

Fundamentals of Artificial Intelligence

Chapter 05: Adversarial Search and Games

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Outline

- 1 Games
- 2 Optimal Decisions in Games
- 3 Alpha-Beta Pruning
- 4 Adversarial Search with Resource Limits
- 5 Stochastic Games

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Games and AI

- Games are a form of **multi-agent environment**
 - Q.: **What do other agents do and how do they affect our success?**
 - recall: cooperative vs. competitive multi-agent environments
 - competitive multi-agent environments give rise to **adversarial problems** (aka **games**)
- Q.: **Why study games in AI?**
 - lots of fun, historically entertaining
 - **easy to represent**: agents restricted to **small number of actions** with **precise rules**
 - interesting also because **computationally very hard**
(ex: chess has $b \approx 35$, $\#nodes \approx 10^{40}$)
 - metaphor for important application domains
(e.g. competitive markets, life sciences, sport, politics, warfare, ...)

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Search and Games

- Search (with no adversary)

- solution is a (heuristic) method for finding a goal
- heuristics techniques can find optimal solutions
- evaluation function: estimate of cost from start to goal through given node
- examples: path planning, scheduling activities, ...

- Games (with adversary), aka adversarial search

- solution is a strategy: specifies a move for every possible opponent reply
- evaluation function (utility): evaluate “goodness” of game position
- examples: tic-tac-toe, chess, checkers, Othello, backgammon, ...
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Types of Games

- Many different kinds of games
- Relevant features:
 - deterministic vs. stochastic (with chance)
 - one, two, or more players
 - zero-sum vs. general games
 - perfect information (can you see the state?) vs. imperfect
- Most common: deterministic, turn-taking, two-player, zero-sum games, perfect information
- Want algorithms for calculating a strategy (aka policy):
 - recommends a move from each state: $policy : S \mapsto A$

(*) "blind tictactoe": a version of tic-tac-toe where the players don't get to see each others' moves.

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	deterministic	chance
perfect information	chess, checkers, go, othello	backgammon monopoly
imperfect information	battleships, blind tictactoe	bridge, poker, scrabble nuclear war

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Games: Main Concepts

- We first consider games with **two players**: “MAX” and “MIN”
 - MAX moves first;
 - they take turns moving until the game is over
 - at the end of the game, points are awarded to the winner and penalties are given to the loser
- A game is a kind of search problem:
 - Initial state S_0 : specifies how the game is set up at the start
 - $Player(s)$: defines which player has the move in a state
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defines the final numeric value for a game ending in state s for player p
 - ex: chess: 1 (win), 0 (loss), $\frac{1}{2}$ (draw)
- S_0 , $Actions(s)$ and $Result(s, a)$ recursively define the **game tree**
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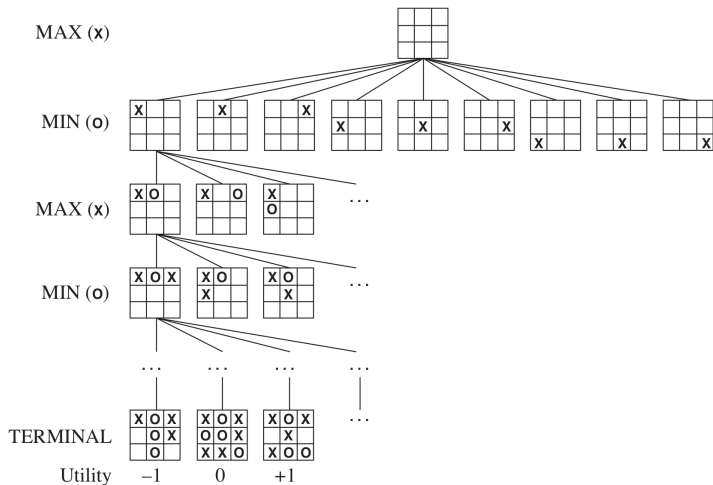
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Game Tree: Example

Partial game tree for tic-tac-toe (2-player, deterministic, turn-taking)



Zero-Sum Games vs. General Games

- General Games

- agents have independent utilities
- cooperation, indifference, competition, and more are all possible

- Zero-Sum Games: the total payoff to all players is the same for each game instance

- adversarial, pure competition
- agents have opposite utilities (values on outcomes)

⇒ Idea: With two-player zero-sum games, we can use one single utility value

- one agent maximizes it, the other minimizes it

⇒ optimal adversarial search as min-max search

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Adversarial Search as Min-Max Search

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- MAX must find a contingent strategy specifying:
 - MAX's move in the initial state
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(a single-agent move is called half-move or ply)

- Analogous to the AND-OR search algorithm
 - MAX playing the role of OR
 - MIN playing the role of AND
- Optimal strategy: for which $Minimax(s)$ returns the highest value

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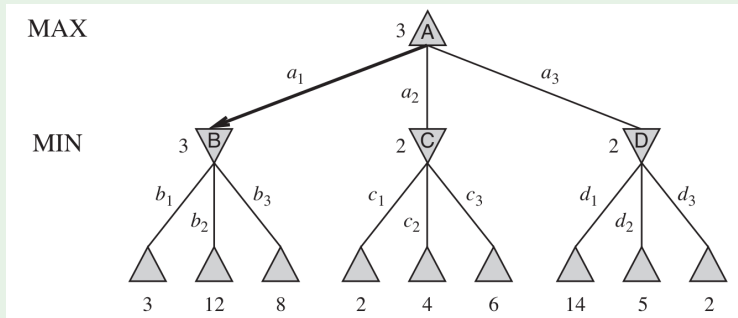
$$Minimax(s) \stackrel{\text{def}}{=} \begin{cases} Utility(s) & \text{if } TerminalTest(s) \\ \max_{a \in Actions(s)} Minimax(Result(s, a)) & \text{if } Player(s) = MAX \\ \min_{a \in Actions(s)} Minimax(Result(s, a)) & \text{if } Player(s) = MIN \end{cases}$$

Min-Max Search: Example

A two-ply game tree

- Δ nodes are “MAX nodes”, ∇ nodes are “MIN nodes”,
 - terminal nodes show the utility values for MAX
 - the other nodes are labeled with their minimax value
- Minimax maximizes the worst-case outcome for MAX

⇒ MAX's root best move is a_1

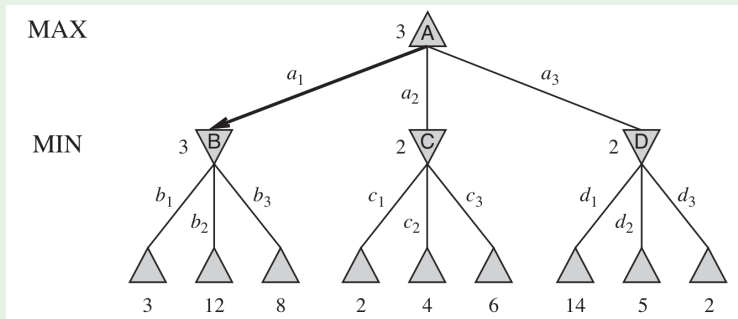


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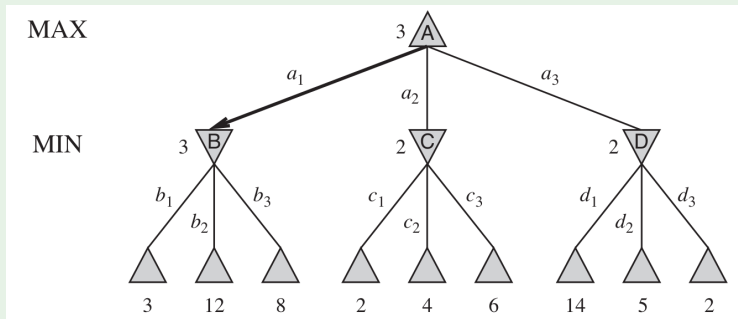


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The Minimax Algorithm

Depth-First Search Minimax Algorithm

```
function MINIMAX-DECISION(state) returns an action  
  return  $\arg \max_{a \in \text{ACTIONS}(s)} \text{MIN-VALUE}(\text{RESULT}(state, a))$ 
```

```
function MAX-VALUE(state) returns a utility value  
  if TERMINAL-TEST(state) then return UTILITY(state)  
   $v \leftarrow -\infty$   
  for each a in ACTIONS(state) do  
     $v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(s, a)))$   
  return v
```

```
function MIN-VALUE(state) returns a utility value  
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  for each a in ACTIONS(state) do  
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Multi-Player Games: Optimal Decisions

- Replace the single value for each node with a **vector of values**
 - terminal states: utility for each agent
 - agents, in turn, choose the action with best value for themselves
- Alliances are possible!
 - e.g., if one agent is in dominant position, the other can ally

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Multiplayer Min-Max Search: Example

The first three plies of a game tree with three players (A, B, C)

- Each node labeled with values from each player's viewpoint
- Agents choose the action with best value for themselves
- If A and B are allied, then they may agree that B and then A choose (5,4,5) instead of (1,5,2)
⇒ benefit for both

to move

A

(1, 2, 6)

B

(1, 2, 6)

(1, 5, 2)

C

(1, 2, 6)

X

(6, 1, 2)

(1, 5, 2)

(5, 4, 5)

A

(1, 2, 6)

(4, 2, 3)

(6, 1, 2)

(7, 4, 1)

(5, 1, 1)

(1, 5, 2)

(7, 7, 1)

(5, 4, 5)

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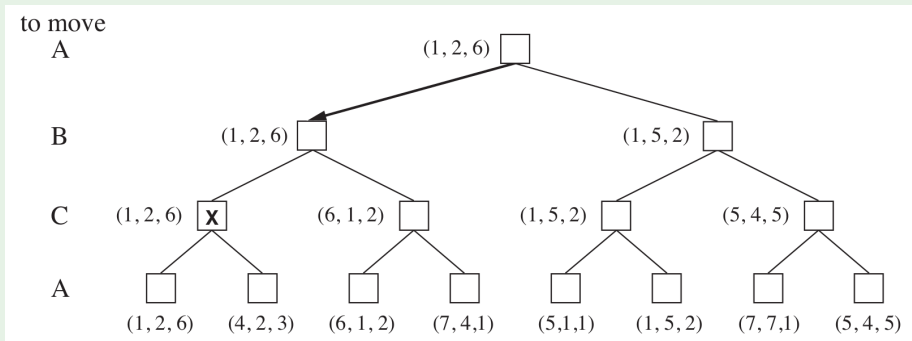
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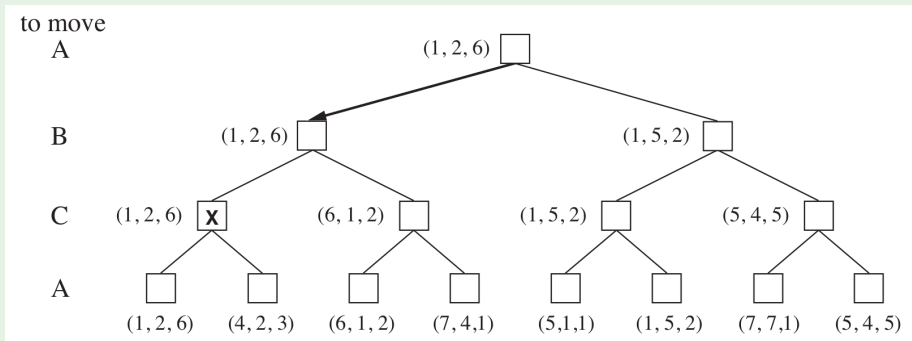
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Exercise

- Consider the Multiplayer Min-Max Search example of previous slide
 - Redo it with choice order A-C-B
 - Redo it with choice order C-A-B
 - Redo it with choice order C-B-A
 - Redo it with choice order B-A-C
 - Redo it with choice order B-C-A
- Do they have all the same outcome?
- For each case, try to define the best moves in case of alliance between the top two players

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The Minimax Algorithm: Properties

- Complete? Yes, if tree is finite
- Optimal? Yes, against an optimal opponent
 - What about non-optimal opponent?
⇒ even better, but non optimal in this case
- Time complexity? $O(b^m)$
- Space complexity? $O(bm)$ (DFS)

For chess, $b \approx 35$, $m \approx 100 \implies 35^{100} = 10^{154}$ (!)

We need to prune the tree!

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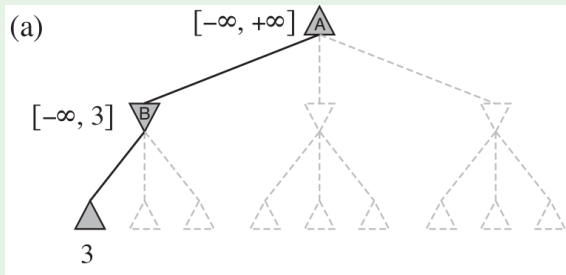
Outline

- 1 Games
- 2 Optimal Decisions in Games
- 3 Alpha-Beta Pruning**
- 4 Adversarial Search with Resource Limits
- 5 Stochastic Games

Pruning Min-Max Search: Example

- Consider the previous execution of the Minimax algorithm
- Let $[min, max]$ track the currently-known bounds for the search
 - (a): B labeled with $[-\infty, 3]$ (MIN will not choose values ≥ 3 for B)
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 - (d): Is it necessary to evaluate the remaining leaves of C?
NO! They cannot produce an upper bound ≥ 2
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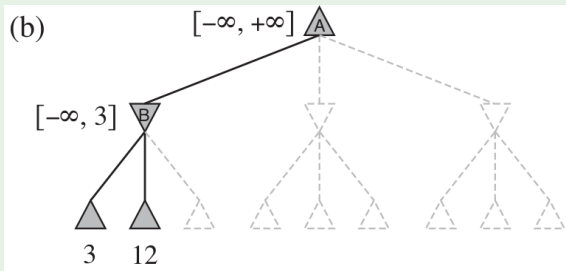
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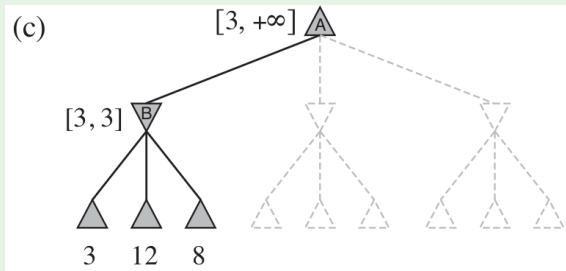
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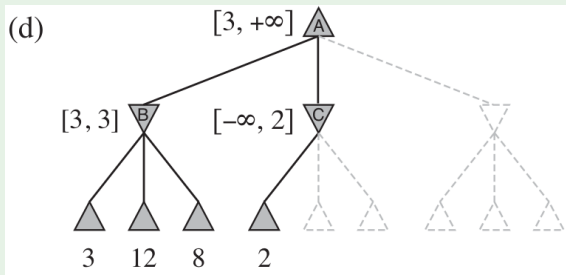
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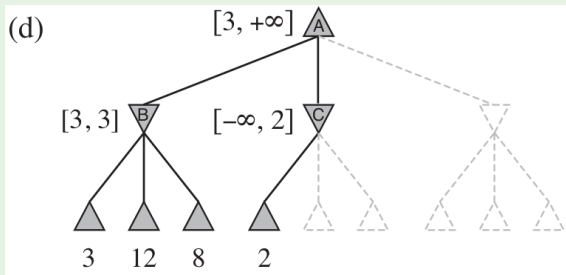
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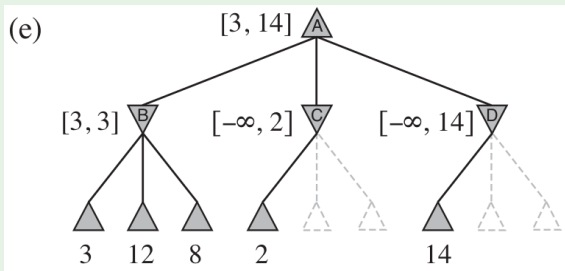
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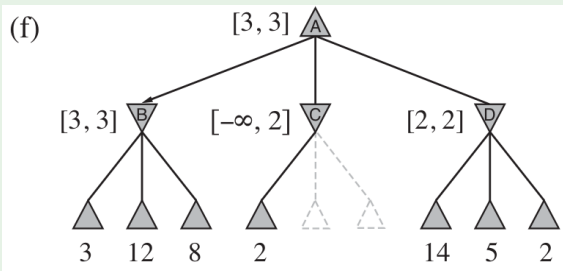
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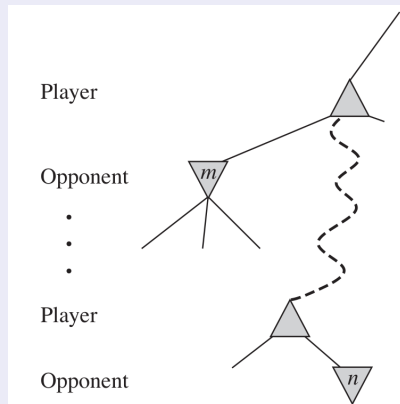
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Alpha-Beta Pruning Technique for Min-Max Search

- Idea: consider a node n (terminal or intermediate)
 - If player has a better choice m at the parent node of n or at any choice point further up, **n will never be reached in actual play**
- ⇒ if we know enough of n to draw this conclusion, **we can prune n**
- Alpha-Beta Pruning: nodes labeled with $[\alpha, \beta]$ s.t.:
 - α : best value for MAX (highest) so far off the current path
⇒ lower bound for future values
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- ⇒ Prune n if its value is worse (lower) than the current α value for MAX (dual for β , MIN)



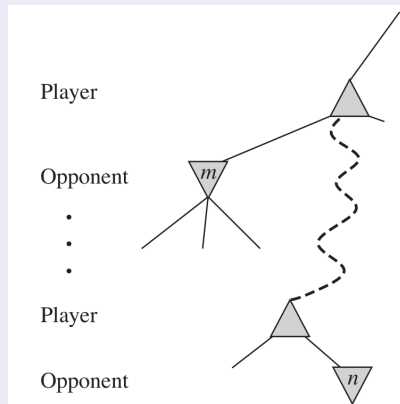
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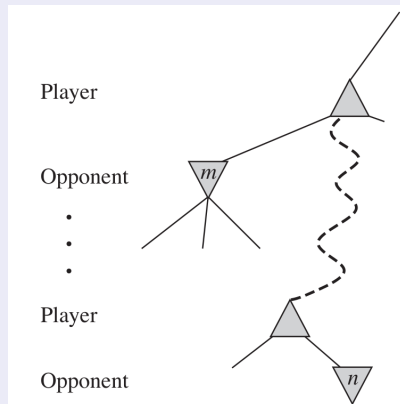
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The Alpha-Beta Search Algorithm

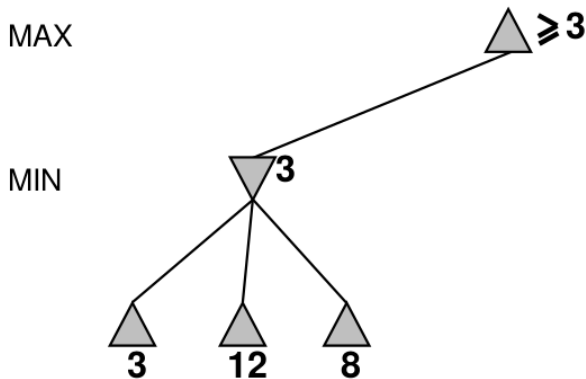
```
function ALPHA-BETA-SEARCH(state) returns an action  
   $v \leftarrow \text{MAX-VALUE}(\textit{state}, -\infty, +\infty)$   
  return the action in  $\text{ACTIONS}(\textit{state})$  with value  $v$ 
```

```
function MAX-VALUE(state,  $\alpha$ ,  $\beta$ ) returns a utility value  
if  $\text{TERMINAL-TEST}(\textit{state})$  then return  $\text{UTILITY}(\textit{state})$   
   $v \leftarrow -\infty$   
  for each  $a$  in  $\text{ACTIONS}(\textit{state})$  do  
     $v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(s,a), \alpha, \beta))$   
    if  $v \geq \beta$  then return  $v$   
     $\alpha \leftarrow \text{MAX}(\alpha, v)$   
  return  $v$ 
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function MIN-VALUE(state,  $\alpha$ ,  $\beta$ ) returns a utility value  
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     $v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(s,a), \alpha, \beta))$   
    if  $v \leq \alpha$  then return  $v$   
     $\beta \leftarrow \text{MIN}(\beta, v)$   
  return  $v$ 
```

Example revisited: Alpha-Beta Cuts

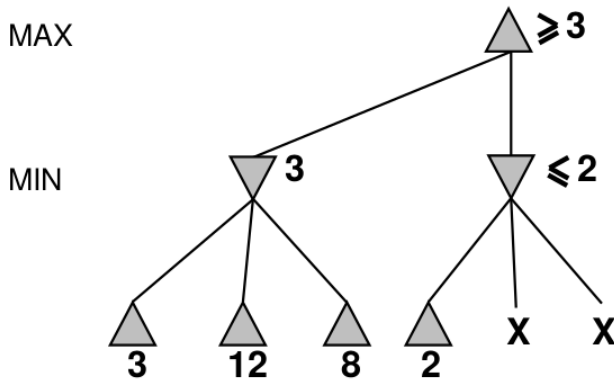
- Notation: $\geq \alpha$; $\leq \beta$;



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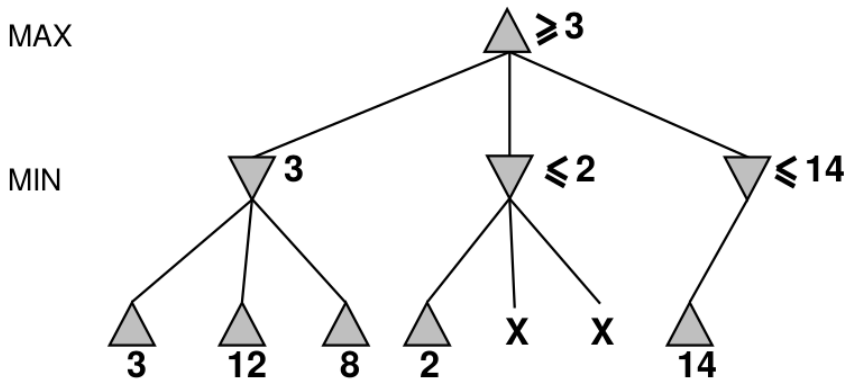
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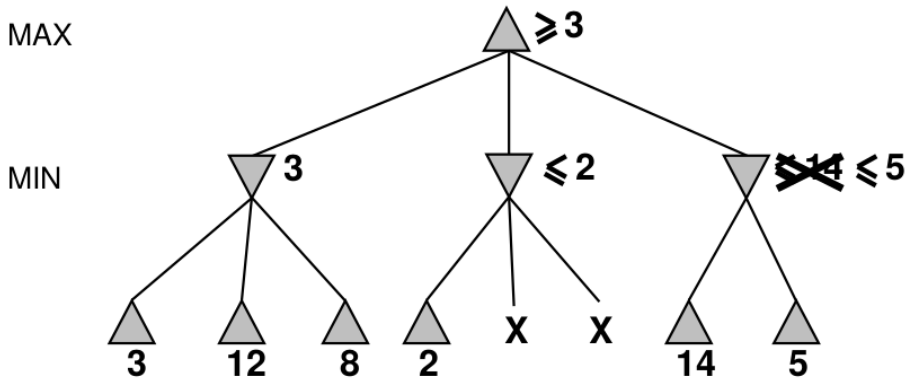
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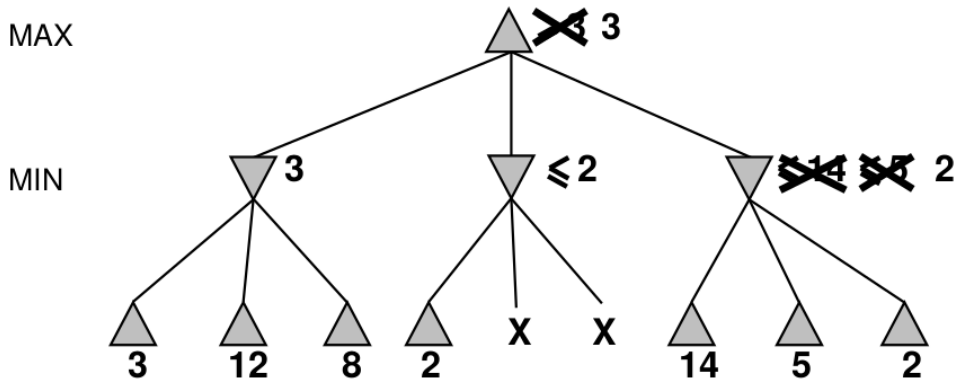
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Properties of Alpha-Beta Search

- Pruning does not affect the final result \implies correctness preserved
- Good move ordering improves effectiveness of pruning
 - Ex: if MIN expands 3rd child of D first, the others are pruned
 - try to examine first the successors that are likely to be best
- With “perfect” ordering, time complexity reduces to $O(b^{m/2})$
 - aka “killer-move heuristic” \implies doubles solvable depth!
- With “random” ordering, time complexity reduces to $O(b^{3m/4})$
- “Graph-based” version further improves performances
 - track explored states via hash table

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Properties of Alpha-Beta Search

- Pruning does not affect the final result \implies **correctness preserved**
- Good move ordering improves effectiveness of pruning
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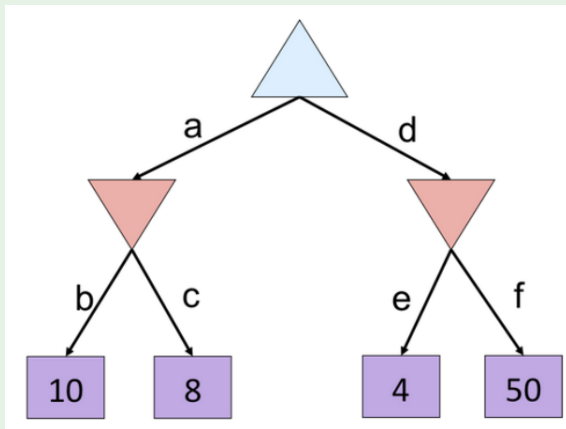
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Exercise 1

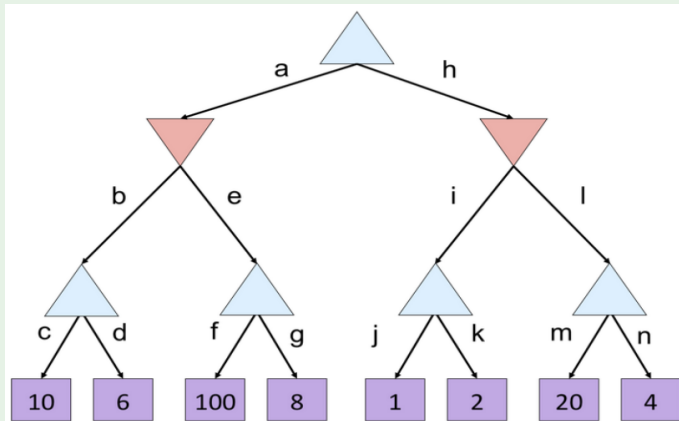
Apply alpha-beta search to the following tree



(© D. Klein, P. Abbeel, S. Levine, S. Russell, U. Berkeley)

Exercise II

Apply alpha-beta search to the following tree



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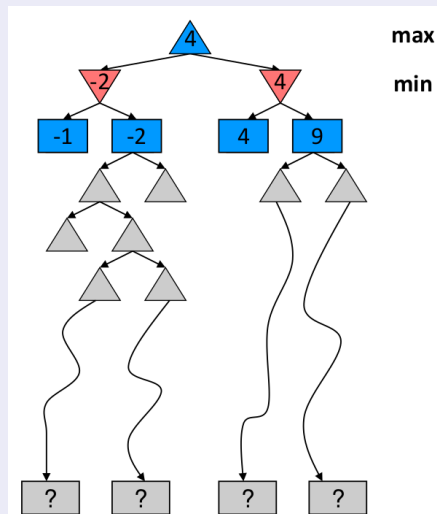
Outline

- 1 Games
- 2 Optimal Decisions in Games
- 3 Alpha-Beta Pruning
- 4 Adversarial Search with Resource Limits**
- 5 Stochastic Games

Adversarial Search with Resource Limits

Problem: In realistic games, full search is impractical!

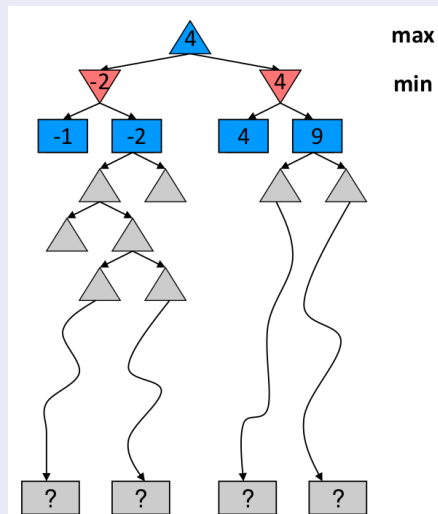
- Complexity: b^d (ex. chess: $\approx 35^{100}$)
- Idea [Shannon, 1949]: Depth-limited search
 - cut off minimax search earlier, after limited depth
 - replace terminal utility function with evaluation for non-terminal nodes
- Ex (chess): depth $d = 8$ (decent)
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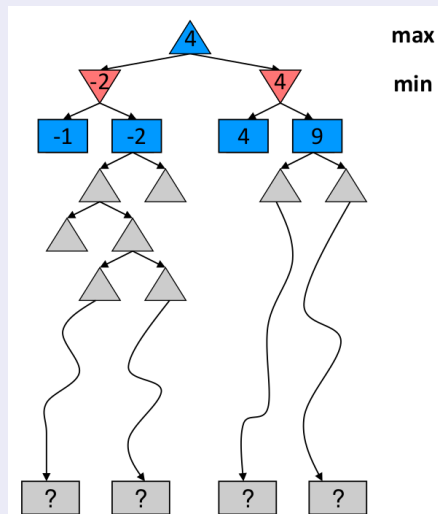
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Adversarial Search with Resource Limits [cont.]

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⇒ effectively turning nonterminal nodes into terminal leaves

- Modify *Minimax()* or Alpha-Beta search in two ways:

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⇒ Heuristic variant of *Minimax()*:

$$H\text{-Minimax}(s, d) \stackrel{\text{def}}{=} \begin{cases} Eval(s) & \text{if } CutOffTest(s, d) \\ \max_{a \in Actions(s)} H\text{-Minimax}(Result(s, a), d + 1) & \text{if } Player(s) = MAX \\ \min_{a \in Actions(s)} H\text{-Minimax}(Result(s, a), d + 1) & \text{if } Player(s) = MIN \end{cases}$$

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Evaluation Functions

Eval(s)

- Should be relatively cheap to compute
- Returns an estimate of the expected utility from a given position
 - Ideal function: returns the actual minimax value of the position
- Should order terminal states the same way as the utility function
 - e.g., wins > draws > losses
- For nonterminal states, should be strongly correlated with the actual chances of winning
- Defines equivalence classes of positions (same *Eval(s)* value)
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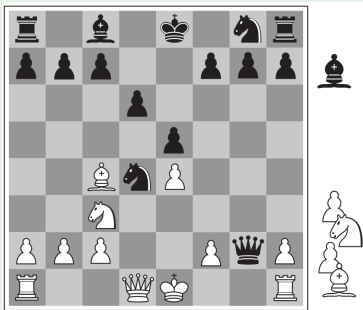
Example

- Two same-score positions (White: -8, Black: -3)

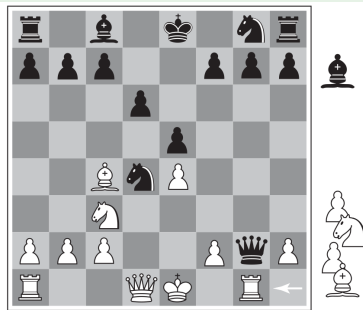
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(Personal note: only very-stupid black player would get into (b))



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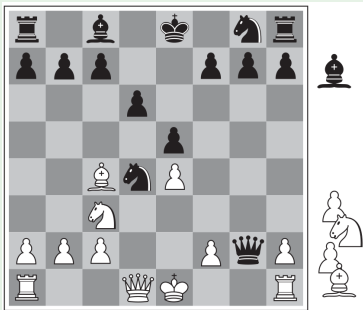


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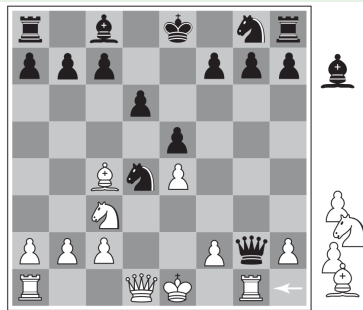
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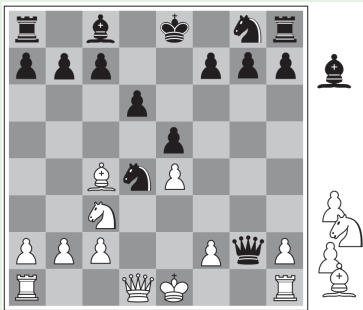


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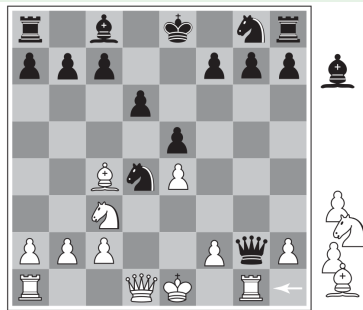
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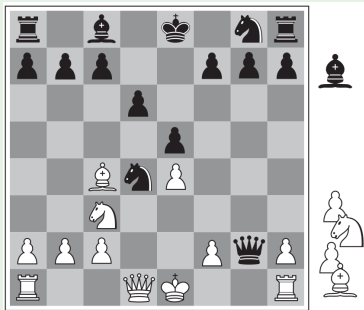


(b) White to move

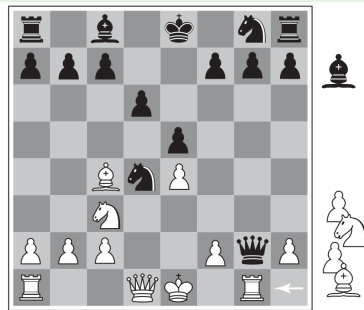
Example

- Two same-score positions (White: -8, Black: -3)
 - (a) Black has an advantage of a knight and two pawns,
⇒ should be enough to win the game
 - (b) White will capture the queen,
⇒ give it an advantage that should be strong enough to win

(Personal note: only very-stupid black player would get into (b))



(a) White to move



(b) White to move

Cutting-off the Search

CutOffTest(state, depth)

- Most straightforward approach: **set a fixed depth limit**
 - d chosen s.t. a move is selected within the allocated time
 - sometimes may produce very inaccurate outcomes (see previous example)
- More robust approach: **apply Iterative Deepening**
- More sophisticated: apply *Eval()* only to **quiescent** states
 - **quiescent**: unlikely to exhibit wild swings in value in the near future
 - e.g. positions with direct favorable captures are not quiescent (previous example (b))

⇒ **further expand non-quiescent states until quiescence is reached**

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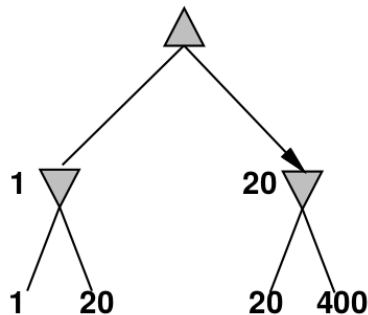
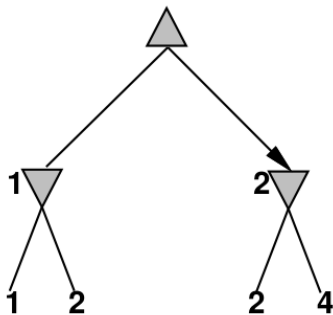
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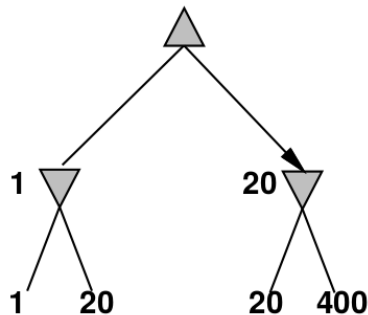
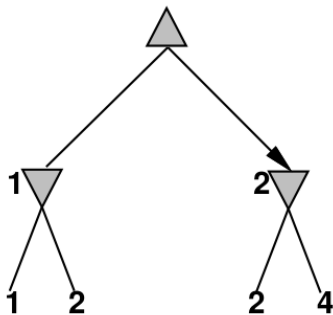
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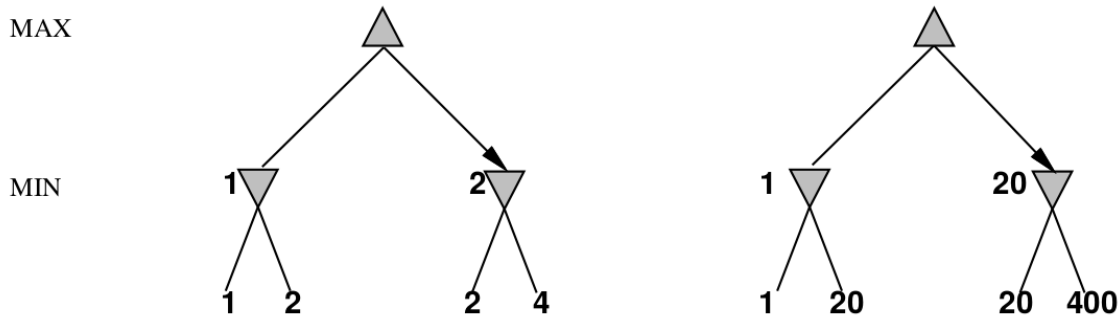


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Deterministic Games in Practice

- **Checkers:** (1994) **Chinook** ended 40-year-reign of world champion **Marion Tinsley**
 - used an endgame database defining perfect play for all positions involving 8 or fewer pieces on the board
 - a total of 443,748,401,247 positions
- **Chess:** (1997) **Deep Blue** defeated world champion **Gary Kasparov** in a six-game match
 - searches 200 million positions per second
 - uses very sophisticated evaluation, and undisclosed methods
- **Othello:**
 - Human champions refuse to compete against computers, which are too good
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Outline

- 1 Games
- 2 Optimal Decisions in Games
- 3 Alpha-Beta Pruning
- 4 Adversarial Search with Resource Limits
- 5 Stochastic Games**

Stochastic Games: Generalities

- In real life, **unpredictable external events may occur**
- **Stochastic Games** mirror unpredictability by **random steps**:
 - e.g. dice throwing, card-shuffling, coin flipping, tile extraction, ...
- Ex: Backgammon
- Cannot calculate definite minimax value, only **expected values**
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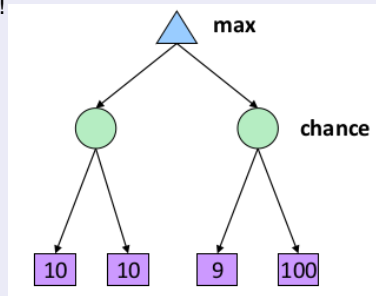
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An Example: Backgammon

- Rules

- 15 pieces each
- white moves clockwise to 25, black moves counterclockwise to 0
- a piece can move to a position unless ≥ 2 opponent pieces there
- if there is one opponent, it is captured and must start over
- termination: all whites in 25 or all blacks in 0

- Ex: Possible white moves (dice: 6,5):

(5-10,5-11)

(5-11,19-24)

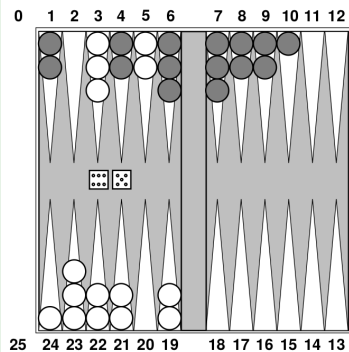
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⇒ **stochastic component** (dice)

- double rolls (1-1),..., (6-6)
have 1/36 probability each
- other 15 distinct rolls
have a 1/18 probability each



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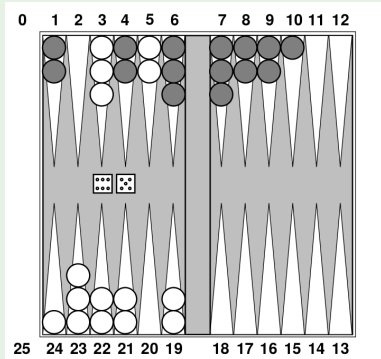
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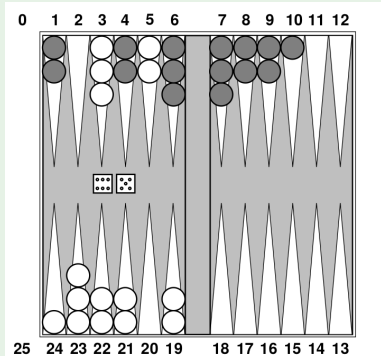
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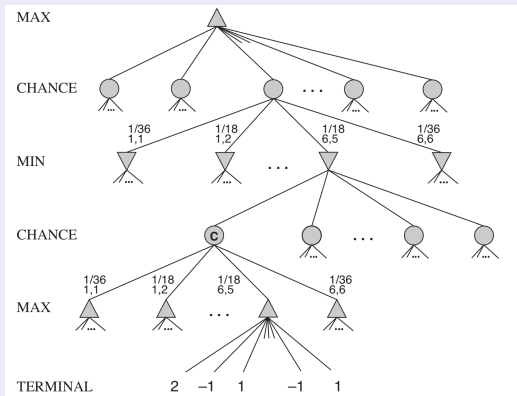
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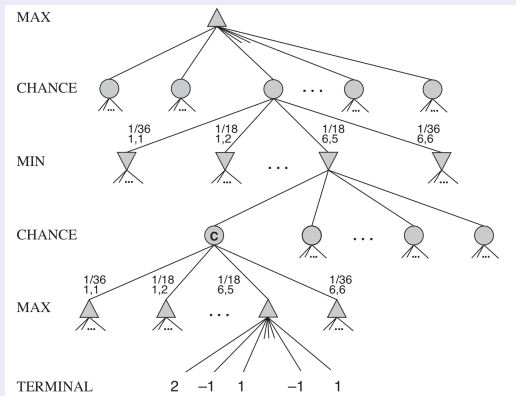
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- Idea: A game tree for a stochastic game includes chance nodes in addition to MAX and MIN nodes.
 - chance nodes above agent represent stochastic events for agent (e.g. dice roll)
 - outgoing arcs represent stochastic event outcomes
 - labeled with stochastic event and relative probability



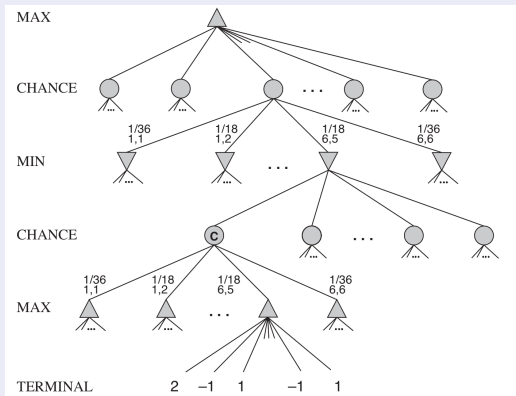
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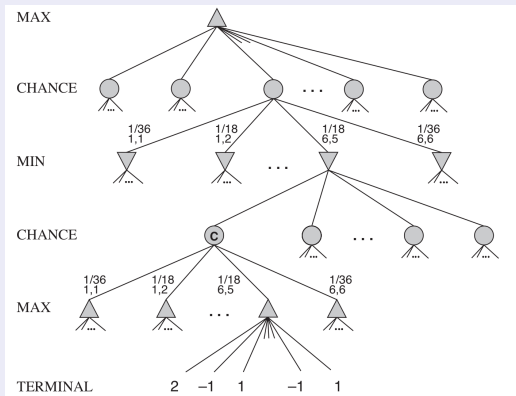
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Algorithm for Stochastic Games: *ExpectMinimax()*

- Extension of *Minimax()*, handling also chance nodes:

$$ExpectMinimax(s) \stackrel{\text{def}}{=} \begin{cases} Utility(s) & \text{if } TerminalTest(s) \\ \max_{a \in Actions(s)} ExpectMinimax(Result(s, a)) & \text{if } Player(s) = MAX \\ \min_{a \in Actions(s)} ExpectMinimax(Result(s, a)) & \text{if } Player(s) = MIN \\ \sum_r P(r) \cdot ExpectMinimax(Result(s, r)) & \text{if } Player(s) = Chance \end{cases}$$

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⇒ Returns the weighted average of the minimax outcomes (recall that $\sum_r P(r) = 1$)

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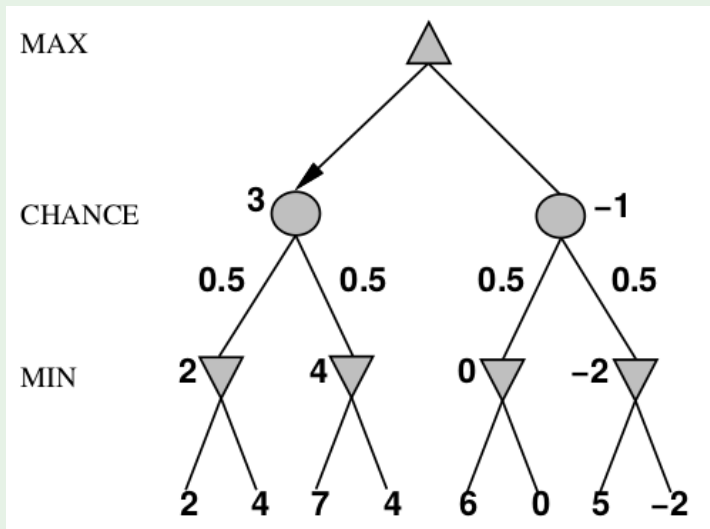
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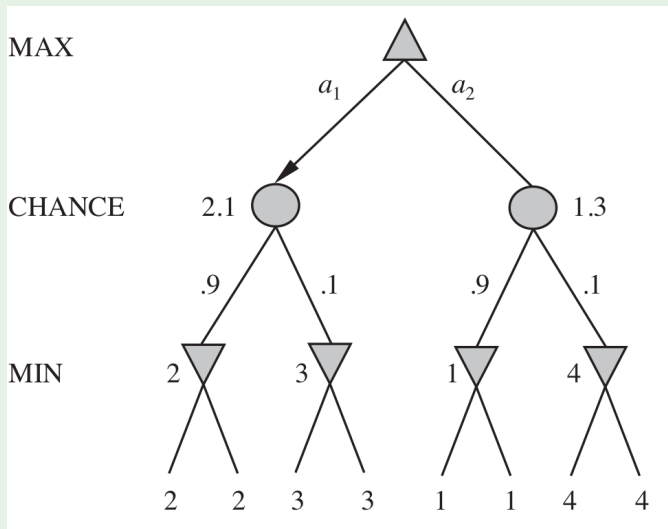
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Simple Example with Coin-Flipping



Example (Non-uniform Probabilities)



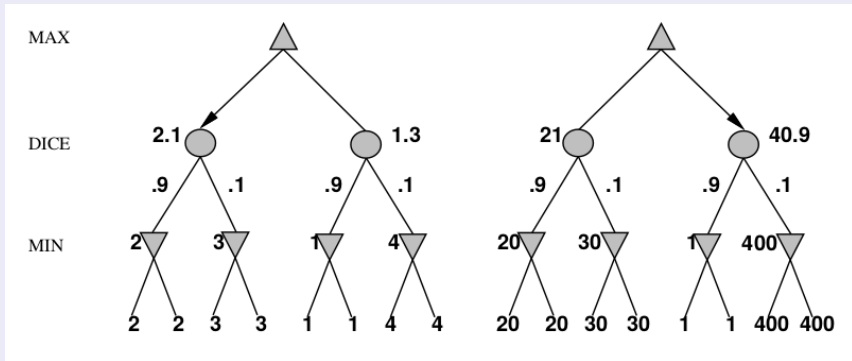
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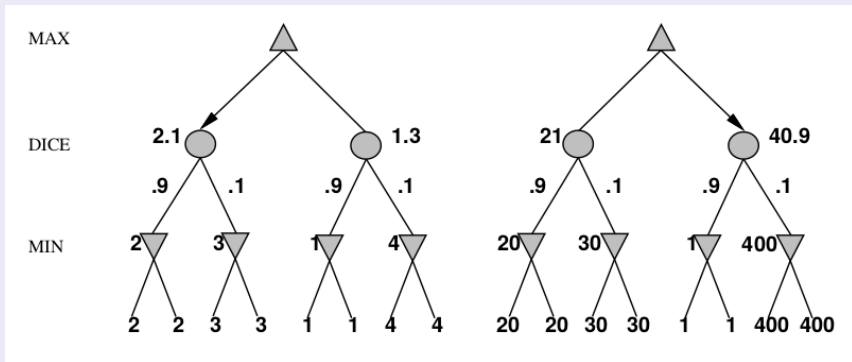
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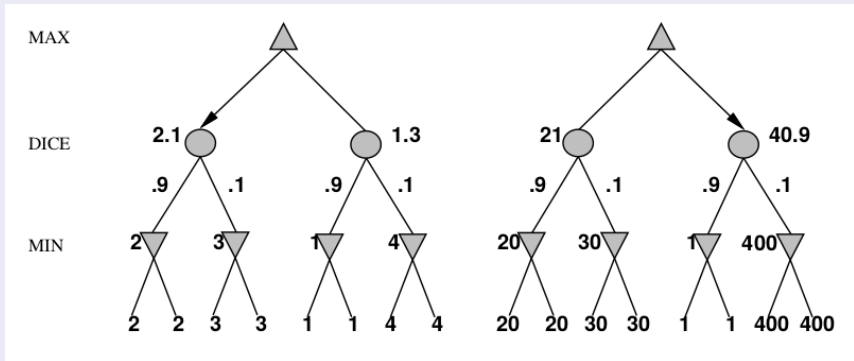
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- Dice rolls increase b : 21 possible rolls with 2 dice
⇒ $O(b^m \cdot n^m)$, n being the number of distinct roll
 - Ex: Backgammon has ≈ 20 moves
⇒ depth 4: $20 \cdot (21 \times 20)^3 \approx 10^9$ (!)
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 - Ex: TD-GGAMMON uses depth-2 search + very-good *Eval()*
 - *Eval()* “learned” by running million training games
 - competitive with world champions

Stochastic Games in Practice

- Dice rolls increase b : 21 possible rolls with 2 dice
 - ⇒ $O(b^m \cdot n^m)$, n being the number of distinct roll
 - Ex: Backgammon has ≈ 20 moves
 - ⇒ depth 4: $20 \cdot (21 \times 20)^3 \approx 10^9$ (!)
 - Alpha-beta pruning much less effective than with deterministic games
- ⇒ Unrealistic to consider high depths in most stochastic games
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