Fundamentals of Artificial Intelligence Chapter 07: Logical Agents

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Outline

Propositional Logic

Propositional Reasoning

- Resolution
- OPLL
- Reasoning with Horn Formulas
- Local Search
- 3 Agents Based on Knowledge Representation & Reasoning
 - Knowledge-Based Agents
 - Example: the Wumpus World
 - Agents Based on Propositional Reasoning
 - Propositional Logic Agents
 - Example: the Wumpus World

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Propositional Logic (aka Boolean Logic)



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Basic Definitions and Notation

Propositional formula (aka Boolean formula or sentence)

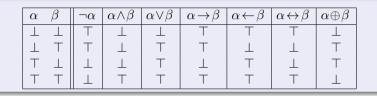
- $\bullet \ \top, \bot \text{ are formulas}$
- a propositional atom $A_1, A_2, A_3, ...$ is a formula;
- if φ_1 and φ_2 are formulas, then

 $\neg \varphi_1, \varphi_1 \land \varphi_2, \varphi_1 \lor \varphi_2, \varphi_1 \to \varphi_2, \varphi_1 \leftarrow \varphi_2, \varphi_1 \leftrightarrow \varphi_2, \varphi_1 \oplus \varphi_2$ are formulas.

- Ex: $\varphi \stackrel{\text{\tiny def}}{=} (\neg (A_1 \rightarrow A_2)) \land (A_3 \leftrightarrow (\neg A_1 \oplus (A_2 \lor \neg A_4))))$
- $Atoms(\varphi)$: the set $\{A_1, ..., A_N\}$ of atoms occurring in φ .
- Literal: a propositional atom A_i (positive literal) or its negation $\neg A_i$ (negative literal)
 - Notation: if $I := \neg A_i$, then $\neg I := A_i$
- Clause: a disjunction of literals $\bigvee_i I_j$ (e.g., $(A_1 \vee \neg A_2 \vee A_3 \vee ...))$
- Cube: a conjunction of literals $\bigwedge_j I_j$ (e.g., $(A_1 \land \neg A_2 \land A_3 \land ...)$)

Semantics of Boolean operators

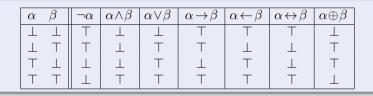
Truth Table



• \land , \lor , \leftrightarrow and \oplus are commutative: $(\alpha \land \beta) \iff (\beta \land \alpha)$ $(\alpha \lor \beta) \iff (\beta \lor \alpha)$ $(\alpha \leftrightarrow \beta) \iff (\beta \leftrightarrow \alpha)$ $(\alpha \oplus \beta) \iff (\beta \oplus \alpha)$ • \land , \lor , \leftrightarrow and \oplus are associative: $((\alpha \land \beta) \land \gamma) \iff (\alpha \land (\beta \land \gamma))$

Semantics of Boolean operators

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• \land , \lor , \leftrightarrow and \oplus are commutative:

• $\land,\lor,\leftrightarrow$ and \oplus are associative:

$$\begin{array}{ll} ((\alpha \wedge \beta) \wedge \gamma) & \iff (\alpha \wedge (\beta \wedge \gamma)) & \iff (\alpha \wedge \beta \wedge \gamma) \\ ((\alpha \vee \beta) \vee \gamma) & \iff (\alpha \vee (\beta \vee \gamma)) & \iff (\alpha \vee \beta \vee \gamma) \\ ((\alpha \leftrightarrow \beta) \leftrightarrow \gamma) & \iff (\alpha \leftrightarrow (\beta \leftrightarrow \gamma)) & \iff (\alpha \leftrightarrow \beta \leftrightarrow \gamma) \\ ((\alpha \oplus \beta) \oplus \gamma) & \iff (\alpha \oplus (\beta \oplus \gamma)) & \iff (\alpha \oplus \beta \oplus \gamma) \end{array}$$

The semantics of Implication " $\alpha \rightarrow \beta$ " may be counter-intuitive

$\alpha \rightarrow \beta$: "the antecedent (aka premise) α implies the consequent (aka conclusion) β " (aka "if α holds, then β holds"), but not vice versa

- \bullet does not require causation or relevance between α and β
 - ex: "5 is odd implies Tokyo is the capital of Japan" is true in p.l. (under the standard interpretation of "5", "odd", "Tokyo", "Japan")
 - relation between antecedent & consequent: they are both true

is true whenever its antecedent is false

- ex: "5 is even implies Sam is smart" is true (regardless the smartness of Sam)
- ex: "5 is even implies Tokyo is in Italy" is true (!)
- relation between antecedent & consequent: the former is false
- does not require temporal precedence of α wrt. β
 - ex: "the grass is wet implies it must have rained" is true (the consequent precedes temporally the antecedent)

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Syntactic Properties of Boolean Operators

Boolean logic can be expressed in terms of $\{\neg, \land\}$ (or $\{\neg, \lor\}$) only!

Syntactic Properties of Boolean Operators

Boolean logic can be expressed in terms of $\{\neg, \wedge\}$ (or $\{\neg, \vee\}$) only!

• For every pair of formulas $\alpha \iff \beta$ below, show that α and β can be rewritten into each other by applying the syntactic properties of the previous slide

•
$$(A_1 \wedge A_2) \vee A_3 \iff (A_1 \vee A_3) \wedge (A_2 \vee A_3)$$

•
$$(A_1 \lor A_2) \land A_3 \iff (A_1 \land A_3) \lor (A_2 \land A_3)$$

•
$$A_1
ightarrow (A_2
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ightarrow A_4)) \iff (A_1 \land A_2 \land A_3)
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•
$$A_1 \rightarrow (A_2 \wedge A_3) \iff (A_1 \rightarrow A_2) \wedge (A_1 \rightarrow A_3)$$

•
$$(A_1 \lor A_2) \to A_3 \iff (A_1 \to A_3) \land (A_2 \to A_3)$$

•
$$A_1 \oplus A_2 \iff (A_1 \lor A_2) \land (\neg A_1 \lor \neg A_2)$$

•
$$\neg A_1 \leftrightarrow \neg A_2 \iff A_1 \leftrightarrow A_2$$

• $A_1 \leftrightarrow A_2 \leftrightarrow A_3 \iff A_1 \oplus A_2 \oplus A_3$

Tree & DAG Representations of Formulas

- Formulas can be represented either as trees or as DAGS (Directed Acyclic Graphs)
- DAG representation can be up to exponentially smaller
 - $\bullet\,$ in particular, when $\leftrightarrow\mbox{'s}$ are involved

 $(A_1 \leftrightarrow A_2) \leftrightarrow (A_3 \leftrightarrow A_4)$

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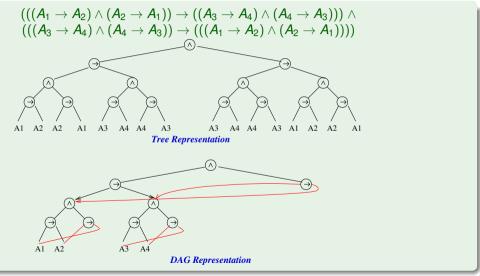
$$(A_1 \leftrightarrow A_2) \leftrightarrow (A_3 \leftrightarrow A_4) \\ \Downarrow \\ (((A_1 \leftrightarrow A_2) \rightarrow (A_3 \leftrightarrow A_4)) \land \\ ((A_3 \leftrightarrow A_4) \rightarrow (A_1 \leftrightarrow A_2)))$$

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$$\begin{array}{c} (A_1 \leftrightarrow A_2) \leftrightarrow (A_3 \leftrightarrow A_4) \\ \downarrow \\ (((A_1 \leftrightarrow A_2) \rightarrow (A_3 \leftrightarrow A_4)) \land \\ ((A_3 \leftrightarrow A_4) \rightarrow (A_1 \leftrightarrow A_2))) \\ \downarrow \\ (((A_1 \rightarrow A_2) \land (A_2 \rightarrow A_1)) \rightarrow ((A_3 \rightarrow A_4) \land (A_4 \rightarrow A_3))) \land \\ (((A_3 \rightarrow A_4) \land (A_4 \rightarrow A_3)) \rightarrow (((A_1 \rightarrow A_2) \land (A_2 \rightarrow A_1)))) \end{array}$$

Tree & DAG Representations of Formulas: Example



- Total truth assignment μ for φ :
 - $\mu : Atoms(\varphi) \longmapsto \{\top, \bot\}.$
 - represents a possible world or a possible state of the world
- Partial Truth assignment μ for φ :
 - $\mu : \mathcal{A} \longmapsto \{\top, \bot\}, \mathcal{A} \subset Atoms(\varphi).$
 - represents 2^k total assignments, k is # unassigned variables
- Notation: set and formula representations of an assignment
 - μ can be represented as a set of literals:
 - $\mathsf{EX:} \{ \mu(\mathsf{A}_1) := \top, \mu(\mathsf{A}_2) := \bot \} \implies \{ \mathsf{A}_1, \neg \mathsf{A}_2 \}$
 - μ can be represented as a formula (cube): EX: { $\mu(A_1) := \top, \mu(A_2) := \bot$ } \implies ($A_1 \land \neg A_2$)

$$\mu \models A_i \iff \mu(A_i) = \top$$

$$\mu \models \neg \varphi \iff \text{not } \mu \models \varphi$$

$$\mu \models \alpha \land \beta \iff \mu \models \alpha \text{ and } \mu \models \beta$$

$$\mu \models \alpha \lor \beta \iff \mu \models \alpha \text{ or } \mu \models \beta$$

$$\mu \models \alpha \Rightarrow \beta \iff \text{if } \mu \models \alpha, \text{ then } \mu \models \mu$$

$$\mu \models \alpha \Leftrightarrow \beta \iff \mu \models \alpha \text{ iff } \mu \models \beta$$

$$\mu \models \alpha \oplus \beta \iff \mu \models \alpha \text{ iff not } \mu \models \beta$$

- $M(\varphi) \stackrel{\text{\tiny def}}{=} \{\mu \mid \mu \models \varphi\}$ (the set of models of φ)
- A partial truth assignment μ satisfies φ iff all its total extensions satisfy φ
 - (Ex: $\{A_1\} \models (A_1 \lor A_2)$) because $\{A_1, A_2\} \models (A_1 \lor A_2)$ and $\{A_1, \neg A_2\} \models (A_1 \lor A_2)$)
- φ is satisfiable iff $\mu \models \varphi$ for some μ (i.e. $M(\varphi) \neq \emptyset$)
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Property

 φ is valid iff $\neg\varphi$ is unsatisfiable

Deduction Theorem $\alpha \models \beta$ iff $\alpha \rightarrow \beta$ is valid ($\models \alpha \rightarrow \beta$)

Corollary $\alpha \models \beta$ iff $\alpha \land \neg \beta$ is unsatisfiable

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 $\alpha \models \beta$ iff $\alpha \land \neg \beta$ is unsatisfiable

• α and β are equivalent iff, for every μ , $\mu \models \alpha$ iff $\mu \models \beta$ (i.e., if $M(\alpha) = M(\beta)$)

α and β are equi-satisfiable iff exists μ₁ s.t. μ₁ ⊨ α iff exists μ₂ s.t. μ₂ ⊨ β
(i.e., if M(α) ≠ Ø iff M(β) ≠ Ø)

- α, β equivalent $\downarrow \quad \cancel{\alpha}, \beta$ equi-satisfiable
- EX: $A_1 \lor A_2$ and $(A_1 \lor \neg A_3) \land (A_3 \lor A_2)$ are equi-satisfiable, not equivalent. $\{\neg A_1, A_2, A_3\} \models (A_1 \lor A_2)$, but $\{\neg A_1, A_2, A_3\} \not\models (A_1 \lor \neg A_3) \land (A_3 \lor A_2)$

• Typically used when β is the result of applying some transformation T to α : $\beta \stackrel{\text{def}}{=} T(\alpha)$:

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- T is validity-preserving [resp. satisfiability-preserving] iff
 - $T(\alpha)$ and α are equivalent [resp. equi-satisfiable]

- For N variables, there are up to 2^N truth assignments to be checked.
- The problem of deciding the satisfiability of a propositional formula is NP-complete
- The most important logical problems (validity, inference, entailment, equivalence, ...) can be straightforwardly reduced to (un)satisfiability, and are thus (co)NP-complete.

₩

No existing worst-case-polynomial algorithm.

• φ is in Conjunctive normal form iff it is a conjunction of disjunctions of literals:

 $\bigwedge_{i=1}^{L}\bigvee_{j_i=1}^{K_i}I_{j_i}$

- the disjunctions of literals $\bigvee_{j_i=1}^{K_i} I_{j_i}$ are called clauses
- Easier to handle: list of lists of literals.
 - \Longrightarrow no reasoning on the recursive structure of the formula

Classic CNF Conversion $CNF(\varphi)$

```
Every φ can be reduced into CNF by, e.g.,
(i) expanding implications and equivalences

α → β ⇒ ¬α ∨ β
α ↔ β ⇒ (¬α ∨ β) ∧ (α ∨ ¬β)

(ii) pushing down negations recursively:

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¬(α ∨ β) ⇒ ¬α ∧ ¬β
¬¬α ⇒ α
```

(iii) applying recursively the DeMorgan's Rule: $(\alpha \land \beta) \lor \gamma \implies (\alpha \lor \gamma) \land (\beta \lor \gamma)$

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• ex: $||CNF(\bigvee_{i=1}^{N}(I_{i1} \land I_{i2})|| = ||(I_{11} \lor I_{21} \lor ... \lor I_{N1}) \land (I_{12} \lor I_{21} \lor ... \lor I_{N1}) \land ... \land (I_{12} \lor I_{22} \lor ... \lor I_{N2})|| = 2^{N}$

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 - $\varphi \implies \varphi[(l_i \leftrightarrow l_j)|B] \land CNF(B \leftrightarrow (l_i \leftrightarrow l_j))$
 - I_i , I_j being literals and *B* being a "new" variable.
- Worst-case linear!
- $Atoms(CNF_{label}(\varphi)) \supseteq Atoms(\varphi)$
- CNF_{label}(φ) is equi-satisfiable w.r.t. φ: M(CNF(φ)) ≠ Ø iff M(φ) ≠ Ø
- Much more used than classic conversion in practice.

Labeling CNF conversion $CNF_{label}(\varphi)$

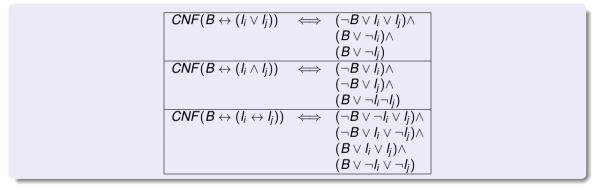
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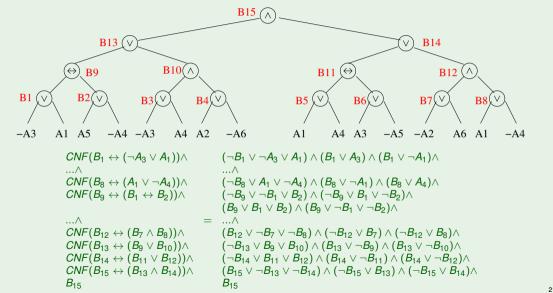
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Labeling CNF conversion $CNF_{label}(\varphi)$ (cont.)



Labeling CNF Conversion CNF_{label} – Example



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Outline



Propositional Logic

Propositional Reasoning

- Resolution
- DPLL
- Reasoning with Horn Formulas
- Local Search
- Agents Based on Knowledge Representation & Reasoning
 - Knowledge-Based Agents
 - Example: the Wumpus World
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Automated Reasoning in Propositional Logic fundamental task

- Al, formal verification, circuit synthesis, operational research,....
- Important in AI: KB ⊨ α: entail fact α from some knowledge base KR (aka Model Checking: M(KB) ⊆ M(α))
 - typically $||KB|| >> ||\alpha||$
 - sometimes *KB* set of variable implications $(A_1 \land ... \land A_k) \rightarrow B$
- All propositional reasoning tasks reduced to satisfiability (SAT)
 - $KR \models \alpha \Longrightarrow SAT(KR \land \neg \alpha) = false$
 - input formula CNF-ized and fed to a SAT solver
- Current SAT solvers dramatically efficient:
 - handle industrial problems with $10^6 10^7$ variables & clauses!
 - used as backend engines in a variety of systems (not only AI)

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 Resolution: deduction of a new clause from a pair of clauses with exactly one incompatible variable (resolvent):

• Ex:
$$\frac{(A \lor B \lor C \lor D \lor E)}{(A \lor B \lor D \lor E \lor F)}$$

• Note: many standard inference rules subcases of resolution:
(recall that $\alpha \to \beta \iff \neg \alpha \lor \beta$)

$$\frac{A \to B \ B \to C}{A \to C}$$
 (trans.) $\frac{A \ A \to B}{B}$ (m. ponens) $\frac{\neg B \ A \to B}{\neg A}$ (m. tollens)

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Assume input formula in CNF

• if not, apply Tseitin CNF-ization first

$\implies \varphi$ is represented as a set of clauses

- Search for a refutation of φ (is φ unsatisfiable?)
 - recall: $\alpha \models \beta$ iff $\alpha \land \neg \beta$ unsatisfiable
- Basic idea: apply iteratively the resolution rule to pairs of clauses with a conflicting literal, producing novel clauses, until either
 - a false clause is generated, or
 - the resolution rule is no more applicable
- Correct: if returns an empty clause, then φ unsat ($\alpha \models \beta$)
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Very-Basic PL-Resolution Procedure

function PL-RESOLUTION(KB, α) returns *true* or *false* inputs: KB, the knowledge base, a sentence in propositional logic α , the query, a sentence in propositional logic

 $clauses \leftarrow \text{the set of clauses in the CNF representation of } KB \land \neg \alpha$ $new \leftarrow \{ \ \}$

loop do

for each pair of clauses C_i , C_j in clauses do $resolvents \leftarrow PL-RESOLVE(C_i, C_j)$ if resolvents contains the empty clause then return true $new \leftarrow new \cup resolvents$ if $new \subseteq clauses$ then return false

 $clauses \gets clauses \cup new$

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General "set" notation (Γ clause set):

$$\frac{\Gamma,\phi_1,..\phi_n}{\Gamma,\phi_1',..\phi_{n'}'} \quad \left(e.g.\right)$$

• Removal of valid clauses:

• Clause Subsumption (*C* clause):

• Unit Resolution:

• Unit Subsumption:

 $\frac{\Gamma, C_1 \lor p, C_2 \lor \neg p}{\Gamma, C_1 \lor p, C_2 \lor \neg p, C_1 \lor C_2},$

• Unit Propagation = Unit Resolution + Unit Subsumption

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 $\Gamma \land (p \lor \neg p \lor C)$

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 $\frac{\Gamma \land C \land (C \lor \bigvee_{i} l_{i})}{\Gamma \land (C)}$ $\frac{\Gamma \land (l) \land (\neg l \lor \bigvee_{i} l_{i})}{\Gamma \land (l) \land (\bigvee_{i} l_{i})}$ $\frac{\Gamma \land (l) \land (I \lor \bigvee_{i} l_{i})}{\Gamma \land (l) \land (l \lor \bigvee_{i} l_{i})}$

 $\Gamma \land (p \lor \neg p \lor C)$

 $\frac{\Gamma, C_1 \lor p, C_2 \lor \neg p}{\Gamma, C_1 \lor p, C_2 \lor \neg p, C_1 \lor C_2},$

- Unit Subsumption:
- Unit Propagation = Unit Resolution + Unit Subsumption

Improvements: Subsumption & Unit Propagation

General "set" notation (Γ clause set):

$$\frac{\Gamma,\phi_1,..\phi_n}{\Gamma,\phi_1',..\phi_{n'}'} \quad \left(e.g\right)$$

- Removal of valid clauses:
- Clause Subsumption (*C* clause):
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 $\frac{\Gamma \land (p \lor \neg p \lor C)}{\Gamma} \\
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"Deterministic" rule: applied before other "non-deterministic" rules!

Remark

What happens with more than 1 resolvent?

• Common mistake: the following is not a correct application of the resolution rule:

$$\frac{\Gamma, \ (C_1 \lor l_1 \lor l_2), \ (C_2 \lor \neg l_1 \lor \neg l_2)}{\Gamma, \ (C_1 \lor l_1 \lor l_2), \ (C_2 \lor \neg l_1 \lor \neg l_2), \ (C_1 \lor C_2)}$$

• Rather, a correct application would be:

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... but $(C_1 \lor C_2 \lor \neg l_1 \lor \neg l_2)$ is valid and should be removed

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Propositional Reasoning

- Resolution
- OPLL
- Reasoning with Horn Formulas
- Local Search
- Agents Based on Knowledge Representation & Reasoning
 - Knowledge-Based Agents
 - Example: the Wumpus World
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- $\bullet\,$ Tries to build an assignment μ satisfying φ
- At each step assigns a truth value to (all instances of) one atom
- Performs deterministic choices (mostly unit-propagation) first
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The DPLL Procedure [cont.]

function DPLL-SATISFIABLE?(*s*) **returns** *true* or *false* **inputs**: *s*, a sentence in propositional logic

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clauses \leftarrow the set of clauses in the CNF representation of s
symbols \leftarrow a list of the proposition symbols in s
return DPLL(clauses, symbols, { })
```

function DPLL(clauses, symbols, model) returns true or false

if every clause in clauses is true in model then return true if some clause in clauses is false in model then return false P, value \leftarrow FIND-PURE-SYMBOL(symbols, clauses, model) if P is non-null then return DPLL(clauses, symbols – P, model \cup {P=value})) P, value \leftarrow FIND-UNIT-CLAUSE(clauses, model) if P is non-null then return DPLL(clauses, symbols – P, model \cup {P=value})) $P \leftarrow$ FIRST(symbols); rest \leftarrow REST(symbols) return DPLL(clauses, rest, model \cup {P=true}) or DPLL(clauses, rest, model \cup {P=false}))

(© S. Russell & P. Norwig, AIMA)

Pure-Symbol Rule out of date, no more used in modern solvers.

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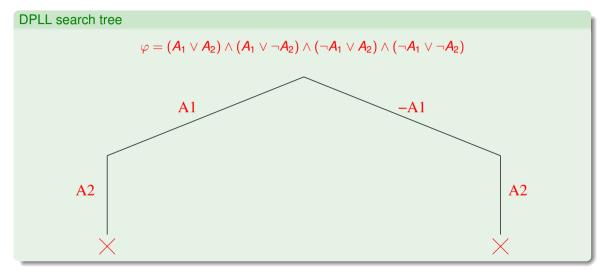
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DPLL: Example



DPLL – example

DPLL (without pure-literal rule)

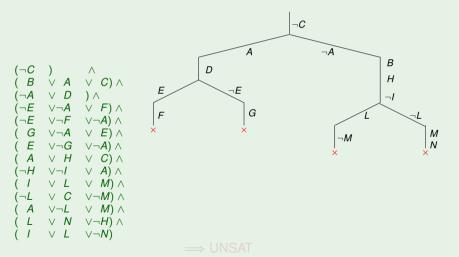
Here "choose-literal" selects variable in alphabetic order, selecting true first.

 \implies UNSAT

DPLL – example

DPLL (without pure-literal rule)

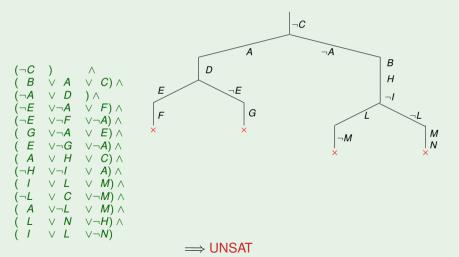
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 - inspired to conflict-driven backjumping and learning in CSPs
 - learns implied clauses as nogoods
- Random restarts
 - abandon the current search tree and restart on top level
 - previously-learned clauses maintained
- Smart literal selection heuristics (ex: VSIDS)
 - "static": scores updated only at the end of a branch
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• A Horn clause is a clause containing at most one positive literal

- a definite clause is a clause containing exactly one positive literal
- a goal clause is a clause containing no positive literal
- A Horn formula is a conjunction/set of Horn clauses

• Ex: $\begin{array}{c} A_1 \lor \neg A_2 & // \text{ definite} \\ A_2 \lor \neg A_3 \lor \neg A_4 & // \text{ definite} \\ \neg A_5 \lor \neg A_3 \lor \neg A_4 & // \text{ goal} \\ A_3 & // \text{ definite} \end{array}$

• Intuition: implications between positive Boolean variables:

 $egin{array}{ccc} A_2 & op & A_1 \ (A_3 \wedge A_4) & op & A_2 \ (A_5 \wedge A_3 \wedge A_4) & op & \bot \ & A_3 \end{array}$

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- Often allow to represent knowledge-base entailment $KB \models \alpha$:
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Property

Checking the satisfiability of Horn formulas requires polynomial time:

Hint:

- Eliminate unit clauses by propagating their value;
- If an empty clause is generated, return unsat
- Otherwise, every clause contains at least one negative literal
- \Rightarrow Assign all variables to ot; return the assignment
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A simple polynomial procedure for Horn-SAT

```
function Horn_SAT(formula \varphi, assignment & \mu) {

Unit_Propagate(\varphi, \mu);

if (\varphi == \bot)

then return UNSAT;

else {

\mu := \mu \cup \bigcup_{A_i \not\in \mu} \{\neg A_i\};

return SAT;

}

function Unit_Propagate(formula & \varphi, assignment & \mu)
```

```
while (\varphi \neq \top and \varphi \neq \bot and {a unit clause (I) occurs in \varphi}) do {

\varphi = assign(\varphi, I);

\mu := \mu \cup \{I\};
```

$$\begin{array}{cccc} \neg A_1 & \lor & A_2 & \lor \neg A_3 \\ A_1 & \lor \neg A_3 & \lor \neg A_4 \\ \neg A_2 & \lor \neg A_4 \\ A_3 & \lor \neg A_4 \\ A_4 \end{array}$$

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$$\mu := \{A_4 := \top, A_3 := \top\}$$

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$$\mu := \{A_{4} := \top, A_{3} := \top, A_{2} := \bot\}$$

$$\begin{array}{ccc} \neg A_1 & \lor & A_2 & \lor \neg A_3 & \times \\ A_1 & \lor \neg A_3 & \lor \neg A_4 \\ \neg A_2 & \lor \neg A_4 \\ A_3 & \lor \neg A_4 \\ A_4 \end{array}$$
$$\mu := \{A_4 := \top, A_3 := \top, A_2 := \bot, A_1 := \top\} \Longrightarrow \mathsf{UNSAT}$$

$$\begin{array}{cccc} A_1 & \bigtriangledown \neg A_2 \\ A_2 & \lor \neg A_5 & \lor \neg A_4 \\ A_4 & \lor \neg A_3 \\ A_3 \end{array}$$

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$$\begin{array}{ccc} A_1 & \vee \neg A_2 \\ A_2 & \vee \neg A_5 & \vee \neg A_4 \\ A_4 & \vee \neg A_3 \\ A_3 \end{array} \\ \mu := \{ \textbf{A}_3 := \top \} \end{array}$$

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$$\mu:=\{\textbf{A}_3:=\top, \textbf{A}_4:=\top\}\end{array}$$

$$\begin{array}{ccc} \mathcal{A}_1 & \bigtriangledown \neg \mathcal{A}_2 \\ \mathcal{A}_2 & \lor \neg \mathcal{A}_5 & \lor \neg \mathcal{A}_4 \\ \mathcal{A}_4 & \lor \neg \mathcal{A}_3 \\ \mathcal{A}_3 \end{array}$$

 $\mu := \{ \mathbf{A_3} := \top, \mathbf{A_4} := \top \} \Longrightarrow \mathsf{SAT}$

Outline



Propositional Logic

Propositional Reasoning

- Resolution
- DPLL
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- Local Search
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 - Knowledge-Based Agents
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Similar to Local Search for CSPs

- Input: set of clauses
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 - allow states with unsatisfied clauses
 - "neighbour states" differ for one variable truth value
 - steps: reassign variable truth values
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- Stochastic local search [see Ch. 4] applies to SAT as well
 - random walk, simulated annealing, GAs, taboo search, ...
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- Note: can detect only satisfiability, not unsatisfiability
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prob. p: flip variable from *C* at random prob. 1-p: flip variable from *C* causing a minimum number of unsat clauses

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The WalkSAT Procedure

function WALKSAT(*clauses*, *p*, *max_flips*) **returns** a satisfying model or *failure* **inputs**: *clauses*, a set of clauses in propositional logic

p, the probability of choosing to do a "random walk" move, typically around 0.5 max_flips , number of flips allowed before giving up

 $model \leftarrow$ a random assignment of true/false to the symbols in clauses

for i = 1 to max_flips do

if model satisfies clauses then return model

 $clause \leftarrow$ a randomly selected clause from clauses that is false in modelwith probability p flip the value in model of a randomly selected symbol from clauseelse flip whichever symbol in clause maximizes the number of satisfied clauses return failure

(© S. Russell & P. Norwig, AIMA)

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You can think about deep learning as equivalent to ... our visual cortex or auditory cortex. But, of course, true intelligence is a lot more than just that, you have to recombine it into higher-level thinking and symbolic reasoning, a lot of the things classical AI tried to deal with in the 80s.

•••

We would like to build up to this symbolic level of reasoning - maths, language, and logic. So that's a big part of our work.

Demis Hassabis, CEO of Google Deepmind

- Knowledge Representation & Reasoning (KR&R): the field of AI dedicated to representing knowledge of the world in a form a computer system can utilize to solve complex tasks
- The class of systems/agents that derive from this approach are called knowledge based (KB) systems/agents
- A KB agent maintains a knowledge base (KB) of facts
 - collection of domain-specific facts believed by the agent
 - expressed in a formal language (e.g. propositional logic)
 - represent the agent's representation of the world
 - initially contains the background knowledge
 - KB queries and updates via logical entailment, performed by an inference engine
- Inference engine allows for inferring actions and new knowledge
 - domain-independent algorithms, can answer any question



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• Reasoning: formal manipulation of the symbols representing a collection of beliefs to produce representations of new ones

- Logical entailment ($KB \models \alpha$) is the fundamental operation -
- Ex:
 - (KB acquired fact): "Patient x is allergic to medication m"
 - (KB general rule): "Anybody allergic to m is also allergic to m'."
 - (KB general rule): "If x is allergic to m', do not prescribe m' for x."
 - (query): "Prescribe m' for x?"
 - (answer) No (because patient x is allergic to medication m')
- Other forms of reasoning (last part of this course)
 - Probablistic reasoning
- Other forms of reasoning (not addressed in this course)
 - Abductive reasoning (aka diagnosis): given *KB* and β , conjecture hypotheses α s.t (*KB* $\land \alpha$) $\models \beta$
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- KB Agent must be able to:
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- Agents can be described at different levels
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Knowledge-Based Agent: General Schema

• Given a percept, the agent

- Tells the KB of the percept at time step t
- ASKs the KB for the best action to do at time step t
- Tells the KB that it has in fact taken that action
- Details hidden in three functions: MAKE-PERCEPT-SENTENCE, MAKE-ACTION-QUERY, MAKE-ACTION-SENTENCE
 - construct logic sentences
 - implement the interface between sensors/actuators and KRR core
- Tell and Ask may require complex logical inference

function KB-AGENT(*percept*) **returns** an *action* **persistent**: *KB*, a knowledge base

t, a counter, initially 0, indicating time

```
TELL(KB, MAKE-PERCEPT-SENTENCE(percept, t))

action \leftarrow Ask(KB, MAKE-ACTION-QUERY(t))

TELL(KB, MAKE-ACTION-SENTENCE(action, t))

t \leftarrow t + 1

return action
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Task Environment: PEAS Description

Performance measure:

- gold: +1000, death: -1000
- step: -1, using the arrow: -10

Environment:

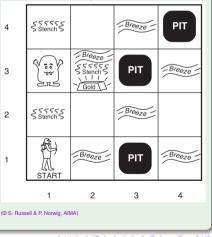
- squares adjacent to Wumpus are stenchy
- squares adjacent to pit are breezy
- glitter iff gold is in the same square
- shooting kills Wumpus if you are facing it
- shooting uses up the only arrow
- grabbing picks up gold if in same square
- releasing drops the gold in same square

Actuators:

Left turn, Right turn, Forward, Grab, Release, Shoot

Sensors:

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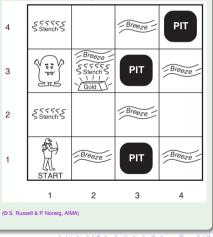
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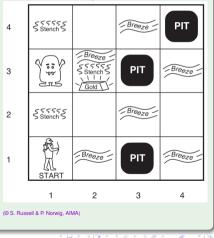
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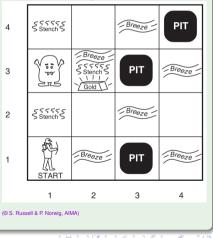
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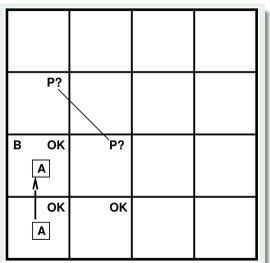
- The KB initially contains the rules of the environment.
- Agent is initially in 1,1
- Percepts: no stench, no breeze
- ⇒ [1,2] and [2,1] OK

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ок А	ок	

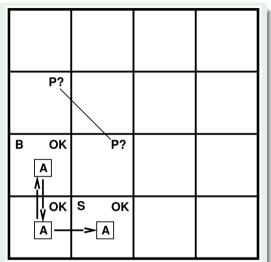
- Agent moves to [2,1]
- perceives a breeze
- ⇒ Pit in [3,1] or [2,2]
- perceives no stench
- ⇒ no Wumpus in [3,1], [2,2]

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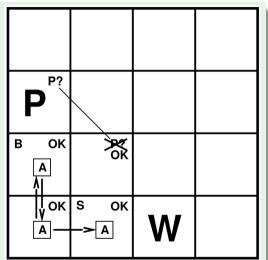
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- ⇒ Pit in [3,1] or [2,2]
- perceives no stench
- ⇒ no Wumpus in [3,1], [2,2]



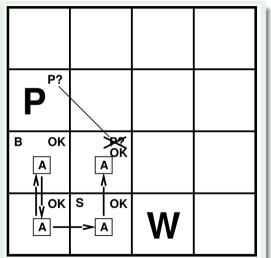
- Agent moves to [1,1]-[1,2]
- perceives no breeze
- ⇒ no Pit in [1,3], [2,2]
- ⇒ [2,2] OK
- \Rightarrow pit in [3,1]
- perceives a stench
- ⇒ Wumpus in [2,2] or [1,3]!



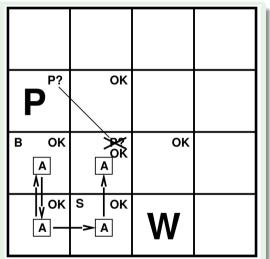
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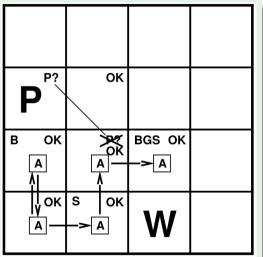
- Agent moves to [2,2]
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- ⇒ no Wumpus in [3,2], [2,3] ⇒ [3,2] and [2,3] OK

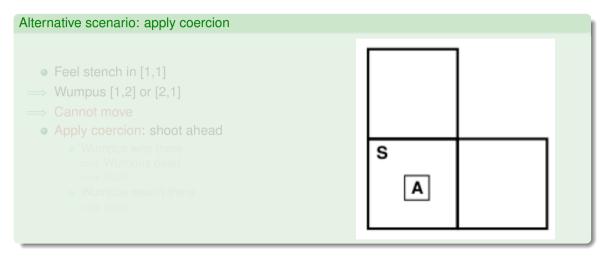


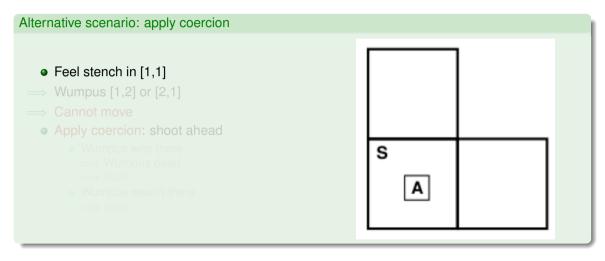
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- \Rightarrow [3,2] and [2,3] OK

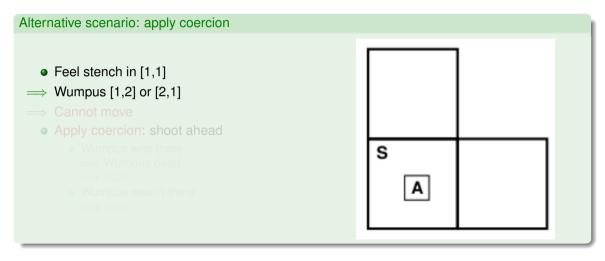


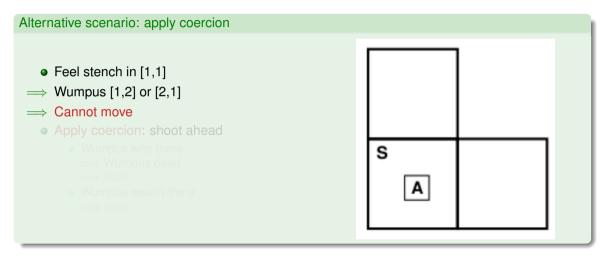
- Agent moves to [2,3]
- perceives a glitter
- \Rightarrow bag of gold!

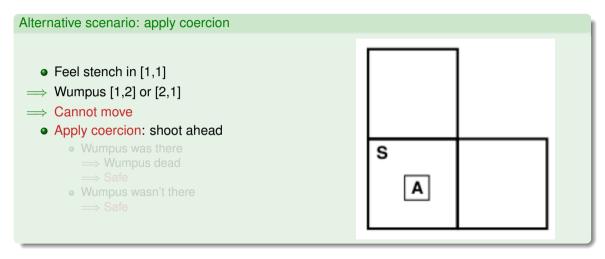


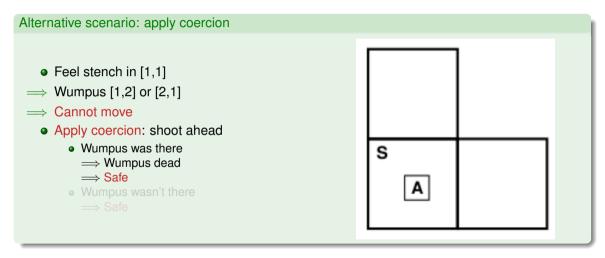


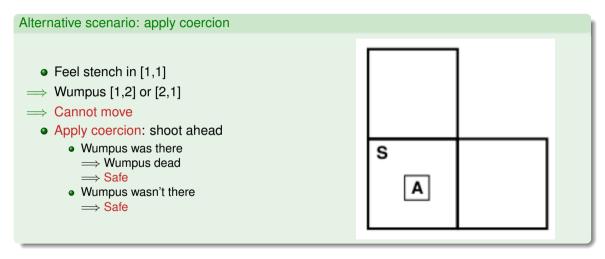


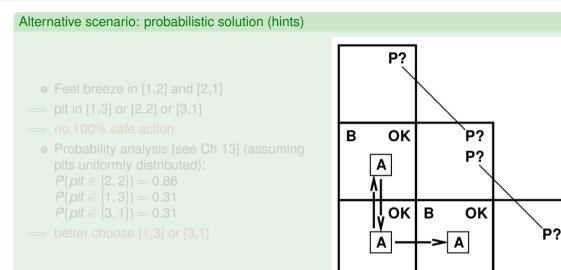


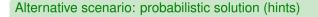










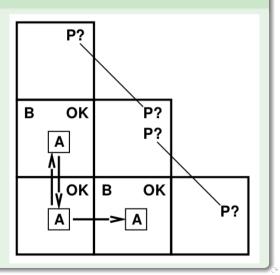


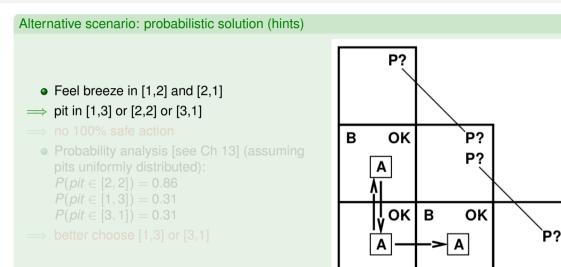
• Feel breeze in [1,2] and [2,1]

- ⇒ pit in [1,3] or [2,2] or [3,1]
- \implies no 100% safe action

• Probability analysis [see Ch 13] (assuming pits uniformly distributed): $P(pit \in [2, 2]) = 0.86$ $P(pit \in [1, 3]) = 0.31$ $P(pit \in [3, 1]) = 0.31$

 \implies better choose [1,3] or [3,1]



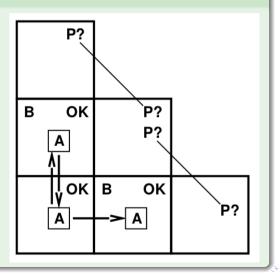


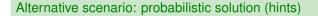


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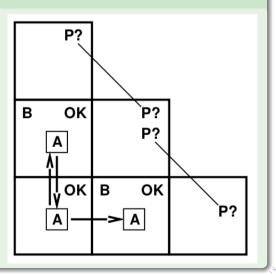
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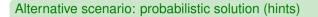
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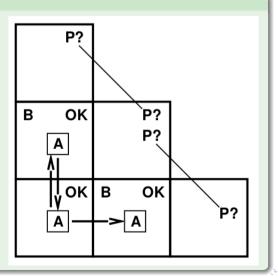


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Outline

Propositional Log

Propositional Reasoning

- Resolution
- DPLL
- Reasoning with Horn Formulas
- Local Search
- Agents Based on Knowledge Representation & Reasoning
 - Knowledge-Based Agents
 - Example: the Wumpus World

Agents Based on Propositional Reasoning

- Propositional Logic Agents
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Agents Based on Propositional Reasoning

- Propositional Logic Agents
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• Kind of Logic agents

• Language: propositional logic, first-order logic, ...

- represent KB as set of propositional formulas
- percepts and actions are (collections of) propositional atoms
- in practice: sets of clauses
- Perform propositional logic inference
 - model checking, entailment
 - in practice: incremental calls to a SAT solver

Kind of Logic agents

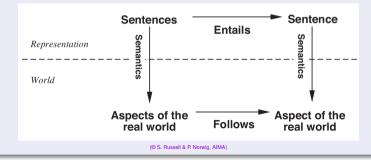
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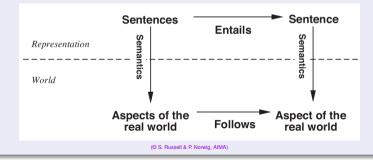
Reasoning process (propositional entailment) sound

- sentences are configurations of the agent
- reasoning constructs new configurations from old ones
 - the new configurations represent aspects of the world that actually follow from the aspects that the old configurations represent



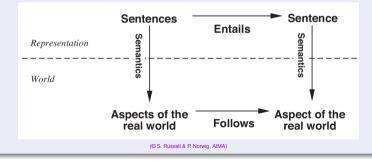
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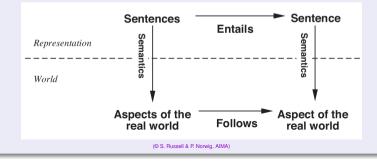
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Scenario in Wumpus World

Consider pits (and breezes) only:

- initial: $\neg P_{[1,1]}$
- after detecting nothing in [1,1]: $\neg B_{[1,1]}$
- move to [2,1], detect breeze: $B_{[2,1]}$
- Q: are there pits in [1,2], [2,1], [3,1]?
- 3 variables: $P_{[1,2]}, P_{[2,1]}, P_{[3,1]}, \implies$ 8 possible models
 - Query α_1 : $KB \models \neg P_{[1,2]}$
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R

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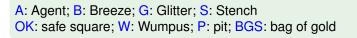
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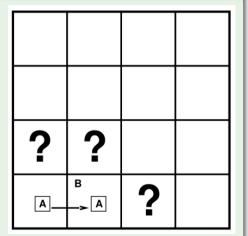
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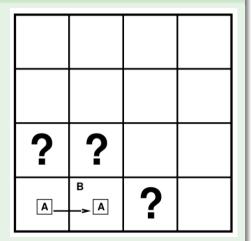
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Scenario in Wumpus World

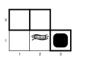
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8 possible models











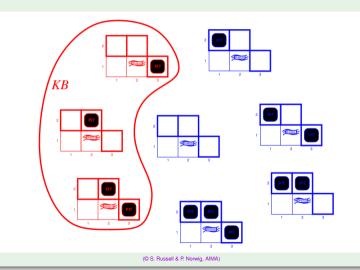






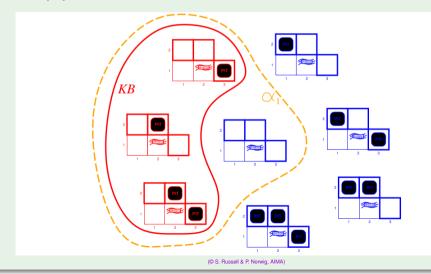
(© S. Russell & P. Norwig, AIMA)

KB: Wumpus World rules + observations \implies 3 models

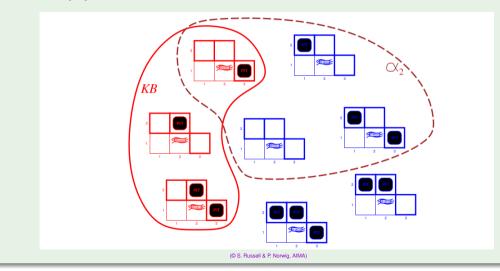


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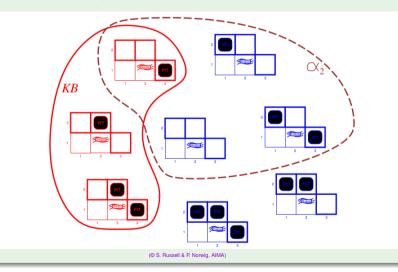
Query $\alpha_1 : \neg P_{[1,2]} \Longrightarrow KB \models \alpha_1$ (i.e $M(KB) \subseteq M(\alpha_1)$)



Query $\alpha_2 : \neg P_{[2,2]} \Longrightarrow KB \not\models \alpha_2$ (i.e $M(KB) \not\subseteq M(\alpha_2)$)



In practice: $DPLL(CNF(KB \land \neg \alpha_2)) = sat$



Outline

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Propositional Reasoning

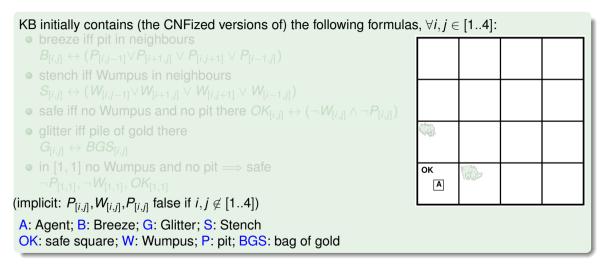
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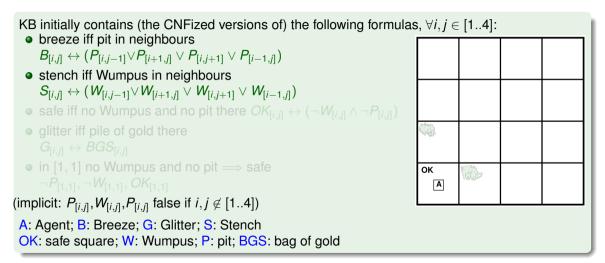
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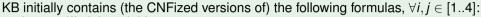
Example: Exploring the Wumpus World



KB initially contains (the CNFized versions of) the following formulas, $\forall i, j \in [1..4]$: breeze iff pit in neighbours $B_{[i,i]} \leftrightarrow (P_{[i,i-1]} \lor P_{[i+1,i]} \lor P_{[i,i+1]} \lor P_{[i-1,i]})$ stench iff Wumpus in neighbours • safe iff no Wumpus and no pit there $OK_{[i,j]} \leftrightarrow (\neg W_{[i,j]} \land \neg P_{[i,j]})$ • alitter iff pile of aold there • in [1, 1] no Wumpus and no pit \implies safe OK Α (implicit: $P_{[i,j]}, W_{[i,j]}, P_{[i,j]}$ false if $i, j \notin [1..4]$) A: Agent; B: Breeze; G: Glitter; S: Stench OK: safe square; W: Wumpus; P: pit; BGS: bag of gold



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• breeze iff pit in neighbours

 $B_{[i,j]} \leftrightarrow (P_{[i,j-1]} \lor P_{[i+1,j]} \lor P_{[i,j+1]} \lor P_{[i-1,j]})$

stench iff Wumpus in neighbours

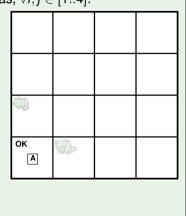
 $\mathcal{S}_{[i,j]} \leftrightarrow (\mathcal{W}_{[i,j-1]} \lor \mathcal{W}_{[i+1,j]} \lor \mathcal{W}_{[i,j+1]} \lor \mathcal{W}_{[i-1,j]})$

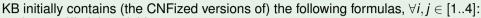
- safe iff no Wumpus and no pit there $OK_{[i,j]} \leftrightarrow (\neg W_{[i,j]} \land \neg P_{[i,j]})$
- glitter iff pile of gold there

 $G_{[i,j]} \leftrightarrow BGS_{[i,j]}$

• in [1, 1] no Wumpus and no pit \implies safe $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$

(implicit: $P_{[i,j]}, W_{[i,j]}, P_{[i,j]}$ false if $i, j \notin [1..4]$)





• breeze iff pit in neighbours

 $B_{[i,j]} \leftrightarrow (P_{[i,j-1]} \lor P_{[i+1,j]} \lor P_{[i,j+1]} \lor P_{[i-1,j]})$

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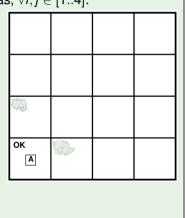
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- safe iff no Wumpus and no pit there $OK_{[i,j]} \leftrightarrow (\neg W_{[i,j]} \land \neg P_{[i,j]})$
- glitter iff pile of gold there
 - $G_{[i,j]} \leftrightarrow BGS_{[i,j]}$
- in [1, 1] no Wumpus and no pit \implies safe $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$

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A: Agent; B: Breeze; G: Glitter; S: Stench

OK: safe square; W: Wumpus; P: pit; BGS: bag of gold



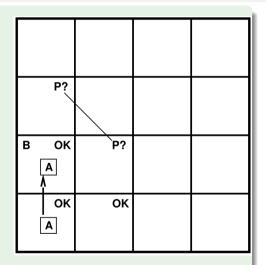
- KB initially contains: $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$ $B_{[1,1]} \leftrightarrow (P_{[1,2]} \lor P_{[2,1]})$ $S_{[1,1]} \leftrightarrow (W_{[1,2]} \lor W_{[2,1]})$ $OK_{[1,2]} \leftrightarrow (\neg W_{[1,2]} \land \neg P_{[1,2]})$ $OK_{[2,1]} \leftrightarrow (\neg W_{[2,1]} \land \neg P_{[2,1]})$
- Agent is initially in 1,1
- Percepts (no stench, no breeze): $\neg S_{[1,1]}$, $\neg B_{[1,1]}$
- $\Rightarrow \neg W_{[1,2]}, \neg W_{[2,1]}, \neg P_{[1,2]}, \neg P_{[2,1]}$
- $\Rightarrow OK_{[1,2]}, OK_{[2,1]}$ ([1,2]&[2,1] OK)
- Add all them to KB

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ок А	ок	

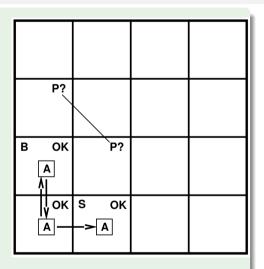
- KB initially contains: $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$ $B_{[2,1]} \leftrightarrow (P_{[1,1]} \lor P_{[2,2]} \lor P_{[3,1]})$ $S_{[2,1]} \leftrightarrow (W_{[1,1]} \lor W_{[2,2]} \lor W_{[3,1]})$...
- Agent moves to [2,1]
- perceives a breeze: *B*_[2,1]
- $\Rightarrow (P_{[3,1]} \lor P_{[2,2]})$ (pit in [3,1] or [2,2])
- perceives no stench $\neg S_{[2,1]}$
- → ¬W_[3,1], ¬W_[2,2] (no Wumpus in [3,1], [2,2])
- Add all them to KB

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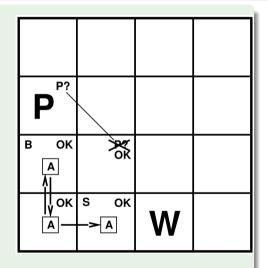
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- perceives no stench $\neg S_{[2,1]}$
- $\Rightarrow \neg W_{[3,1]}, \neg W_{[2,2]}$ (no Wumpus in [3,1], [2,2])
 - Add all them to KB



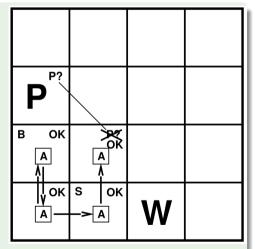
- KB initially contains: $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$ $(P_{[3,1]} \lor P_{[2,2]}), \neg W_{[3,1]}, \neg W_{[2,2]}$ $B_{[1,2]} \leftrightarrow (P_{[1,1]} \lor P_{[2,2]} \lor P_{[1,3]})$ $S_{[1,2]} \leftrightarrow (W_{[1,1]} \lor W_{[2,2]} \lor W_{[1,3]})$ $OK_{[2,2]} \leftrightarrow (\neg W_{[2,2]} \land \neg P_{[2,2]})$
- Agent moves to [1,1]-[1,2]
- perceives no breeze: $\neg B_{[1,2]}$
- ⇒ ¬ $P_{[2,2]}$, ¬ $P_{[1,3]}$ (no pit in [2,2], [1,3]) ⇒ $P_{[3,1]}$ (pit in [3,1])
- perceives a stench: $S_{[1,2]}$
- $\Rightarrow W_{[1,3]}$ (Wumpus in [1,3]!)
- ⇒ *OK*_[2,2] ([2,2] OK)
- Add all them to KB



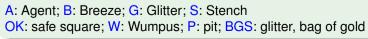
- KB initially contains: $\neg P_{[1,1]}, \neg W_{[1,1]}, OK_{[1,1]}$ $(P_{[3,1]} \lor P_{[2,2]}), \neg W_{[3,1]}, \neg W_{[2,2]}$ $B_{[1,2]} \leftrightarrow (P_{[1,1]} \lor P_{[2,2]} \lor P_{[1,3]})$ $S_{[1,2]} \leftrightarrow (W_{[1,1]} \lor W_{[2,2]} \lor W_{[1,3]})$ $OK_{[2,2]} \leftrightarrow (\neg W_{[2,2]} \land \neg P_{[2,2]})$
- Agent moves to [1,1]-[1,2]
- perceives no breeze: $\neg B_{[1,2]}$
- $\Rightarrow \neg P_{[2,2]}, \neg P_{[1,3]}$ (no pit in [2,2], [1,3])
- \implies $P_{[3,1]}$ (pit in [3,1])
 - perceives a stench: S_[1,2]
- \implies $W_{[1,3]}$ (Wumpus in [1,3]!)
- ⇒ *OK*_[2,2] ([2,2] OK)
 - Add all them to KB

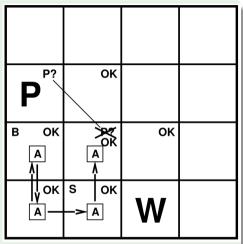


- KB initially contains:
 - $\begin{array}{l} B_{[2,2]} \leftrightarrow (P_{[2,1]} \lor P_{[3,2]} \lor P_{[2,3]} \lor P_{[1,2]}) \\ S_{[2,2]} \leftrightarrow (W_{[2,1]} \lor W_{[3,2]} \lor W_{[2,3]} \lor W_{[1,2]}) \\ OK_{[3,2]} \leftrightarrow (\neg W_{[3,2]} \land \neg P_{[3,2]}) \\ OK_{[2,3]} \leftrightarrow (\neg W_{[2,3]} \land \neg P_{[2,3]}) \end{array}$
- Agent moves to [2,2]
- perceives no breeze: $\neg B_{[2,2]}$
- $\Rightarrow \neg P_{[3,2]}, \neg P_{[2,3]}$ (no pit in [3,2], [2,3])
- perceives no stench: $\neg S_{[2,2]}$
- ⇒ $\neg W_{[3,2]}, \neg W_{[3,2]}$ (no Wumpus in [3,2], [2,3]) ⇒ $OK_{[3,2]}, OK_{[2,3]}$, ([3,2] and [2,3] OK) • Add all them to KB

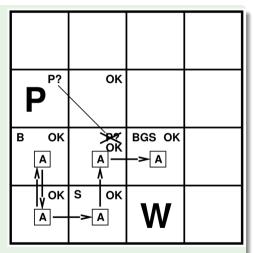


- KB initially contains:
 - $\begin{array}{l} B_{[2,2]} \leftrightarrow (P_{[2,1]} \lor P_{[3,2]} \lor P_{[2,3]} \lor P_{[1,2]}) \\ S_{[2,2]} \leftrightarrow (W_{[2,1]} \lor W_{[3,2]} \lor W_{[2,3]} \lor W_{[1,2]}) \\ OK_{[3,2]} \leftrightarrow (\neg W_{[3,2]} \land \neg P_{[3,2]}) \\ OK_{[2,3]} \leftrightarrow (\neg W_{[2,3]} \land \neg P_{[2,3]}) \end{array}$
- Agent moves to [2,2]
- perceives no breeze: $\neg B_{[2,2]}$
- ⇒ ¬**P**_[3,2], ¬**P**_[2,3] (no pit in [3,2], [2,3])
 - perceives no stench: $\neg S_{[2,2]}$
- $\implies \neg W_{[3,2]}, \neg W_{[3,2]}$ (no Wumpus in [3,2], [2,3])
- $\Rightarrow OK_{[3,2]}, OK_{[2,3]}, ([3,2] \text{ and } [2,3] OK)$
- Add all them to KB





- KB initially contains: $G_{[2,3]} \leftrightarrow BGS_{[2,3]}$
- Agent moves to [2,3]
- perceives a glitter: *G*_[2,3]
- $\Rightarrow BGS_{[2,3]}$ (bag of gold!)
- Add it them to KB



- Convert all formulas from KB into CNF
- Execute all steps in the example as resolution calls
- Execute all steps in the example as DPLL calls

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