories play a role in predictions about objects
 - agent infers the presence of certain objects from perceptual input
 - infers category from the perceived properties of the objects,
 - uses category information to make predictions about the objects
- Categories can be represented in two ways by FOL
 - predicates (ex Basketball(x)): relations
 - reification of categories into objects (ex Basketballs): sets
 - ⇒ allows categories to be argument of predicates/functions
- Membership of a category as set membership
 - ex: Member(b, Basketballs) (abbr. $b \in Basketballs$)
- Subcategories (aka subclasses) are (strict) subsets
 - ex: Subset(Basketballs, Balls) (abbr. Basketballs ⊂ Balls)

- KR requires the organisation of objects into categories
 - interaction at the level of the object
 - reasoning at the level of categories
 - ex: typically we want to buy a basketball, rather than a particular basketball instance
- Categories play a role in predictions about objects
 - agent infers the presence of certain objects from perceptual input
 - infers category from the perceived properties of the objects,
 - uses category information to make predictions about the objects
- Categories can be represented in two ways by FOL
 - predicates (ex Basketball(x)): relations
 - reification of categories into objects (ex Basketballs): sets
 - ⇒ allows categories to be argument of predicates/functions
- Membership of a category as set membership
 - ex: Member(b, Basketballs) (abbr. $b \in Basketballs$)
- Subcategories (aka subclasses) are (strict) subsets
 - ex: Subset(Basketballs, Balls) (abbr. Basketballs ⊂ Balls)

Inheritance and Taxonomies

- A subcategory inherits the properties of the category
 - ex:

```
if \forall x.(x \in Food \rightarrow Edible(x)), Fruit \subset Food, Apples \subset Fruit then \forall x.(x \in Apple \rightarrow Edible(x))
```

- A member inherits the properties of the category
 - if $a \in Apples$, then Edible(a)
- Subclass relation organize categories into taxonomies (aka taxonomic hierarchies)
 - ex: taxonomy of >10M living&extinct species
 - ex: Dewey Decimal System: taxonomy of all fields of knowledge

Inheritance and Taxonomies

- A subcategory inherits the properties of the category
 - ex:

```
if \forall x.(x \in Food \rightarrow Edible(x)), Fruit \subset Food, Apples \subset Fruit then \forall x.(x \in Apple \rightarrow Edible(x))
```

- A member inherits the properties of the category
 - if $a \in Apples$, then Edible(a)
- Subclass relation organize categories into taxonomies (aka taxonomic hierarchies)
 - ex: taxonomy of >10M living&extinct species
 - ex: Dewey Decimal System: taxonomy of all fields of knowledge

Inheritance and Taxonomies

- A subcategory inherits the properties of the category
 - ex:

```
if \forall x.(x \in Food \rightarrow Edible(x)), Fruit \subset Food, Apples \subset Fruit then \forall x.(x \in Apple \rightarrow Edible(x))
```

- A member inherits the properties of the category
 - if a ∈ Apples, then Edible(a)
- Subclass relation organize categories into taxonomies (aka taxonomic hierarchies)
 - ex: taxonomy of >10M living&extinct species
 - ex: Dewey Decimal System: taxonomy of all fields of knowledge

FOL Reasoning about Categories

- FOL allows to state facts about categories:
 - an object is a member of a category
 BB₉ ∈ Basketballs
 - a category is a subclass of another category Basketballs ⊂ Balls
 - all members of a category have some properties $\forall x. (x \in Basketballs \rightarrow Spherical(x))$
 - members of a category can be recognized by some properties $\forall x.((Orange(x) \land Round(x) \land Diameter(x) = 9.5" \land x \in Balls) \rightarrow x \in Basketballs)$
 - category as a whole has some properties Dogs ∈ DomesticatedSpecies
- New categories can be defined by providing necessary and sufficient conditions for membership
 - $\forall x.(x \in Bachelors \leftrightarrow (Unmarried(x) \land x \in Adults \land x \in Males))$

FOL Reasoning about Categories

- FOL allows to state facts about categories:
 - an object is a member of a category
 BB₉ ∈ Basketballs
 - a category is a subclass of another category Basketballs ⊂ Balls
 - all members of a category have some properties
 ∀x.(x ∈ Basketballs → Spherical(x))
 - members of a category can be recognized by some properties $\forall x.((Orange(x) \land Round(x) \land Diameter(x) = 9.5" \land x \in Balls) \rightarrow x \in Basketballs)$
 - category as a whole has some properties
 Dogs ∈ DomesticatedSpecies
- New categories can be defined by providing necessary and sufficient conditions for membership
 - $\forall x.(x \in Bachelors \leftrightarrow (Unmarried(x) \land x \in Adults \land x \in Males))$

FOL Reasoning about Categories

- FOL allows to state facts about categories:
 - an object is a member of a category
 BB₉ ∈ Basketballs
 - a category is a subclass of another category Basketballs ⊂ Balls
 - all members of a category have some properties
 ∀x.(x ∈ Basketballs → Spherical(x))
 - members of a category can be recognized by some properties $\forall x.((Orange(x) \land Round(x) \land Diameter(x) = 9.5" \land x \in Balls) \rightarrow x \in Basketballs)$
 - category as a whole has some properties
 Dogs ∈ DomesticatedSpecies
- New categories can be defined by providing necessary and sufficient conditions for membership
 - $\forall x. (x \in Bachelors \leftrightarrow (Unmarried(x) \land x \in Adults \land x \in Males))$

Derived relations

Two or more categories in a set s are disjoint iff they have no members in common

```
• Disjoint(s) \leftrightarrow (\forall c_1 c_2. ((c_1 \in s \land c_2 \in s \land c_1 \neq c_2) \rightarrow Intersection(c_1, c_2) = \emptyset)
```

- ex: Disjoint({Animals, Vegetables}), Disjoint({Insects, Birds, Mammals, Reptiles}),
- A set of categories s is an exhaustive decomposition of a category c iff all members of c are covered by categories in s
 - ExaustiveDecomposition $(s, c) \leftrightarrow \forall i. (i \in c \leftrightarrow (\exists c_2. (c_2 \in s \land i \in c_2)))$
 - ex: E.D.({Americans, Canadians, Mexicans}, NorthAmericans)
- A disjoint exhaustive decomposition is a partition
 - $Partition(s, c) \leftrightarrow (Disjoint(s) \land ExhaustiveDecomposition(s, c))$
 - ex: Partition({NorthernItalians, CentralItalians, SouthernItalians, InsularItalians}, Italians)

Derived relations

Two or more categories in a set s are disjoint iff they have no members in common

```
• Disjoint(s) \leftrightarrow (\forall c_1 c_2. ((c_1 \in s \land c_2 \in s \land c_1 \neq c_2) \rightarrow Intersection(c_1, c_2) = \emptyset)
```

- ex: Disjoint({Animals, Vegetables}), Disjoint({Insects, Birds, Mammals, Reptiles}),
- A set of categories s is an exhaustive decomposition of a category c iff all members of c are covered by categories in s
 - ExaustiveDecomposition $(s, c) \leftrightarrow \forall i. (i \in c \leftrightarrow (\exists c_2. (c_2 \in s \land i \in c_2)))$
 - ex: E.D.({Americans, Canadians, Mexicans}, NorthAmericans)
- A disjoint exhaustive decomposition is a partition
 - $Partition(s, c) \leftrightarrow (Disjoint(s) \land ExhaustiveDecomposition(s, c))$
 - ex: Partition({NorthernItalians, CentralItalians, SouthernItalians, InsularItalians}, Italians)

Derived relations

Two or more categories in a set s are disjoint iff they have no members in common

```
• \textit{Disjoint}(s) \leftrightarrow (\forall c_1 c_2. ((c_1 \in s \land c_2 \in s \land c_1 \neq c_2) \rightarrow \textit{Intersection}(c_1, c_2) = \emptyset)
```

- ex: Disjoint({Animals, Vegetables}), Disjoint({Insects, Birds, Mammals, Reptiles}),
- A set of categories s is an exhaustive decomposition of a category c iff all members of c are covered by categories in s
 - ExaustiveDecomposition $(s, c) \leftrightarrow \forall i.(i \in c \leftrightarrow (\exists c_2.(c_2 \in s \land i \in c_2)))$
 - ex: E.D.({Americans, Canadians, Mexicans}, NorthAmericans)
- A disjoint exhaustive decomposition is a partition
 - $Partition(s, c) \leftrightarrow (Disjoint(s) \land ExhaustiveDecomposition(s, c))$
 - ex: Partition({NorthernItalians, CentralItalians, SouthernItalians, InsularItalians}, Italians)

- Many categories have no clear-cut definition (ex: chair, bush, ...)
 - Ex: tomatoes are sometimes green, red, yellow, black; they are mostly round
- One useful solution: category "Typical(.)", s.t. Typical(c) $\subseteq c$
 - → most knowledge about natural kinds will actually be about their typical instances
 - ex: $\forall x.(x \in \mathit{Typical}(\mathit{Tomatoes}) \rightarrow (\mathit{Red}(x) \land \mathit{Round}(x)))$
- \implies We can write down useful facts about categories without providing exact definitions

Note

Quine (1953) challenged the utility of the notion of strict definition

- Ex: "bachelor": is the Pope a bachelor?
 - ⇒ technically yes, but misleading

- Many categories have no clear-cut definition (ex: chair, bush, ...)
 - Ex: tomatoes are sometimes green, red, yellow, black; they are mostly round
- One useful solution: category "Typical(.)", s.t. Typical(c) $\subseteq c$
 - most knowledge about natural kinds will actually be about their typical instances
 - ex: $\forall x.(x \in \mathit{Typical}(\mathit{Tomatoes}) \rightarrow (\mathit{Red}(x) \land \mathit{Round}(x)))$
- \implies We can write down useful facts about categories without providing exact definitions

Note

Quine (1953) challenged the utility of the notion of strict definition

- Ex: "bachelor": is the Pope a bachelor?
 - ⇒ technically yes, but misleading

- Many categories have no clear-cut definition (ex: chair, bush, ...)
 - Ex: tomatoes are sometimes green, red, yellow, black; they are mostly round
- One useful solution: category "Typical(.)", s.t. $Typical(c) \subseteq c$
 - → most knowledge about natural kinds will actually be about their typical instances
 - ex: $\forall x.(x \in \textit{Typical}(\textit{Tomatoes}) \rightarrow (\textit{Red}(x) \land \textit{Round}(x)))$
- ⇒ We can write down useful facts about categories without providing exact definitions

Note

Quine (1953) challenged the utility of the notion of strict definition

- Ex: "bachelor": is the Pope a bachelor?
 - ⇒ technically yes, but misleading

- Many categories have no clear-cut definition (ex: chair, bush, ...)
 - Ex: tomatoes are sometimes green, red, yellow, black; they are mostly round
- One useful solution: category "Typical(.)", s.t. Typical(c) $\subseteq c$
 - most knowledge about natural kinds will actually be about their typical instances
 - ex: $\forall x.(x \in Typical(Tomatoes) \rightarrow (Red(x) \land Round(x)))$
- ⇒ We can write down useful facts about categories without providing exact definitions

Note

Quine (1953) challenged the utility of the notion of strict definition.

- Ex: "bachelor": is the Pope a bachelor?
 - ⇒ technically yes, but misleading

- PartOf(.,.) relation: One object may be part of another
 - PartOf(Bucharest, Romania)
 - PartOf(Romania, EasternEurope)
 - PartOf(EasternEurope, Europe)
- PartOf(.,.) is reflexive and transitive:
- $\forall x. PartOf(x, x)$
 - $\forall x, y, z.((PartOf(x, y) \land PartOf(y, z)) \rightarrow PartOf(x, z))$
 - ⇒ PartOf(Bucharest, Europe)
- Categories of composite objects are often characterized by structural relations among parts.
 Ex: Biped

(© S. Russell & P. Norwig, AIMA)

- PartOf(.,.) relation: One object may be part of another
 - PartOf(Bucharest, Romania)
 - PartOf(Romania, EasternEurope)
 - PartOf(EasternEurope, Europe)
- *PartOf*(.,.) is reflexive and transitive:
 - $\forall x. PartOf(x, x)$
 - $\forall x, y, z.((PartOf(x, y) \land PartOf(y, z)) \rightarrow PartOf(x, z))$
 - ⇒ PartOf(Bucharest, Europe)
- Categories of composite objects are often characterized by structural relations among parts.
 Ex: Biped

(© S. Russell & P. Norwig, AIMA)

- PartOf(.,.) relation: One object may be part of another
 - PartOf(Bucharest, Romania)
 - PartOf(Romania, EasternEurope)
 - PartOf(EasternEurope, Europe)
- *PartOf*(.,.) is reflexive and transitive:
 - $\forall x. PartOf(x, x)$
 - $\forall x, y, z.((PartOf(x, y) \land PartOf(y, z)) \rightarrow PartOf(x, z))$
 - ⇒ PartOf(Bucharest, Europe)
- Categories of composite objects are often characterized by structural relations among parts.
 Ex: Biped

$$Biped(a) \Rightarrow \exists l_1, l_2, b \ Leg(l_1) \land Leg(l_2) \land Body(b) \land \\ PartOf(l_1, a) \land PartOf(l_2, a) \land PartOf(b, a) \land \\ Attached(l_1, b) \land Attached(l_2, b) \land \\ l_1 \neq l_2 \land [\forall l_3 \ Leg(l_3) \land PartOf(l_3, a) \Rightarrow (l_3 = l_1 \lor l_3 = l_2)]$$

(© S. Russell & P. Norwig, AIMA)

- PartOf(.,.) relation: One object may be part of another
 - PartOf(Bucharest, Romania)
 - PartOf(Romania, EasternEurope)
 - PartOf(EasternEurope, Europe)
- *PartOf*(.,.) is reflexive and transitive:
 - ∀x.PartOf(x,x)
 - $\forall x, y, z.((PartOf(x, y) \land PartOf(y, z)) \rightarrow PartOf(x, z))$
 - ⇒ PartOf(Bucharest, Europe)
- Categories of composite objects are often characterized by structural relations among parts.
 Ex: Biped

$$\begin{split} Biped(a) & \Rightarrow & \exists \, l_1, l_2, b \; Leg(l_1) \wedge Leg(l_2) \wedge Body(b) \; \wedge \\ & \quad PartOf(l_1, a) \wedge PartOf(l_2, a) \wedge PartOf(b, a) \; \wedge \\ & \quad Attached(l_1, b) \wedge Attached(l_2, b) \; \wedge \\ & \quad l_1 \neq l_2 \wedge [\forall \, l_3 \; Leg(l_3) \wedge PartOf(l_3, a) \; \Rightarrow \; (l_3 = l_1 \vee l_3 = l_2)] \end{split}$$

(© S. Russell & P. Norwig, AIMA)

Measurements

Quantitative Measurements

- Objects may have "quantitative" properties
 - e.g. height, mass, cost, ...
- Values that we assign to these properties are measures
- Can be represented by unit functions
 - ex $Length(L_1) = Inches(1.5) \wedge Inches(1.5) = Centimeters(3.81)$
- Conversion between units:
 - $\forall i$. Centimeters(2.54 \times i) = Inches(i)
- Measures can be used to describe objects:
 - ex: Diameter(Basketball₁₂) = Inches(9.5)
 - ex: ListPrice(Basketball₁₂) = \$(19)
 - ex: $\forall d.(d \in Days \rightarrow Duration(d) = Hours(24))$

- Objects may have "quantitative" properties
 - e.g. height, mass, cost, ...
- Values that we assign to these properties are measures
- Can be represented by unit functions
 - ex $Length(L_1) = Inches(1.5) \land Inches(1.5) = Centimeters(3.81)$
- Conversion between units:
 - $\forall i$. Centimeters(2.54 \times i) = Inches(i)
- Measures can be used to describe objects:
 - ex: Diameter(Basketball₁₂) = Inches(9.5)
 - ex: ListPrice(Basketball₁₂) = \$(19)
 - ex: $\forall d.(d \in Days \rightarrow Duration(d) = Hours(24))$

- Objects may have "quantitative" properties
 - e.g. height, mass, cost, ...
- Values that we assign to these properties are measures
- Can be represented by unit functions
 - ex $Length(L_1) = Inches(1.5) \land Inches(1.5) = Centimeters(3.81)$
- Conversion between units:
 - $\forall i$. Centimeters(2.54 \times i) = Inches(i)
- Measures can be used to describe objects:
 - ex: $Diameter(Basketball_{12}) = Inches(9.5)$
 - ex: ListPrice(Basketball₁₂) = \$(19)
 - ex: $\forall d.(d \in Days \rightarrow Duration(d) = Hours(24))$

- Objects may have "quantitative" properties
 - e.g. height, mass, cost, ...
- Values that we assign to these properties are measures
- Can be represented by unit functions
 - ex Length(L_1) = Inches(1.5) \wedge Inches(1.5) = Centimeters(3.81)
- Conversion between units:
 - $\forall i$. Centimeters(2.54 \times i) = Inches(i)
- Measures can be used to describe objects:
 - ex: Diameter(Basketball₁₀) = Inches(9.5)
 - ex: ListPrice(Basketball₁₂) = \$(19)

 - ex: $\forall d.(d \in Days \rightarrow Duration(d) = Hours(24))$



- Objects may have "quantitative" properties
 - e.g. height, mass, cost, ...
- Values that we assign to these properties are measures
- Can be represented by unit functions
 - ex $Length(L_1) = Inches(1.5) \land Inches(1.5) = Centimeters(3.81)$
- Conversion between units:
 - $\forall i$. Centimeters(2.54 \times i) = Inches(i)
- Measures can be used to describe objects:
 - ex: Diameter(Basketball₁₂) = Inches(9.5)
 - ex: ListPrice(Basketball₁₂) = \$(19)
 - ex: $\forall d.(d \in \textit{Days} \rightarrow \textit{Duration}(d) = \textit{Hours}(24))$

Measurements [cont.]

Qualitative Measurements

- Some measures have no scale
 - ex: beauty, deliciousness, difficulty,...
- Most important aspect of measures: they are orderable
 - Ex: Deliciousness(SacherTorte) > Deliciousness(BrussellSprout)
 - Ex: Beauty(PaulNewmann) > Beauty(MartyFeldman)
 - Ex: Difficulty(Prove_P \neq NP) > Difficulty(SolvePuzzle)
- Allow for reasoning by exploiting transitivity of monotonicity:

```
\forall e_1 e_2. ((e_1 \in Exercises \land e_2 \in Exercises \land Wrote(Norvig, e_1) \land Wrote(Russell, e_2)) \rightarrow Difficulty(e_1) > Difficulty(e_2))
```

 $\forall e_1 e_2.((e_1 \in Exercises \land e_2 \in Exercises \land Difficulty(e_1) > Difficulty(e_2))$

 \rightarrow ExpectedScore(e_1) < ExpectedScore(e_2)

 $(e_1 e_2 \cdot (ExpectedScore(e_1) < ExpectedScore(e_2) \rightarrow Pick(e_1, e_2) = e_2)$

Then: $(Wrote(Norvig, E_1) \land Wrote(Russell, E_2)) \models Pick(E_1, E_2) = E_2$

 Qualitative physics: a subfield of AI that investigates how to reason about physical systems without numerical computations

Measurements [cont.]

Qualitative Measurements

- Some measures have no scale
 - ex: beauty, deliciousness, difficulty,...
- Most important aspect of measures: they are orderable
 - Ex: Deliciousness(SacherTorte) > Deliciousness(BrussellSprout)
 - Ex: Beauty(PaulNewmann) > Beauty(MartyFeldman)
 - Ex: Difficulty(Prove_P≠NP) > Difficulty(SolvePuzzle)
- Allow for reasoning by exploiting transitivity of monotonicity:

```
 \forall e_1e_2.((e_1 \in Exercises \land e_2 \in Exercises \land \textit{Wrote}(\textit{Norvig}, e_1) \land \textit{Wrote}(\textit{Russell}, e_2)) \\ \rightarrow \textit{Difficulty}(e_1) > \textit{Difficulty}(e_2)) \\ \forall e_1e_2.((e_1 \in Exercises \land e_2 \in Exercises \land \textit{Difficulty}(e_1) > \textit{Difficulty}(e_2)) \\ \rightarrow \textit{ExpectedScore}(e_1) < \textit{ExpectedScore}(e_2)) \\ \forall e_1e_2.(ExpectedScore(e_1) < ExpectedScore(e_2) \rightarrow \textit{Pick}(e_1, e_2) = e_2 \\ \text{Then: } (\textit{Wrote}(\textit{Norvig}, E_1) \land \textit{Wrote}(\textit{Russell}, E_2)) \models \textit{Pick}(E_1, E_2) = E_2
```

 Qualitative physics: a subfield of AI that investigates how to reason about physical systems without numerical computations

Measurements [cont.]

Qualitative Measurements

- Some measures have no scale
 - ex: beauty, deliciousness, difficulty,...
- Most important aspect of measures: they are orderable
 - Ex: Deliciousness(SacherTorte) > Deliciousness(BrussellSprout)
 - Ex: Beauty(PaulNewmann) > Beauty(MartyFeldman)
 - Ex: Difficulty(Prove_P≠NP) > Difficulty(SolvePuzzle)
- Allow for reasoning by exploiting transitivity of monotonicity:

```
 \forall e_1e_2.((e_1 \in Exercises \land e_2 \in Exercises \land Wrote(Norvig, e_1) \land Wrote(Russell, e_2)) \\ \rightarrow Difficulty(e_1) > Difficulty(e_2)) \\ \forall e_1e_2.((e_1 \in Exercises \land e_2 \in Exercises \land Difficulty(e_1) > Difficulty(e_2)) \\ \rightarrow ExpectedScore(e_1) < ExpectedScore(e_2)) \\ \forall e_1e_2.(ExpectedScore(e_1) < ExpectedScore(e_2) \rightarrow Pick(e_1, e_2) = e_2 \\ \text{Then: } (Wrote(Norvig, E_1) \land Wrote(Russell, E_2)) \models Pick(E_1, E_2) = E_2
```

 Qualitative physics: a subfield of AI that investigates how to reason about physical systems without numerical computations

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- \implies Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
 - Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
 - Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- \implies Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
- Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
- Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- → Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
 - Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
 - Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- → Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
 - Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
 - Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- → Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
 - Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
 - Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

- There are countable objects
 - e,g, apples, holes, theorems, ...
- ... and mass objects, aka stuff or substances
 - e.g. butter, water, energy, ...
- → Intuitive meaning "an amount/quantity of..."
 - ex: b ∈ butter: "b is an amount/quantity of butter"
 - Any part of stuff is still stuff:
 - ex: $\forall b, p.((b \in Butter \land PartOf(p, b)) \rightarrow p \in Butter)$
 - Can define sub-categories, which are stuff
 - ex: UnsaltedButter ⊂ Butter
 - Stuff has a number of intrinsic properties, shared by its subparts
 - e.g., color, fat content, density ...
 - ex: $\forall b.(b \in Butter \rightarrow MeltingPoint(b, Centigrade(30)))$
 - Stuff has no extrinsic properties
 - e.g., weight, length, shape, ...

Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

- Intelligence is intrinsically social: agents need to negotiate and coordinate with other agents
- In multi-agents scenarios, to predict what other agents will do, we need methods to model mental states of other agents
 - representations of other agents' knowledge (and beliefs, goals)
- Agent's Propositional attitudes: Knows, Believes, Wants,...
 - ex "Lois Knows that Superman can fly"

Problem

Propositional attitudes do not behave as regular predicates

• issue: Referential opacity vs. referential transparency

- Intelligence is intrinsically social: agents need to negotiate and coordinate with other agents
- In multi-agents scenarios, to predict what other agents will do, we need methods to model mental states of other agents
 - representations of other agents' knowledge (and beliefs, goals)
- Agent's Propositional attitudes: Knows, Believes, Wants,...
 - ex "Lois Knows that Superman can fly"

Problem

Propositional attitudes do not behave as regular predicates

• issue: Referential opacity vs. referential transparency

- Intelligence is intrinsically social: agents need to negotiate and coordinate with other agents
- In multi-agents scenarios, to predict what other agents will do, we need methods to model mental states of other agents
 - representations of other agents' knowledge (and beliefs, goals)
- Agent's Propositional attitudes: Knows, Believes, Wants,...
 - ex "Lois Knows that Superman can fly"

Problem

Propositional attitudes do not behave as regular predicates

issue: Referential opacity vs. referential transparency

- Intelligence is intrinsically social: agents need to negotiate and coordinate with other agents
- In multi-agents scenarios, to predict what other agents will do, we need methods to model mental states of other agents
 - representations of other agents' knowledge (and beliefs, goals)
- Agent's Propositional attitudes: Knows, Believes, Wants,...
 - ex "Lois Knows that Superman can fly"

Problem

Propositional attitudes do not behave as regular predicates

issue: Referential opacity vs. referential transparency

- Consider the assertion "Lois knows that Superman can fly"
- Consider the FOL formalization: *Knows(Lois, CanFly(Superman))*
- Minor Problem: CanFly(Superman) is a formula
 - ⇒ cannot occur as argument of a predicate
 - → must apply reification → make it a term
- Major Problem (Referential Transparency of FOL):
 - since Superman is Clark Kent (but Lois doesn't know it!), FOL allows to conclude "Lois knows that Clark Kent can fly":

```
Superman = Clark \land Knows(Lois, CanFly(Superman))
```

- $\models_{FOL} Knows(Lois, CanFly(Clark))$
- → Wrong inference! (Lois doesn't know Clark Kent can fly!)
- Hint: FOL predicates transparent to equality reasoning:

$$t = s \wedge P(s,...) \models_{FOL} P(t,...)$$

- Consider the assertion "Lois knows that Superman can fly"
- Consider the FOL formalization: *Knows(Lois, CanFly(Superman))*
- Minor Problem: CanFly(Superman) is a formula
 - ⇒ cannot occur as argument of a predicate
 - → must apply reification → make it a term
- Major Problem (Referential Transparency of FOL):
 - since Superman is Clark Kent (but Lois doesn't know it!), FOL allows to conclude "Lois knows that Clark Kent can fly":

```
Superman = Clark \ Knows(Lois, CanFly(Superman))
```

- $\models_{FOL} Knows(Lois, CanFly(Clark))$
- → Wrong inference! (Lois doesn't know Clark Kent can fly!)
- Hint: FOL predicates transparent to equality reasoning:

$$t = s \wedge P(s, ...) \models_{FOL} P(t, ...)$$



- Consider the assertion "Lois knows that Superman can fly"
- Consider the FOL formalization: Knows(Lois, CanFly(Superman))
- Minor Problem: CanFly(Superman) is a formula
 - ⇒ cannot occur as argument of a predicate
 - \implies must apply reification \implies make it a term
- Major Problem (Referential Transparency of FOL):
 - since Superman is Clark Kent (but Lois doesn't know it!), FOL allows to conclude "Lois knows that Clark Kent can fly":

```
Superman = Clark \land Knows(Lois, CanFly(Superman))
```

 $\models_{FOL} Knows(Lois, CanFly(Clark))$

- ⇒ Wrong inference! (Lois doesn't know Clark Kent can fly!)
- Hint: FOL predicates transparent to equality reasoning:

$$t = s \wedge P(s, ...) \models_{FOL} P(t, ...)$$



- Consider the assertion "Lois knows that Superman can fly"
- Consider the FOL formalization: Knows(Lois, CanFly(Superman))
- Minor Problem: CanFly(Superman) is a formula
 - ⇒ cannot occur as argument of a predicate
 - → must apply reification → make it a term
- Major Problem (Referential Transparency of FOL):
 - since Superman is Clark Kent (but Lois doesn't know it!), FOL allows to conclude "Lois knows that Clark Kent can fly":

```
\textit{Superman} = \textit{Clark} \land \textit{Knows}(\textit{Lois}, \textit{CanFly}(\textit{Superman}))
```

 $\models_{FOL} Knows(Lois, CanFly(Clark))$

- ⇒ Wrong inference! (Lois doesn't know Clark Kent can fly!)
- Hint: FOL predicates transparent to equality reasoning:

$$t = s \wedge P(s,...) \models_{FOL} P(t,...)$$

- Consider the assertion "Lois knows that Superman can fly"
- Consider the FOL formalization: Knows(Lois, CanFly(Superman))
- Minor Problem: CanFly(Superman) is a formula
 - ⇒ cannot occur as argument of a predicate
- Major Problem (Referential Transparency of FOL):
 - since Superman is Clark Kent (but Lois doesn't know it!), FOL allows to conclude "Lois knows that Clark Kent can fly":

```
\textit{Superman} = \textit{Clark} \land \textit{Knows}(\textit{Lois}, \textit{CanFly}(\textit{Superman}))
```

- $\models_{FOL} Knows(Lois, CanFly(Clark))$
- ⇒ Wrong inference! (Lois doesn't know Clark Kent can fly!)
- Hint: FOL predicates transparent to equality reasoning:

$$t = s \wedge P(s,...) \models_{FOL} P(t,...)$$

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark}\neg Identity(Superman, Clark))$
- Properties in all modal logics:

```
• K_A(P \land Q) \iff K_AP \land K_AQ
• K_AP \lor K_AQ \models K_A(P \lor Q), but K_A(P \lor Q) \not\models K_AP \lor K_AQ (e.g. K_A(P \lor \neg P) \not\models K_AP \lor K_A \neg P)
```

- The following axiom holds in all (normal) modal logics: $K: (K_A\phi \wedge K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference"
- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - 4 : $K_A\varphi \to K_AK_A\varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" 5 : $\neg K_A\varphi \to K_A\neg K_A\varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": K_{Lois} CanFly(Superman)
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark}\neg Identity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \land Q) \iff K_AP \land K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics: $K: (K_A\phi \wedge K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference
- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - $4: K_A \varphi \to K_A K_A \varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" $5: \neg K_A \varphi \to K_A \neg K_A \varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|Mentity(Superman, Clark)) \lor K_{Clark}|Mentity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics: $K: (K_A\phi \wedge K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference
- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
- 4: $K_A\varphi \to K_AK_A\varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" 5: $\neg K_A\varphi \to K_A \neg K_A\varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": K_{Lois} CanFly(Superman)
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark} \neg Identity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics: $K: (K_A\phi \wedge K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference
- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
- 4: $K_A\varphi \to K_AK_A\varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" 5: $\neg K_A\varphi \to K_A \neg K_A\varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it"
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ullet ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{Clark}|M_{$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics:

 $K: (K_A\phi \land K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference"

- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - 4 : $K_A\varphi \to K_AK_A\varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" 5 : $\neg K_A\varphi \to K_A\neg K_A\varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it"
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ullet ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark} \neg Identity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics:

 $K: (K_A\phi \land K_A(\phi \to \psi) \to K_A\psi$ (distribution axiom): "A is able to perform propositional inference"

- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - 4 : $K_A \varphi \to K_A K_A \varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it"
 - 5 : $\neg K_A \varphi \rightarrow K_A \neg K_A \varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it"
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark} \neg Identity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics:

```
K: (K_A\phi \land K_A(\phi \to \psi) \to K_A\psi (distribution axiom): "A is able to perform propositional inference"
```

- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - 4 : $K_A\varphi \to K_AK_A\varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it"
 - 5 : $\neg K_A \varphi \rightarrow K_A \neg K_A \varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it"
- Referential Opacity: $Superman = Clark \land K_{Lois}CanFly(Superman) \not\models K_{Lois}CanFly(Clark)$
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

- Modal logics include special modal operators that take formulas (not terms!) as arguments
 - "A knows P" is represented with K_AP (P formula, not term!)
 - ex: "Lois knows that Superman can fly": $K_{Lois}CanFly(Superman)$
 - ex: "Lois knows Clark Kent knows if he is Superman or not": $K_{Lois}(K_{Clark}|dentity(Superman, Clark)) \lor K_{Clark} \neg Identity(Superman, Clark))$
- Properties in all modal logics:
 - $K_A(P \wedge Q) \iff K_AP \wedge K_AQ$
 - $K_AP \vee K_AQ \models K_A(P \vee Q)$, but $K_A(P \vee Q) \not\models K_AP \vee K_AQ$ (e.g. $K_A(P \vee \neg P) \not\models K_AP \vee K_A \neg P$)
- The following axiom holds in all (normal) modal logics:

```
K: (K_A\phi \land K_A(\phi \to \psi) \to K_A\psi (distribution axiom): "A is able to perform propositional inference"
```

- The following axioms hold in some (normal) modal logics:
 - $T: K_A \varphi \to \varphi$ (knowledge axiom): "A knows only true facts"
 - 4 : $K_A \varphi \to K_A K_A \varphi$ (positive-introspection axiom): "If A knows fact φ , then [s]he knows [s]he knows it" 5 : $\neg K_A \varphi \to K_A \neg K_A \varphi$ (negative-introspection axiom):
 - "If A doesn't knows φ , then [s]he knows [s]he doesn't know it"
- Referential Opacity: Superman = Clark \land K_{Lois} CanFly(Superman) $\not\models$ K_{Lois} CanFly(Clark)
- Reasoning in (propositional) Modal logics is NP-hard (most often even PSPACE-hard)

Semantics of Modal Logics

- A model (Kripke model) is a collection of possible worlds w_i
 - possible worlds are connected in a graph by accessibility relations
 - ullet one relation for each distinct modal operator K_A
- w_1 is accessible from w_0 wrt. K_A if everything which holds in w_1 is consistent with what A knows in w_0 (written " $Acc(K_A, w_0, w_1)$ " or " $w_0 \stackrel{K_A}{\longmapsto} w_1$ ")
 - \implies $K_A \varphi$ holds in w_o iff φ holds in every world w_i accessible from w_0
 - the more is known in w_0 , the less worlds are accessible from w_0
 - remark: two possible worlds may differ also for what an agent knows there
- Different modal logics differ by different properties of $Acc(K_A,...)$
 - $T: K_A \varphi \to \varphi$ holds iff $Acc(K_A, ...)$ reflexive: $w \stackrel{K_A}{\longmapsto} w$
 - 4: $K_A \varphi \to K_A K_A \varphi$ holds iff $Acc(K_A, ...)$ transitive: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_1 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_0 \stackrel{K_A}{\longmapsto} w_2$
 - 5: $\neg K_A \varphi \to K_A \neg K_A \varphi$ holds iff $Acc(K_A, ...)$ euclidean: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_0 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_1 \stackrel{K_A}{\longmapsto} w_2$

/41

Semantics of Modal Logics

- A model (Kripke model) is a collection of possible worlds w_i
 - possible worlds are connected in a graph by accessibility relations
 - ullet one relation for each distinct modal operator K_A
- w_1 is accessible from w_0 wrt. K_A if everything which holds in w_1 is consistent with what A knows in w_0 (written " $Acc(K_A, w_0, w_1)$ " or " $w_0 \stackrel{K_A}{\longmapsto} w_1$ ")
 - \implies $K_A \varphi$ holds in w_o iff φ holds in every world w_i accessible from w_0
 - the more is known in w_0 , the less worlds are accessible from w_0
 - remark: two possible worlds may differ also for what an agent knows there
- Different modal logics differ by different properties of $Acc(K_A,...)$
 - $T: K_A \varphi \to \varphi$ holds iff $Acc(K_A, ...)$ reflexive: $w \stackrel{K_A}{\longmapsto} w$
 - 4: $K_A \varphi \to K_A K_A \varphi$ holds iff $Acc(K_A, ...)$ transitive: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_1 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_0 \stackrel{K_A}{\longmapsto} w_2$
 - 5: $\neg K_A \varphi \to K_A \neg K_A \varphi$ holds iff $Acc(K_A, ...)$ euclidean: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_0 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_1 \stackrel{K_A}{\longmapsto} w_2$

Semantics of Modal Logics

- A model (Kripke model) is a collection of possible worlds w_i
 - possible worlds are connected in a graph by accessibility relations
 - ullet one relation for each distinct modal operator K_A
- w₁ is accessible from w₀ wrt. Kᵢ if everything which holds in w₁ is consistent with what A knows in w₀ (written "Acc(Kᵢ, w₀, w₁)" or "w₀ → w₁")
 - \implies $K_A \varphi$ holds in w_o iff φ holds in every world w_i accessible from w_0
 - the more is known in w_0 , the less worlds are accessible from w_0
 - remark: two possible worlds may differ also for what an agent knows there
- Different modal logics differ by different properties of $Acc(K_A,...)$
 - $T: K_A \varphi \to \varphi$ holds iff $Acc(K_A, ...)$ reflexive: $w \stackrel{K_A}{\longmapsto} w$
 - 4 : $K_A \varphi \to K_A K_A \varphi$ holds iff $Acc(K_A, ...)$ transitive: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_1 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_0 \stackrel{K_A}{\longmapsto} w_2$
 - 5: $\neg K_A \varphi \to K_A \neg K_A \varphi$ holds iff $Acc(K_A, ...)$ euclidean: $w_0 \stackrel{K_A}{\longmapsto} w_1$ and $w_0 \stackrel{K_A}{\longmapsto} w_2 \Longrightarrow w_1 \stackrel{K_A}{\longmapsto} w_2$

4: transitive

$$w_0$$
 w_1 w_2

5: euclidean

0/41

Semantics of Modal Logics: Some Remarks

Assume the knowledge of *A* is correct: $T: K_A \varphi \to \varphi$ ("Everything which *A* knows holds")

- $\not\models \varphi \to K_A \varphi$: A does not know everything which holds!
 - → A does not know exactly in which world [s]he is
- The less worlds are accessible, the more precise is the knowledge of A
 - uncertainty on some information makes accessible worlds different
 A does not know the world [s]he is
 - complete knowledge: current world is the only successor of itself

Notice the difference

- $K_A \neg P$: agent A knows that P does not hold (in all accessible worlds P is false)
- $\neg K_A P$: agent A does not know if P holds (in some accessible worlds P is false)
- $\implies K_A \neg P \models \neg K_A P$, but $\neg K_A P \not\models K_A \neg P$

Semantics of Modal Logics: Some Remarks

Assume the knowledge of *A* is correct: $T: K_A \varphi \to \varphi$ ("Everything which *A* knows holds")

- $\not\models \varphi \to K_A \varphi$: A does not know everything which holds!
 - ⇒ A does not know exactly in which world [s]he is
- The less worlds are accessible, the more precise is the knowledge of A
 - uncertainty on some information makes accessible worlds differen
 A does not know the world (s)he is
 - complete knowledge: current world is the only successor of itself
 A knows exactly the world [s]he is

Notice the difference:

- $K_A \neg P$: agent A knows that P does not hold (in all accessible worlds P is false)
- $\neg K_A P$: agent A does not know if P holds (in some accessible worlds P is false)
- $\implies K_A \neg P \models \neg K_A P$, but $\neg K_A P \not\models K_A \neg P$

Semantics of Modal Logics: Some Remarks

Assume the knowledge of *A* is correct: $T: K_A \varphi \to \varphi$ ("Everything which *A* knows holds")

- $\not\models \varphi \to K_A \varphi$: A does not know everything which holds!
 - ⇒ A does not know exactly in which world [s]he is
- The less worlds are accessible, the more precise is the knowledge of A
 - uncertainty on some information makes accessible worlds different
 A does not know the world [s]he is
 - complete knowledge: current world is the only successor of itself
 A knows exactly the world [s]he is
 - w_0 w_n Uncertainty

W

Complete knowledge

Notice the difference

- $K_A \neg P$: agent A knows that P does not hold (in all accessible worlds P is false)
- $\neg K_A P$: agent A does not know if P holds (in some accessible worlds P is false)
- $\implies K_A \neg P \models \neg K_A P$, but $\neg K_A P \not\models K_A \neg P$

Semantics of Modal Logics: Some Remarks

Assume the knowledge of A is correct: $T: K_A \varphi \to \varphi$ ("Everything which A knows holds")

- $\not\models \varphi \to K_A \varphi$: A does not know everything which holds!
 - ⇒ A does not know exactly in which world [s]he is
- The less worlds are accessible, the more precise is the knowledge of A
 - uncertainty on some information makes accessible worlds different
 A does not know the world [s]he is
 - complete knowledge: current world is the only successor of itself
 A knows exactly the world [s]he is

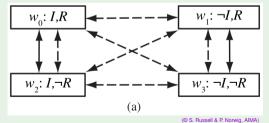
Notice the difference:

- $K_A \neg P$: agent A knows that P does not hold (in all accessible worlds P is false)
- $\neg K_A P$: agent A does not know if P holds (in some accessible worlds P is false)
- $\implies K_A \neg P \models \neg K_A P$, but $\neg K_A P \not\models K_A \neg P$

1/41

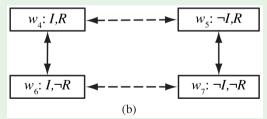
Accessibility relations: $K_{Superman}$ (solid arrows) and K_{Lois} (dotted arrows).

- Legenda:
 - R: "the weather report says tomorrow will rain"
 - I: "Superman's secret identity is Clark Kent."
 - Ex: $K_{Lois}(K_{Clark}I \vee K_{Clark}\neg I)$: "Lois Knows that Clark Knows if he is Superman or not."
- Superman knows his own identity: $K_{Superman}I \lor K_{Superman}I$, and
 (a) neither Superman nor Lois has seen the weather report, she knows Superman knows if he is Clark $(\neg K_{Lois}R \land \neg K_{Lois}\neg R) \land (\neg K_{Superman}R \land \neg K_{Superman}\neg R) \land K_{Lois}(K_{Superman}I \lor K_{Superman}\neg I)$



Accessibility relations: $K_{Superman}$ (solid arrows) and K_{Lois} (dotted arrows).

- Legenda:
 - R: "the weather report says tomorrow will rain"
 - I: "Superman's secret identity is Clark Kent."
 - Ex: $K_{Lois}(K_{Clark}I \vee K_{Clark}\neg I)$: "Lois Knows that Clark Knows if he is Superman or not."
- Superman knows his own identity: $K_{Superman}I \lor K_{Superman}\neg I$, and (b) Lois has seen the weather report, Superman has not, but he knows that Lois has seen it $(K_{Lois}R \lor K_{Lois}\neg R) \land (\neg K_{Superman}R \land \neg K_{Superman}\neg R)$ $K_{Lois}(K_{Superman}I \lor K_{Superman}\neg I) \land K_{Superman}(K_{Lois}R \lor K_{Lois}\neg R)$

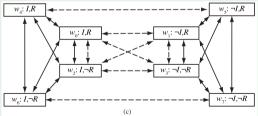


Accessibility relations: $K_{Superman}$ (solid arrows) and K_{Lois} (dotted arrows).

- Legenda:
 - R: "the weather report says tomorrow will rain"
 - I: "Superman's secret identity is Clark Kent."
 - Ex: $K_{Lois}(K_{Clark}I \vee K_{Clark}\neg I)$: "Lois Knows that Clark Knows if he is Superman or not."

@ S. Russell & P. Norwig, AIMA

• Superman knows his own identity: $K_{Superman}I \lor K_{Superman}\lnot I$, and (c) Lois may or may not have seen the weather report, Superman has not: $((\lnot K_{Lois}R \land \lnot K_{Lois}\lnot R) \lor (K_{Lois}R \lor K_{Lois}\lnot R)) \land (\lnot K_{Sup}.R \land \lnot K_{Sup}.\lnot R) K_{Lois}(K_{Superman}I \lor K_{Superman}\lnot I)$



Accessibility relations: $K_{Superman}$ (solid arrows) and K_{Lois} (dotted arrows).

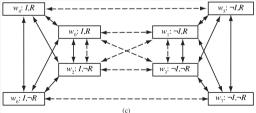
- Legenda:
 - R: "the weather report says tomorrow will rain"
 - I: "Superman's secret identity is Clark Kent."
 - Ex: $K_{Lois}(K_{Clark}I \vee K_{Clark}\neg I)$: "Lois Knows that Clark Knows if he is Superman or not."

@ S. Russell & P. Norwig, AIMA

- Superman knows his own identity: $K_{Superman}I \lor K_{Superman}\neg I$, and
 - (c) Lois may or may not have seen the weather report, Superman has not:

$$((\neg K_{Lois}R \land \neg K_{Lois}\neg R) \lor (K_{Lois}R \lor K_{Lois}\neg R)) \land (\neg K_{Sup.}R \land \neg K_{Sup.}\neg R)$$

 $K_{Lois}(K_{Superman}I \lor K_{Superman} \lnot I)$



Exercise

Consider the previous example.

• For each scenario (a), (b) and (c) define doubly-nested knowledge in terms of

```
[\neg]K_{Lois}[\neg]K_{Lois}[\neg]I,

[\neg]K_{Lois}[\neg]K_{Lois}[\neg]R,

[\neg]K_{Sup.}[\neg]K_{Sup.}[\neg]I,

[\neg]K_{Sup.}[\neg]K_{Sup.}[\neg]R
```

Exercise

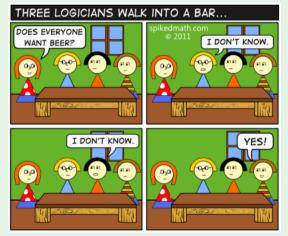
Consider (normal) modal logics (i.e., axioms K, T, 4 and 5 hold).

Let IsRed(Pen), IsOnTable(Pen) be possible facts, let Mary, John be agents and let K_{Mary} , K_{John} denote the modal operators "Mary knows that..." respectively. For each of the following facts, say if it is true or false.

- If $K_{Mary} \neg IsRed(Pen)$ holds, then $\neg K_{Mary} IsRed(Pen)$ holds
- If $\neg K_{Mary}$ IsRed(Pen) holds, then K_{Mary} ¬IsRed(Pen) holds
- If K_{John}IsRed(Pen) and IsRed(Pen) ↔ IsOnTable(Pen) hold, then K_{John}IsOnTable(Pen) holds
- If K_{Mary} IsRed(Pen) and K_{Mary} (IsRed(Pen) \to K_{John} IsRed(Pen)) hold, then K_{Mary} K_{John} IsRed(Pen)) holds

Exercise

- Why does the third logician answers "Yes"?
- Formalize and solve the problem by means of modal logic (K+T+4+5)



Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

Reasoning Systems for Categories

Q. How to organize and reason with categories?

- Semantic Networks
 - allow to visualize knowledge bases
 - efficient algorithms for category membership inference
 - limited expressivity
 - many variants
- Description Logics (DLs)
 - formal language for constructing and combining category definitions
 - (relatively) efficient algorithms to decide subset and superset relationships between categories
 - many DLs
 - up to very high expressivity
 - up to very high complexity (e.g., DOUBLY-EXPTIME)

Reasoning Systems for Categories

Q. How to organize and reason with categories?

- Semantic Networks
 - allow to visualize knowledge bases
 - efficient algorithms for category membership inference
 - limited expressivity
 - many variants
- Description Logics (DLs)
 - formal language for constructing and combining category definitions
 - (relatively) efficient algorithms to decide subset and superset relationships between categories
 - many DLs
 - up to very high expressivity
 - up to very high complexity (e.g., DOUBLY-EXPTIME)

Reasoning Systems for Categories

Q. How to organize and reason with categories?

- Semantic Networks
 - allow to visualize knowledge bases
 - efficient algorithms for category membership inference
 - limited expressivity
 - many variants
- Description Logics (DLs)
 - formal language for constructing and combining category definitions
 - (relatively) efficient algorithms to decide subset and superset relationships between categories
 - many DLs
 - up to very high expressivity
 - up to very high complexity (e.g., DOUBLY-EXPTIME)

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

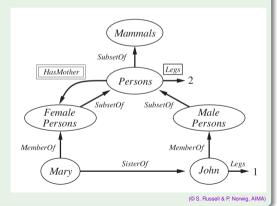
- Allow for representing individual objects, categories of objects, and relations among objects
- A Semantic Network is a graph where:
 - nodes, with a label, correspond to concepts
 - arcs, labelled and directed, correspond to binary relations between concepts (aka roles)
- Two kinds of nodes:
 - Generic concepts, corresponding to categories/classes
 - Individual concepts, corresponding to individuals
- Two special relations are always present, with different names
 - IS-A, aka SubsetOf/SubclassOf (subclass)
 - InstanceOf aka MemberOf (membership)
- Inheritance detection straightforward
- Ability to represent default values for categories
- Limited expressive power: cannot represent negation, disjunction, nested function symbols, existential quantification

Semantic Networks: Example

Notice

- "HasMother" is a relation between persons (individuals) (categories do not have mothers)
- "HasMother" (double-boxed notation) means $\forall x. (x \in Persons \rightarrow [\forall y. (HasMother(x, y) \rightarrow y \in FemalePersons)])$
- "Legs" is a property of single persons (individuals)
- "Legs" (single-boxed notation) means:

 $\forall x.(x \in Persons \rightarrow Legs(x, 2))$

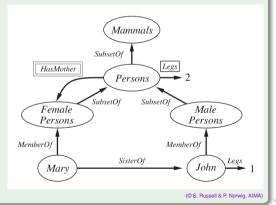


Semantic Networks: Example

Notice

- "HasMother" is a relation between persons (individuals) (categories do not have mothers)
- "HasMother" (double-boxed notation) means $\forall x. (x \in Persons \rightarrow [\forall y. (HasMother(x, y) \rightarrow y \in FemalePersons)])$
- "Legs" is a property of single persons (individuals)
- "Legs" (single-boxed notation) means:

 $\forall x.(x \in Persons \rightarrow Legs(x, 2))$

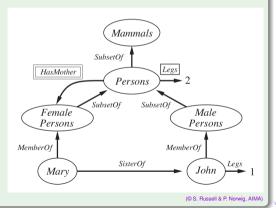


Semantic Networks: Example

Notice

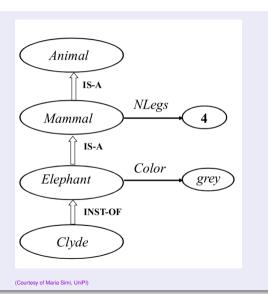
- "HasMother" is a relation between persons (individuals) (categories do not have mothers)
- "HasMother" (double-boxed notation) means $\forall x. (x \in Persons \rightarrow [\forall y. (HasMother(x, y) \rightarrow y \in FemalePersons)])$
- "Legs" is a property of single persons (individuals)
- "Legs" (single-boxed notation) means:

$$\forall x.(x \in Persons \rightarrow Legs(x, 2))$$



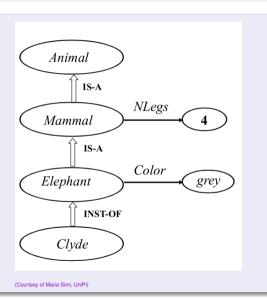
Inheritance in Semantic Networks

- Inheritance conveniently implemented as link traversal
- Q. How many legs has Clyde
- follow the INST-OF/IS-A chain until find the property NLegs



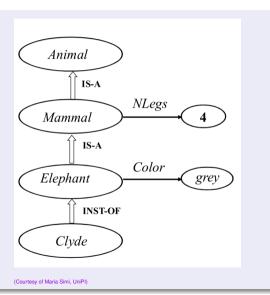
Inheritance in Semantic Networks

- Inheritance conveniently implemented as link traversal
- Q. How many legs has Clyde?
- follow the INST-OF/IS-A chain until find the property NLegs



Inheritance in Semantic Networks

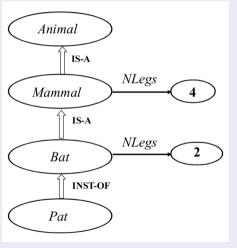
- Inheritance conveniently implemented as link traversal
- Q. How many legs has Clyde?
- follow the INST-OF/IS-A chain until find the property NLegs



Inheritance with Exceptions

The presence of exceptions does not create any problem with S.N.

- How many legs has Pat?
- Just take the most specific information: the first that is found going up the hierarchy
- ability to represent default values for categories

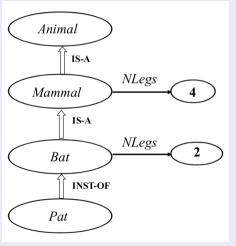


(Courtesy of Maria Simi, UniPI)

Inheritance with Exceptions

The presence of exceptions does not create any problem with S.N.

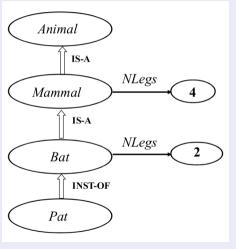
- How many legs has Pat?
- Just take the most specific information: the first that is found going up the hierarchy
- ability to represent default values for categories



Inheritance with Exceptions

The presence of exceptions does not create any problem with S.N.

- How many legs has Pat?
- Just take the most specific information: the first that is found going up the hierarchy
- ability to represent default values for categories



(Courtesy of Maria Simi, UniPI)

Encoding N-Ary Relations

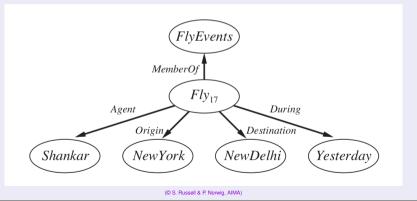
- Semantic networks allow only binary relations
- Q. How to represent n-ary relations?
- \implies Reify the proposition as an event belonging to an appropriate event category
 - ex "Fly₁₇" for Fly(Shankar, NewYork, NewDelhi, Yesterday)

Encoding N-Ary Relations

- Semantic networks allow only binary relations
- Q. How to represent n-ary relations?
- ⇒ Reify the proposition as an event belonging to an appropriate event category
 - ex "Fly₁₇" for Fly(Shankar, NewYork, NewDelhi, Yesterday)

Encoding N-Ary Relations

- Semantic networks allow only binary relations
- Q. How to represent n-ary relations?
- ⇒ Reify the proposition as an event belonging to an appropriate event category
 - ex "Fly₁₇" for Fly(Shankar, NewYork, NewDelhi, Yesterday)



Outline

- Ontologies and Ontological Engineering
- Categories and Objects
- Reasoning about Knowledge
- Reasoning about Categories
 - Semantic Networks (hints)
 - Description Logics

Description Logics

- Designed to describe definitions and properties about categories
- Principal inference tasks:
 - Subsumption: check if one category is a subset (sub-category) of another
 - Classification: check whether an object belongs to a category
 - Consistency: check if category membership criteria are satisfiable
- Defaults and exceptions are lost

Description Logics

- Designed to describe definitions and properties about categories
- Principal inference tasks:
 - Subsumption: check if one category is a subset (sub-category) of another
 - Classification: check whether an object belongs to a category
 - Consistency: check if category membership criteria are satisfiable
- Defaults and exceptions are lost

Description Logics

- Designed to describe definitions and properties about categories
- Principal inference tasks:
 - Subsumption: check if one category is a subset (sub-category) of another
 - Classification: check whether an object belongs to a category
 - Consistency: check if category membership criteria are satisfiable
- Defaults and exceptions are lost

Concepts, corresponding to unary relations

- T, ⊥: universal and empty concepts
- atomic concepts: ex: Female, Male, Article, Journalist,...
- operators for the construction of complex concepts: and (\Box) , or (\Box) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
- ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren.Person \sqcap \geq 3 \ hasChild.Female$
- ex: articles that have authors and whose authors are all journalists: Article □ ∃hasAuthor. T □ ∀hasAuthor. Journalist

Roles corresponding to binary relations

- ex: hasAuthor, hasChild
- can be combined with operators for constructing complex roles
- hasChildren
 ≡ hasSon
 □ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\Box) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren. Person \sqcap \geq 3 \ hasChild. Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. ▼□ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren ≡ hasSon ⊔ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\Box) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren. Person \sqcap \geq 3 \ hasChild. Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. ▼□ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren
 ≡ hasSon
 □ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\Box) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren.Person \sqcap \geq 3 \ hasChild.Female$
 - ex: articles that have authors and whose authors are all journalists: $Article \sqcap \exists hasAuthor. \top \sqcap \forall hasAuthor. Journalist$
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren ≡ hasSon ⊔ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\sqcup) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren. Person \sqcap \geq 3 \ hasChild. Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. □ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren ≡ hasSon ⊔ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T,⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\sqcup) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren. Person \sqcap \geq 3 \ hasChild. Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. □ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren ≡ hasSon ⊔ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\Box) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren.Person \sqcap \geq 3 \ hasChild.Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. □ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - hasChildren ≡ hasSon ⊔ hasDaughter
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T,⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\sqcup) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren.Person \sqcap \geq 3 \ hasChild.Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. □ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - $hasChildren \equiv hasSon \sqcup hasDaughter$
- Individuals (used in assertions only)
 - ex: Mary, John

- Concepts, corresponding to unary relations
 - T, ⊥: universal and empty concepts
 - atomic concepts: ex: Female, Male, Article, Journalist,...
 - operators for the construction of complex concepts: and (\Box) , or (\sqcup) , not (\neg) , all (\forall) , some (\exists) , atleast $(\geq n)$, atmost $(\leq n)$, ...
 - ex: mothers (i.e., women who have children) of at least three female children: $Woman \sqcap \exists hasChildren.Person \sqcap \geq 3 \ hasChild.Female$
 - ex: articles that have authors and whose authors are all journalists:
 Article □ ∃hasAuthor. □ ∀hasAuthor. Journalist
- Roles corresponding to binary relations
 - ex: hasAuthor, hasChild
 - can be combined with operators for constructing complex roles
 - $hasChildren \equiv hasSon \sqcup hasDaughter$
- Individuals (used in assertions only)
 - ex: Mary, John

Terminologies (T-Boxes): sets of

- concepts definitions (C₁ ≡ C₂)
 ex: Father ≡ Man □ ∃hasChild.Person
- or concept generalizations $(C_1 \sqsubseteq C_2)$ ex: Woman \sqsubseteq Person
- Assertions (A-Boxes): assert
 - individuals as concept members i : C,
 where i is an individual and C is a concept
 ex: mary : Person, john : Father
 - individual pairs as relation members (i, j): R, where i,j are individuals and R is a relation ex: (iohn. marv): hasChild

- Terminologies (T-Boxes): sets of
 - concepts definitions $(C_1 \equiv C_2)$ ex: Father = Man $\square \exists hasChild\ Person$
 - or concept generalizations ($C_1 \sqsubseteq C_2$) ex: Woman \sqsubseteq Person
- Assertions (A-Boxes): assert
 - individuals as concept members i: C,
 where i is an individual and C is a concept
 ex: mary: Person, john: Father
 - individual pairs as relation members (i, j): R, where i,j are individuals and R is a relation ex: (inhn marx) - hasChild

- Terminologies (T-Boxes): sets of
 - concepts definitions ($C_1 \equiv C_2$)
 - ex: $Father \equiv Man \sqcap \exists hasChild.Person$
 - or concept generalizations ($C_1 \sqsubseteq C_2$)
 - ex: $Woman \sqsubseteq Person$
- Assertions (A-Boxes): assert
 - Individuals as concept members i: C,
 where i is an individual and C is a concept
 ext. mary Person John Father
 - individual pairs as relation members (i, j): R,
 where i,j are individuals and R is a relation
 - ex: (john, mary) : hasChild

- Terminologies (T-Boxes): sets of
 - concepts definitions $(C_1 \equiv C_2)$ ex: Father = Man $\square \exists hasChild\ Person$
 - or concept generalizations ($C_1 \sqsubseteq C_2$) ex: *Woman* \sqsubseteq *Person*
- Assertions (A-Boxes): assert
 - individuals as concept members i: C,
 where i is an individual and C is a concept
 ex: mary: Person, iohn: Father
 - individual pairs as relation members \(\lambda i, j \rangle : R, \)
 where i,j are individuals and R is a relation
 ext. \(\lambda i, \)
 and \(\lambda : \)
 \(\lambda = \)

- Terminologies (T-Boxes): sets of
 - concepts definitions ($C_1 \equiv C_2$) ex: Father $\equiv Man \sqcap \exists hasChild.Person$
 - or concept generalizations ($C_1 \sqsubseteq C_2$) ex: Woman \sqsubseteq Person
- Assertions (A-Boxes): assert
 - individuals as concept members i : C,
 where i is an individual and C is a concept
 ex: mary : Person, john : Father
 - individual pairs as relation members \(\lambda i, j \rangle : R, \)
 where i,j are individuals and R is a relation
 ex: \(\lambda i \) in mary \(\lambda : hasChild \)

- Terminologies (T-Boxes): sets of
 - concepts definitions $(C_1 \equiv C_2)$ ex: Father \equiv Man $\sqcap \exists$ has Child. Person
 - or concept generalizations ($C_1 \sqsubseteq C_2$) ex: *Woman* \sqsubseteq *Person*
- Assertions (A-Boxes): assert
 - individuals as concept members i: C,
 where i is an individual and C is a concept
 ex: mary: Person, john: Father
 - individual pairs as relation members \(\langle i, j \rangle : R\),
 where i,j are individuals and R is a relation
 ex: \(\langle john, mary \rangle : hasChild\)

T-Box: Example (Logic ALCN)

```
Woman ≡ Person □ Female
                            Person □ ¬ Woman
                   Man
                            Woman □ ∃hasChild Person
                Mother
                             Man □ ∃hasChild.Person
                 Father
                 Parent
                            Father | | Mother
           Grandmother =
                            Mother □ ∃hasChild. Parent
MotherWithManyChildren
                             Mother \square \geqslant 3 has Child Person
                        MotherWithoutDaughter
                             Mother □ ∀hasChild.¬ Woman
                   Wife
                         ■ Woman □ ∃hasHusband Man
```

Reasoning Services for DLs

- Design and management of ontologies
 - consistency checking of concepts, creation of hierarchies
- Ontology integration
 - Relations between concepts of different ontologies
 - Consistency of integrated hierarchies
- Queries
 - Determine whether facts are consistent wrt ontologies
 - Determine if individuals are instances of concepts
 - Retrieve individuals satisfying a query (concept)
 - Verify if a concept is more general than another (subsumption)

Reasoning Services for DLs

- Design and management of ontologies
 - consistency checking of concepts, creation of hierarchies
- Ontology integration
 - Relations between concepts of different ontologies
 - Consistency of integrated hierarchies
- Queries
 - Determine whether facts are consistent wrt ontologies
 - Determine if individuals are instances of concepts
 - Retrieve individuals satisfying a query (concept)
 - Verify if a concept is more general than another (subsumption)

Reasoning Services for DLs

- Design and management of ontologies
 - consistency checking of concepts, creation of hierarchies
- Ontology integration
 - Relations between concepts of different ontologies
 - Consistency of integrated hierarchies
- Queries
 - Determine whether facts are consistent wrt ontologies
 - Determine if individuals are instances of concepts
 - Retrieve individuals satisfying a query (concept)
 - Verify if a concept is more general than another (subsumption)

Querying a DL Ontology: Example

All the children of John are females. Mary is a child of John. Tim is a friend of professor Blake. Prove that Mary is a female.

- A ^{det} { john : ∀hasChild.female, (john, mary) : hasChild, (blake, tim) : hasFriend, blake : professor}
- Query: mary : female (or: is $A \sqcap mary : \neg female$ unsatisfiable?)
- Yes

Querying a DL Ontology: Example

All the children of John are females. Mary is a child of John. Tim is a friend of professor Blake. Prove that Mary is a female.

- A ^{def} = {john : ∀hasChild.female, (john, mary) : hasChild, (blake, tim) : hasFriend, blake : professor}
- Query: mary: female (or: is $A \sqcap mary$: $\neg female$ unsatisfiable?)
- Yes

Exercise

Given:

- a set of basic concepts: {Person, Male, Doctor, Engineer}
- a set of relations: {hasChild}

with their obvious meaning. Write a \mathcal{T} -box in \mathcal{ALCN} defining the following concepts

- (a) Female, Man, Woman (with their standard meaning)
- (b) femaleDoctorWithoutChildren: female doctor with no children
- (c) fatherOfFemaleDoctor: father of at least two female doctors
- (d) motherOfDoctorsOrEngineers: woman whose children are all engineers or a doctors

anon-exclusive or.