

Fundamentals of Artificial Intelligence

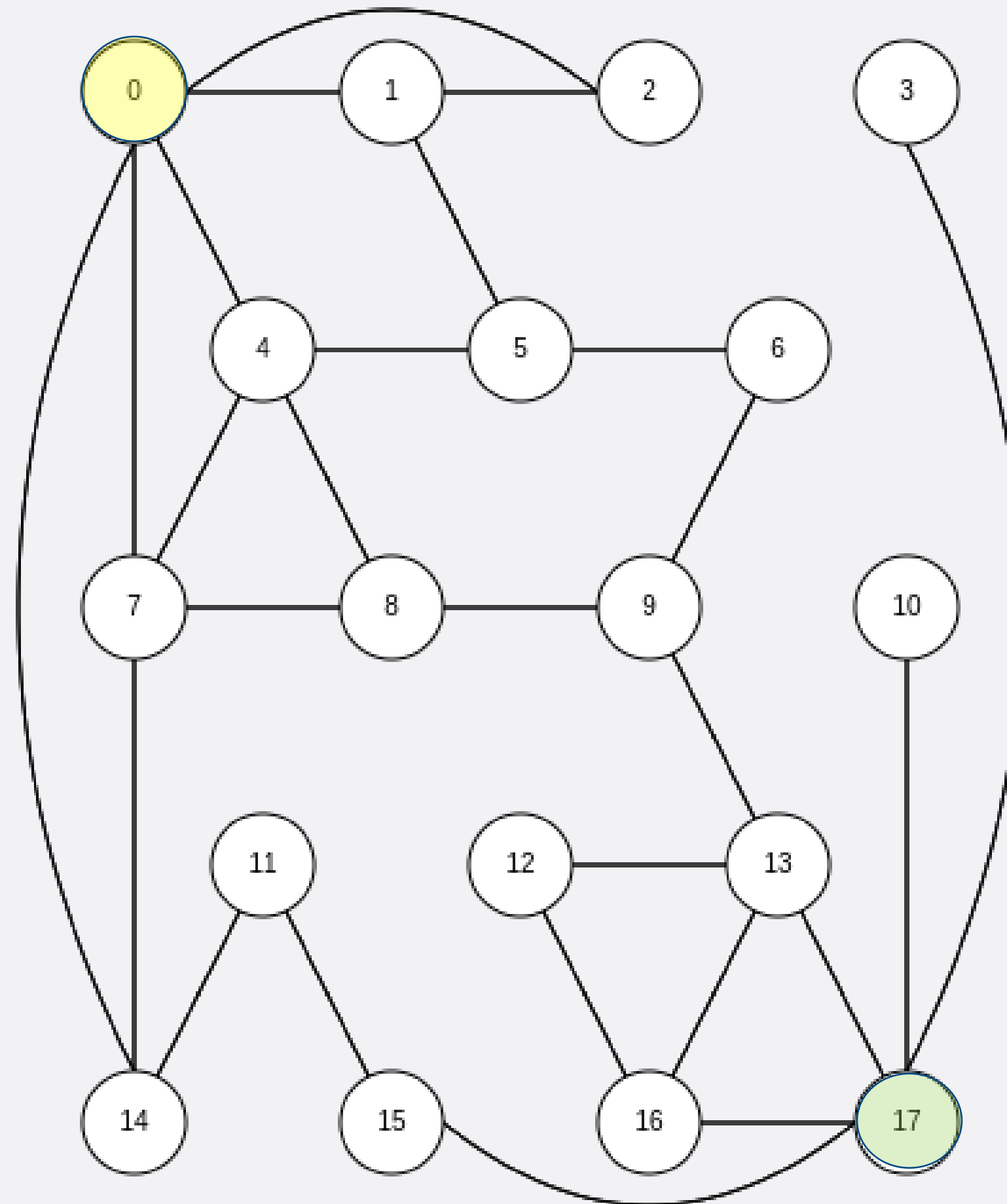
Laboratory

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Department of Information Engineering and Computer Science
Academic Year 2020/2021

Exercise 3.10

- Apply both the **iterative deepening depth-first search** and the **bidirectional search** for reaching the goal (N-17) from the start (N-0)



Exercise 3.10 - Solution

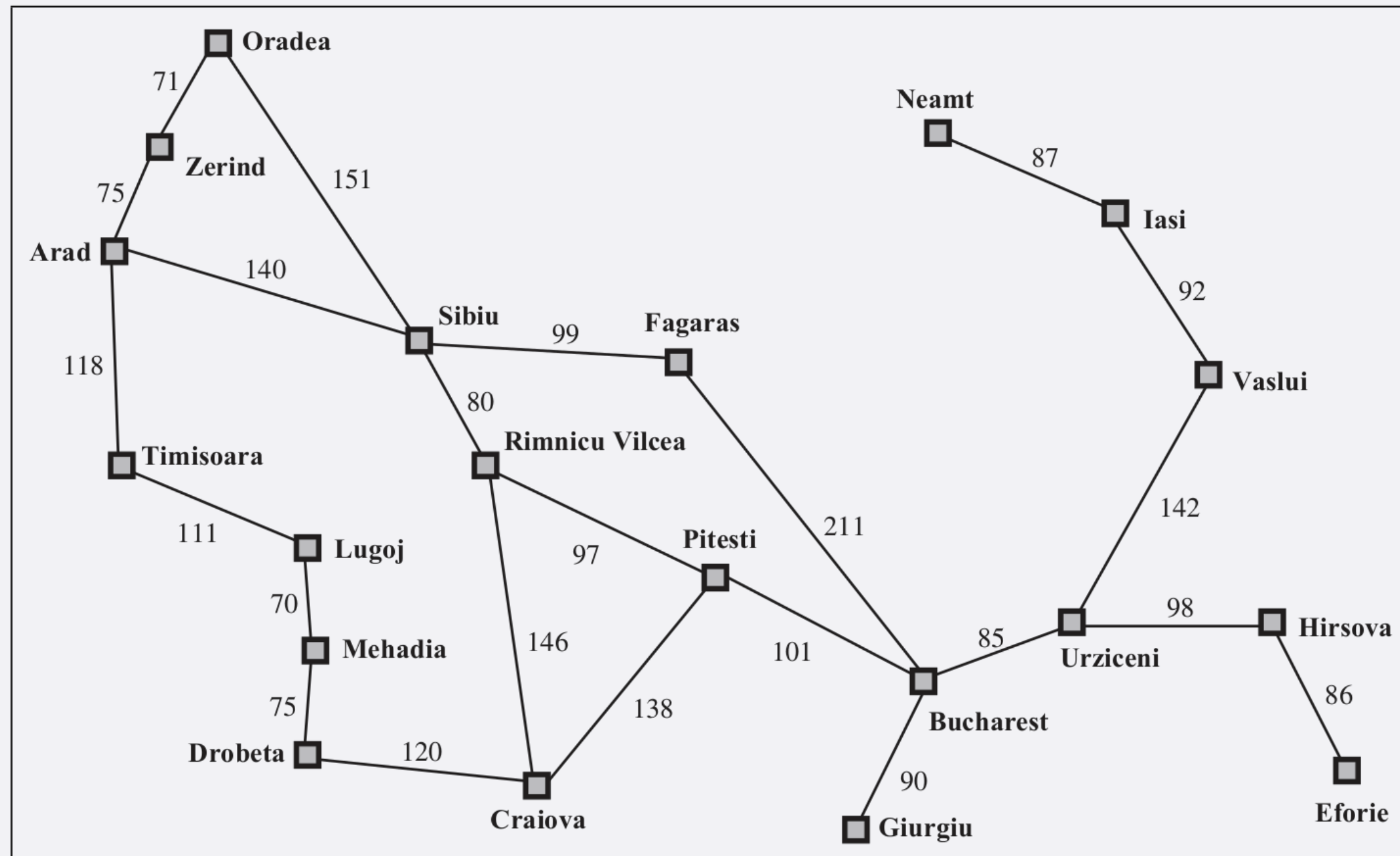
- In order to avoid misunderstanding and to do not create confusion, we apply the algorithm as it is explained in the book without considering possible variants.
- **Iterative deepening**
 - d0 = {0}
 - d1 = {0,1,2,4,7,14}
 - d2 = {0,1,2,4,7,14,5,8,11}
 - d3 = {0,1,2,4,7,14,5,8,11,6,9,15}
 - d4 = {0,1,2,4,7,14,5,8,11,6,9,15,13,17}

Exercise 3.10 - Solution

- In order to avoid misunderstanding and to do not create confusion, we apply the algorithm as it is explained in the book without considering possible variants.
- **Bidirectional search (by applying breadth-first)**
 - Step0 = {0} {17}
 - Step1 = {0,1,2,4,7,14} {17,3,10,13,15,16}
 - Step2 = {0,1,2,4,7,14,5,8,11} {17, 3,10,13,15,16,9,12,11}
- **Bidirectional search (by applying breadth-first)**
 - Step0 = {0} {17}
 - Step1 = {0,1} {17,3}
 - Step2 = {0,1,5} {17,3,10}
 - Step3 = {0,1,5,6} {17,3,10,13}
 - Step4 = {0,1,5,6,9} {17,3,10,13,9}

Exercise 3.11

- Apply the **greedy best-first search** strategy for finding the route from Lugoj to Bucharest.



Arad	366	Mehadia	241
Bucharest	0	Neamt	234
Craiova	160	Oradea	380
Drobeta	242	Pitesti	100
Eforie	161	Rimnicu Vilcea	193
Fagaras	176	Sibiu	253
Giurgiu	77	Timisoara	329
Hirsova	151	Urziceni	80
Iasi	226	Vaslui	199
Lugoj	244	Zerind	374

Exercise 3.11 - Solution

- Apply the **greedy best-first search** strategy for finding the route from Lugoj to Bucharest.
- Initial state: Lugoj(244)
 - Step1, expanding Lugoj: Mehadia(241), Timisoara(329)
 - Step2, expanding Mehadia: Lugoj(244), Drobeta(242)
 - Step3, expanding Drobeta: Mehadia(241), Craiova(160)
 - Step4, expanding Craiova: Drobeta(242), Rimnicu Vilcea(193), Pitesti(100)
 - Step4, expanding Pitesti: Craiova(160), Rimnicu Vilcea(193), **Bucharest(0)**

Exercise 3.12

- A* algorithm

```
-----  
WHILE (QUEUE not empty && first path not reach goal) DO  
  Remove first path from QUEUE  
  Create paths to all children  
  Reject paths with loops  
  Add paths and sort QUEUE (by  $f = \text{cost} + \text{heuristic}$ )  
  IF QUEUE contains paths: P, Q  
    AND P ends in node  $N_i$  && Q contains node  $N_i$   
    AND  $\text{cost}(\mathbf{P}) \geq \text{cost}(\mathbf{Q})$   
  THEN remove P  
  
IF goal reached THEN success ELSE failure  
-----
```

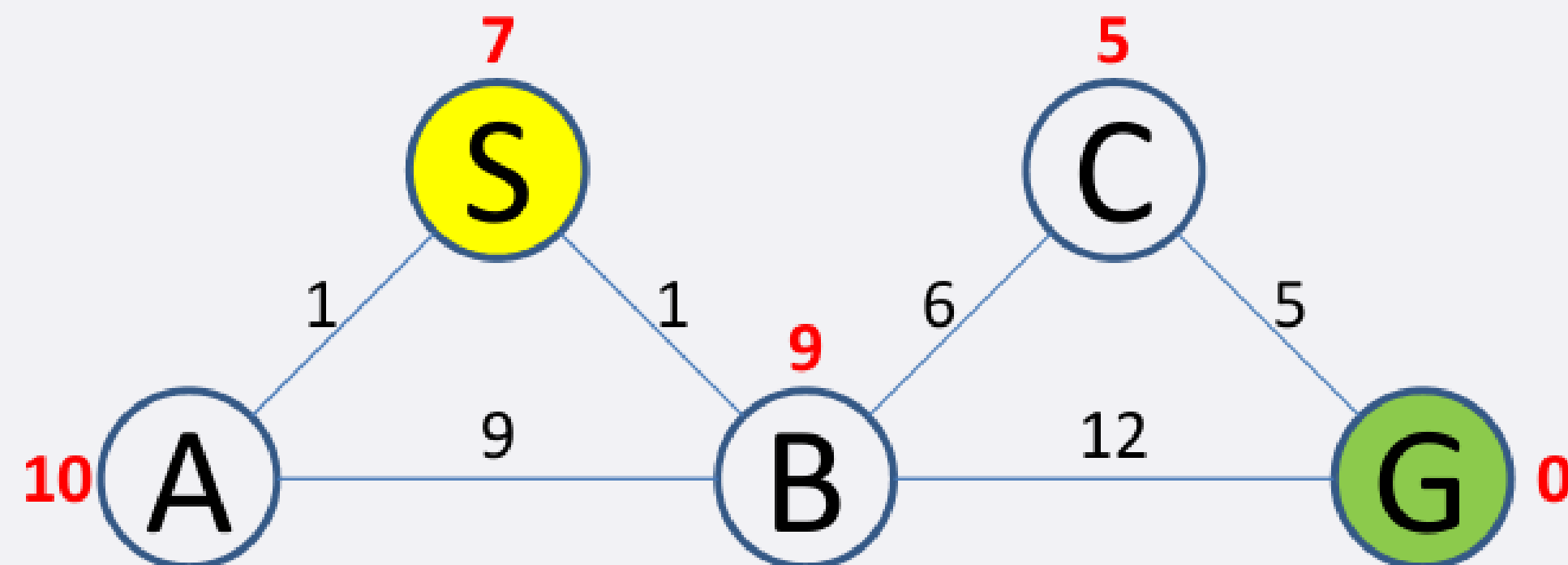
Exercise 3.12



$f = \text{accumulated path cost} + \text{heuristic}$

QUEUE = path containing root

QUEUE = <S>

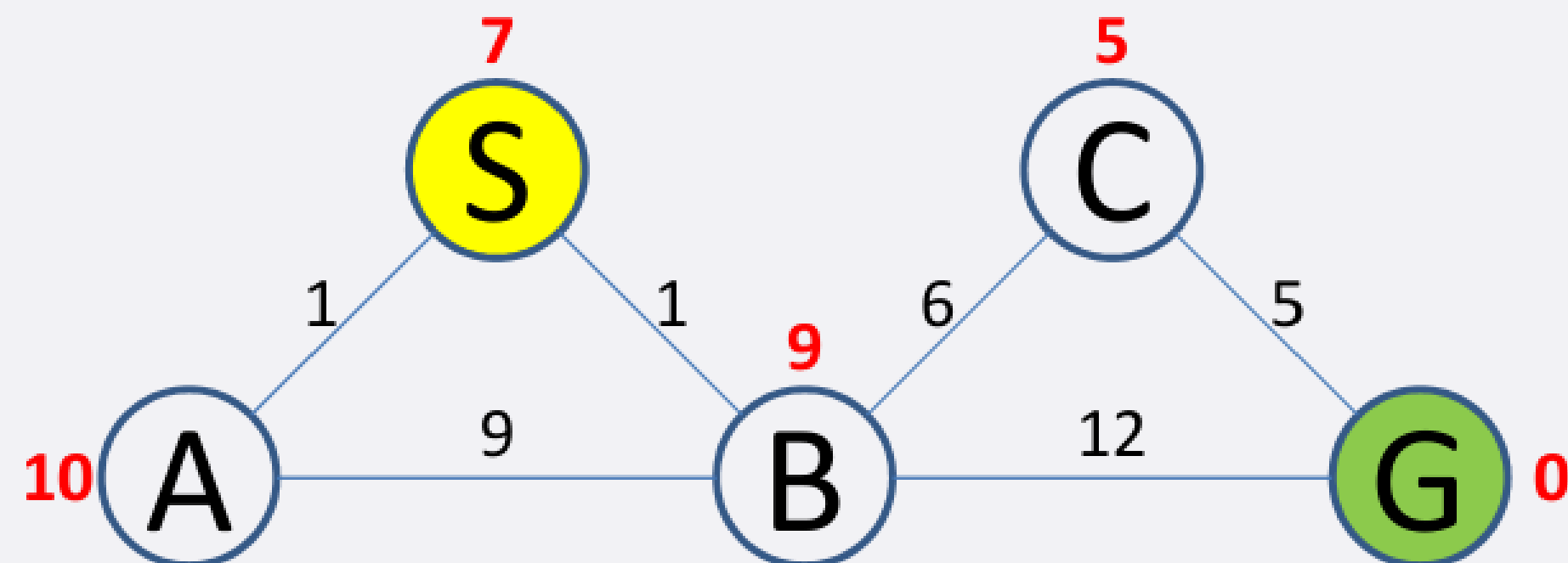
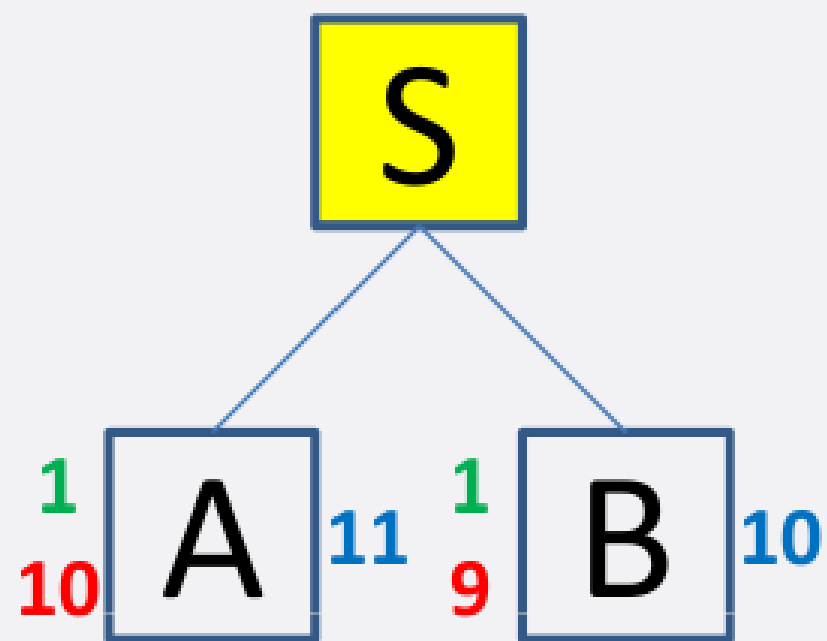


Exercise 3.12

$$f = \text{accumulated path cost} + \text{heuristic}$$

Remove first path, Create paths to all children, Reject loops and Add paths. SORT QUEUE by f

QUEUE = <SB,SA>

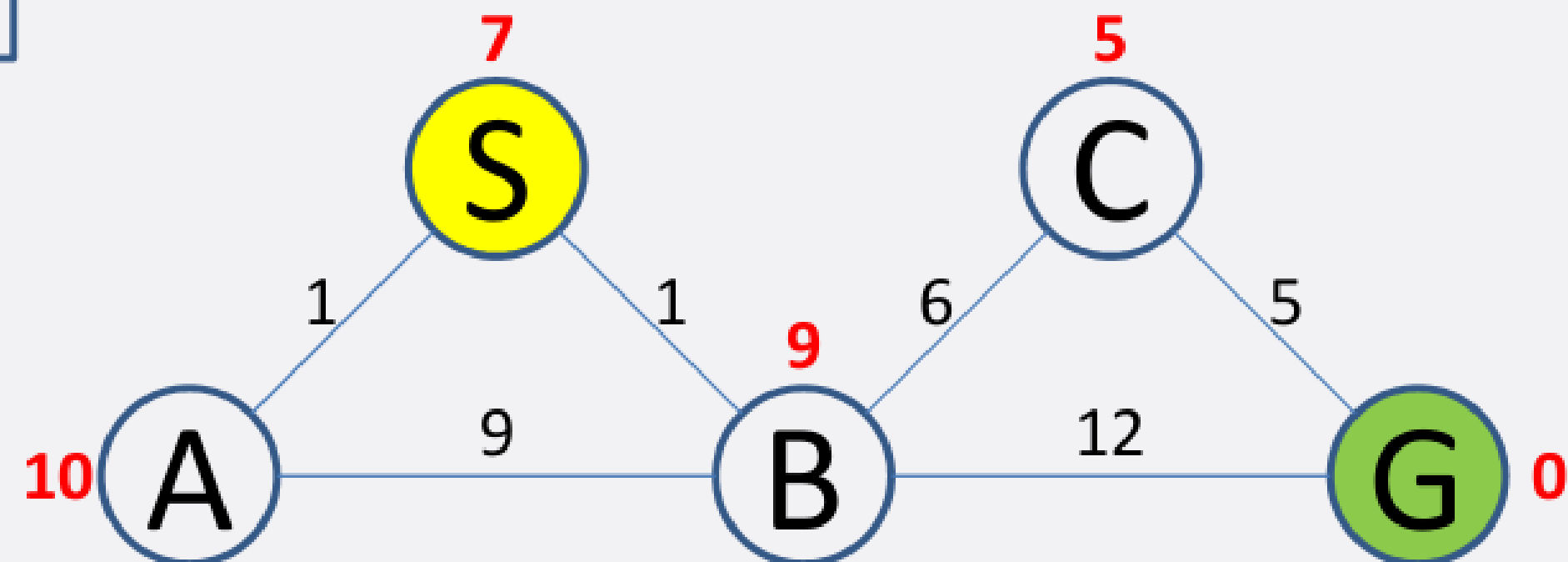
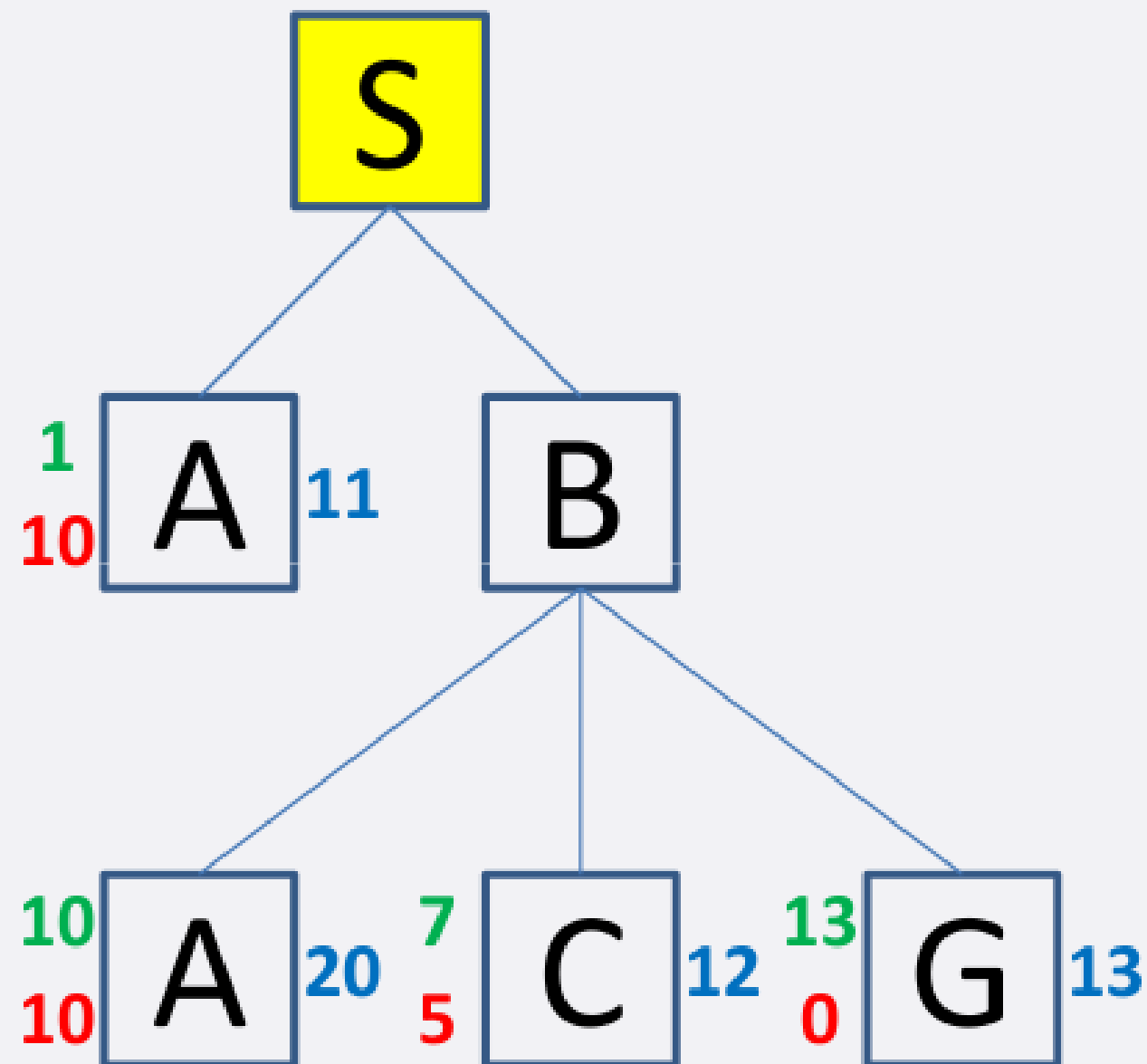


Exercise 3.12

$f = \text{accumulated path cost} + \text{heuristic}$

Remove first path, Create paths to all children, Reject loops and Add paths. SORT QUEUE by f

QUEUE = <SA,SBC,SBG,SBA>

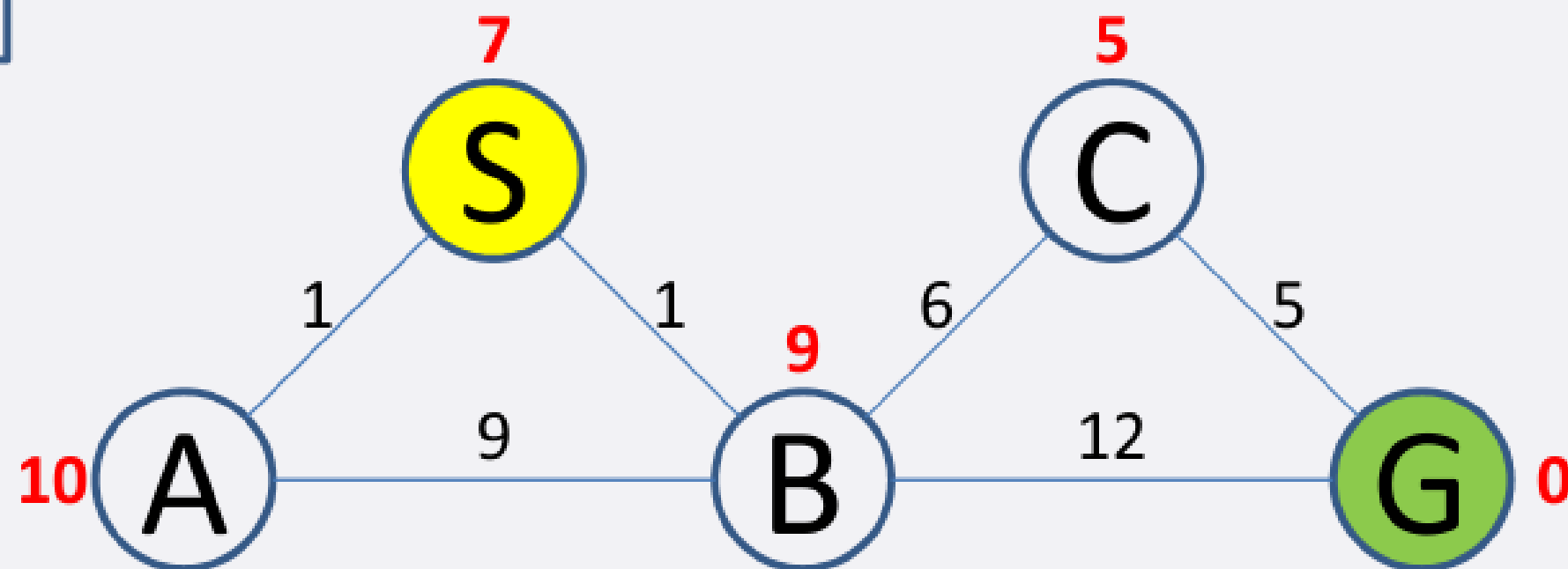
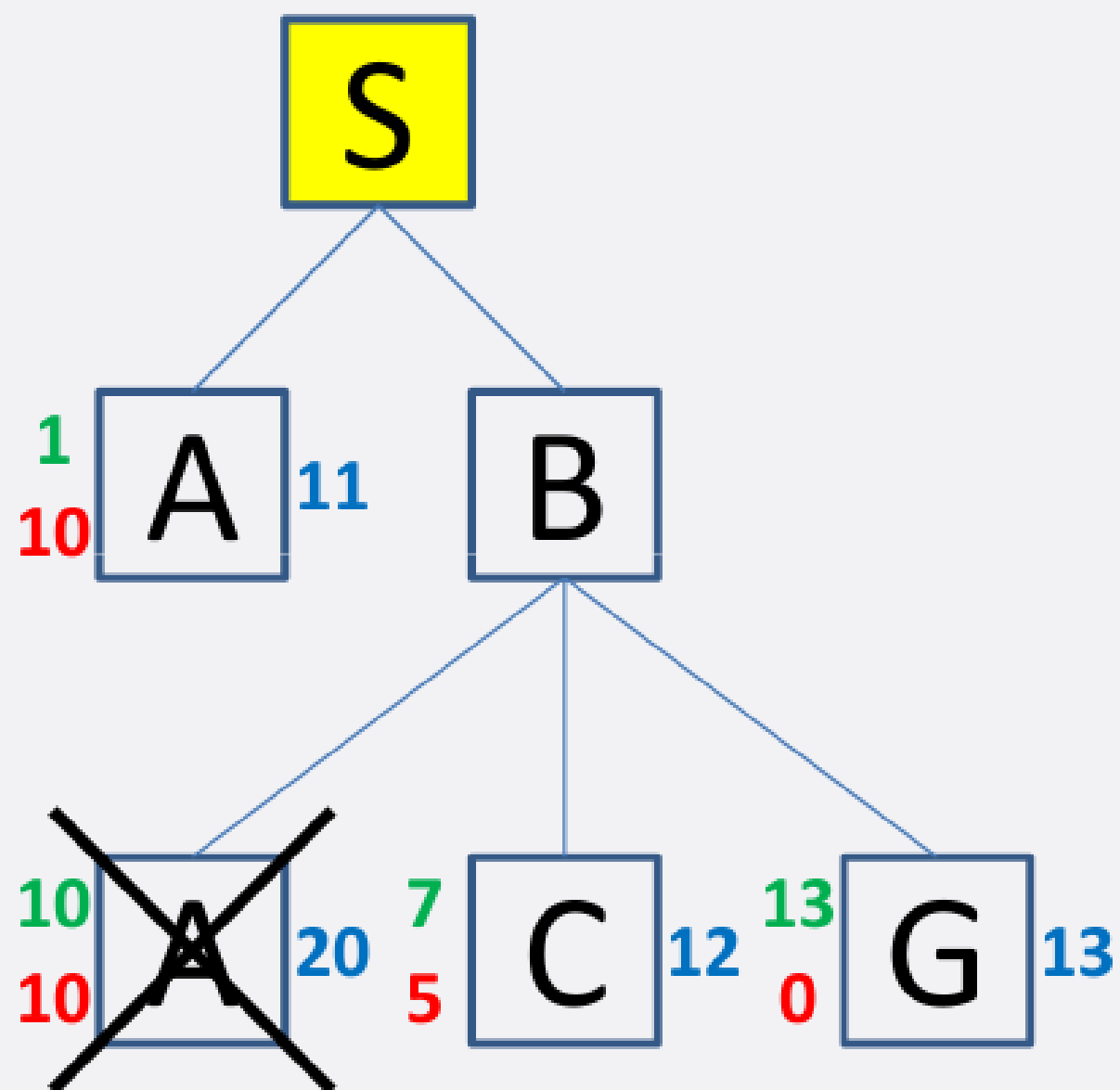


Exercise 3.12

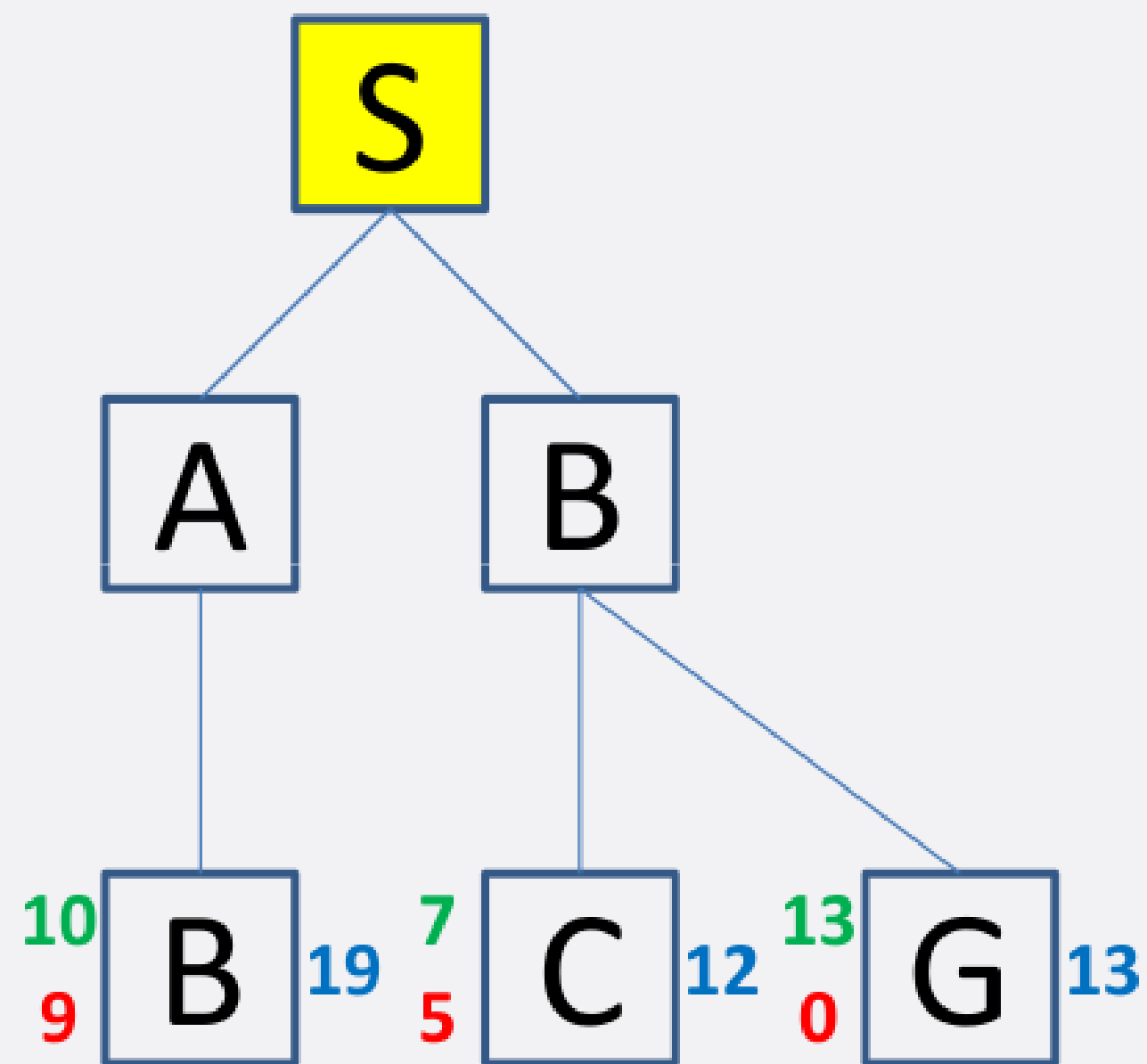
$f = \text{accumulated path cost} + \text{heuristic}$

IF QUEUE contains paths: P, Q
 AND P ends in node Ni && Q contains node Ni
 AND cost(P) ≥ cost(Q)
 THEN remove P

QUEUE = <SA,SBC,SBG,SBA>



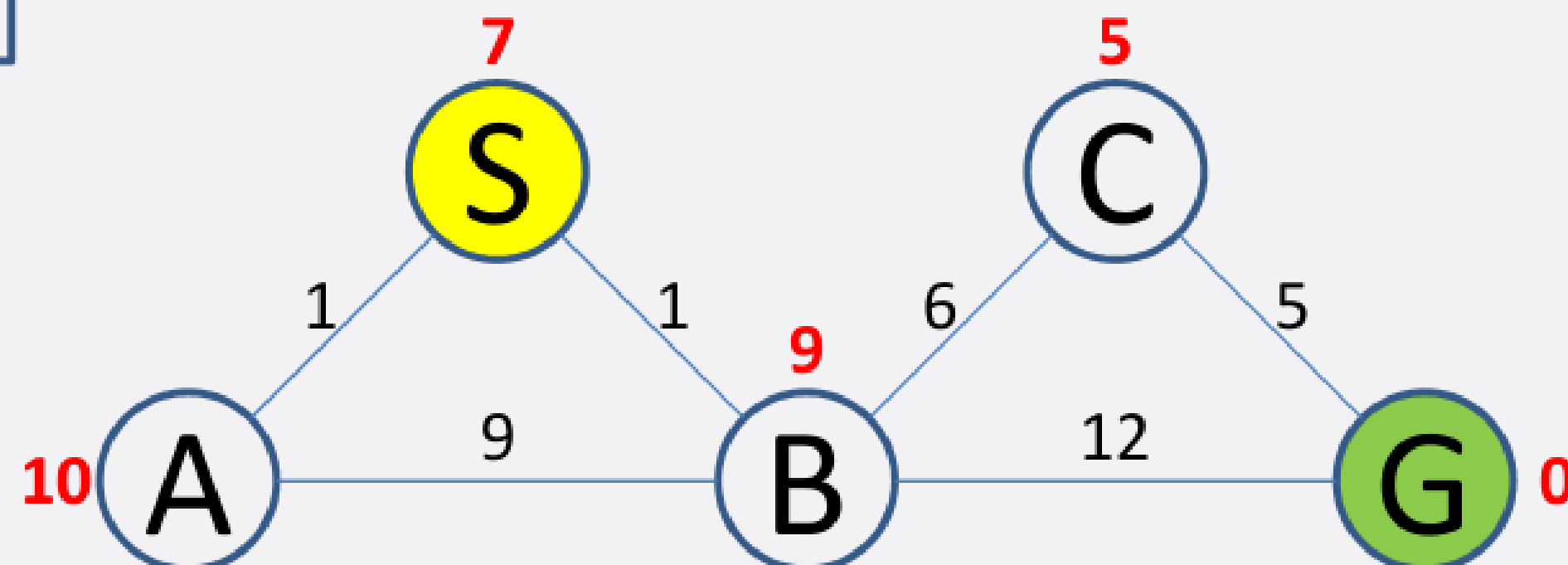
Exercise 3.12



$$f = \text{accumulated path cost} + \text{heuristic}$$

Remove first path, Create paths to all children, Reject loops and Add paths. SORT QUEUE by f

QUEUE = <SBC,SBG,SAB>

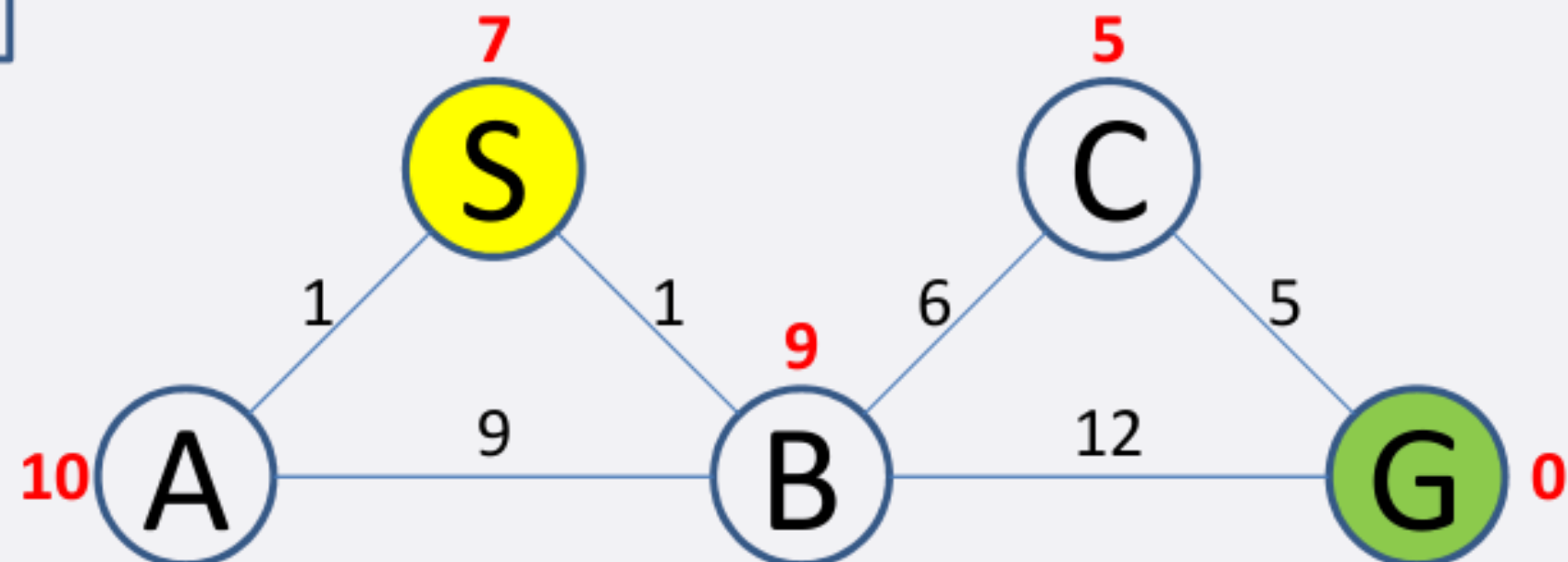
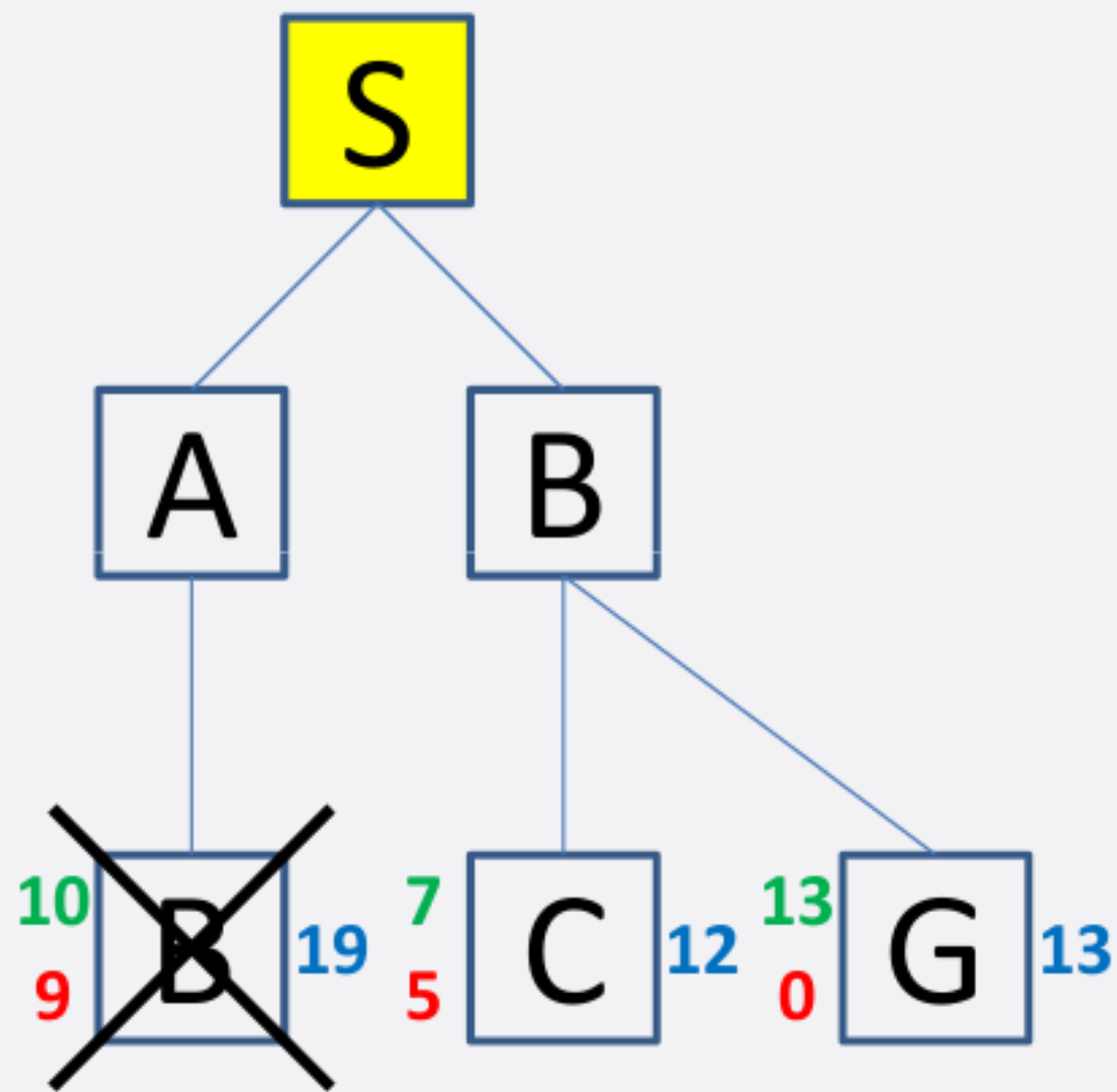


Exercise 3.12

$$f = \text{accumulated path cost} + \text{heuristic}$$

IF QUEUE contains paths: P, Q
AND P ends in node Ni && Q contains node Ni
AND $\text{cost}(P) \geq \text{cost}(Q)$
THEN remove P

QUEUE = < SBC, SBG, SAB >

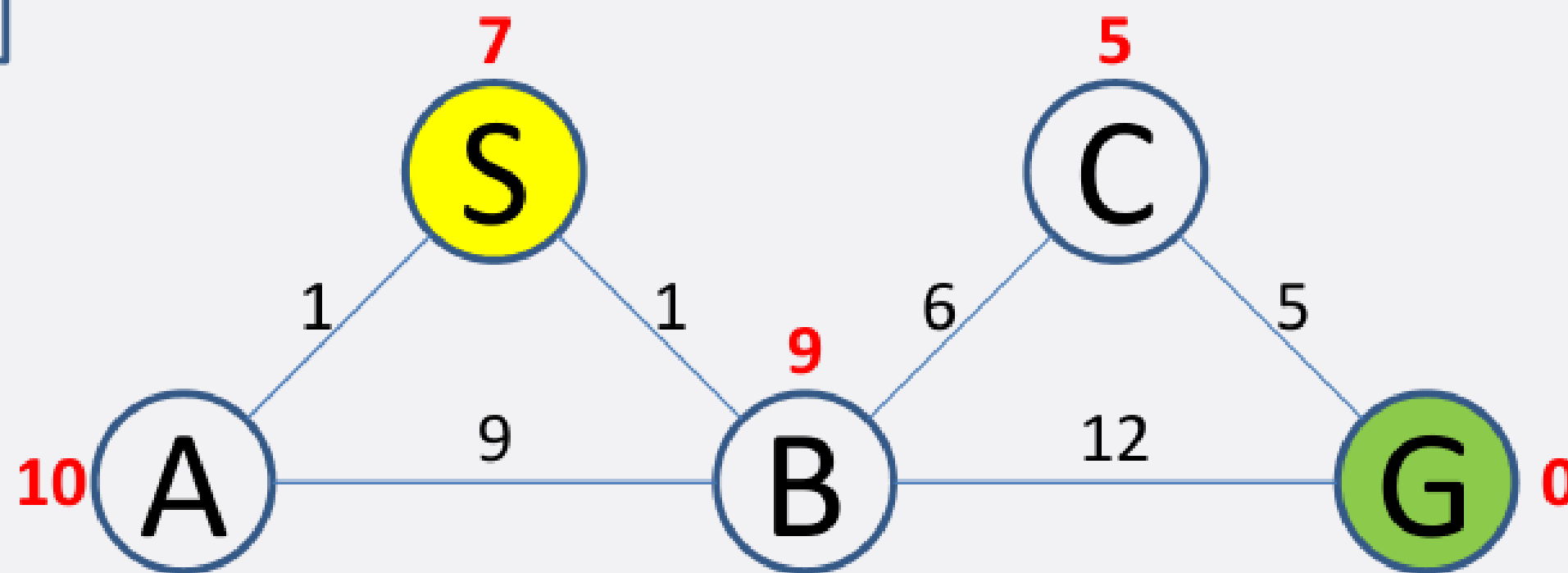
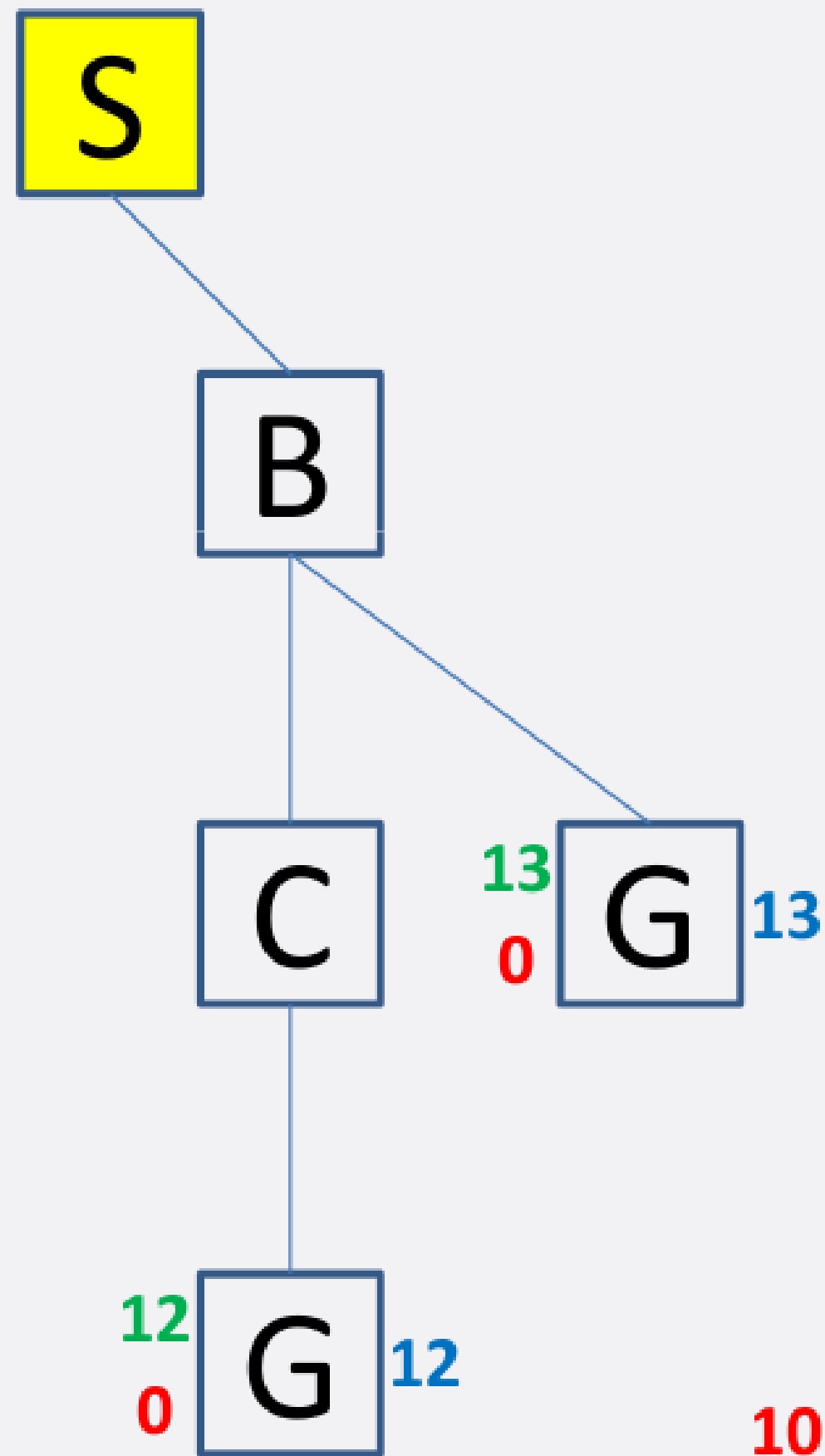


Exercise 3.12

$$f = \text{accumulated path cost} + \text{heuristic}$$

Remove first path, Create paths to all children, Reject loops and Add paths. SORT QUEUE by f

QUEUE = <SBCG,SBG>

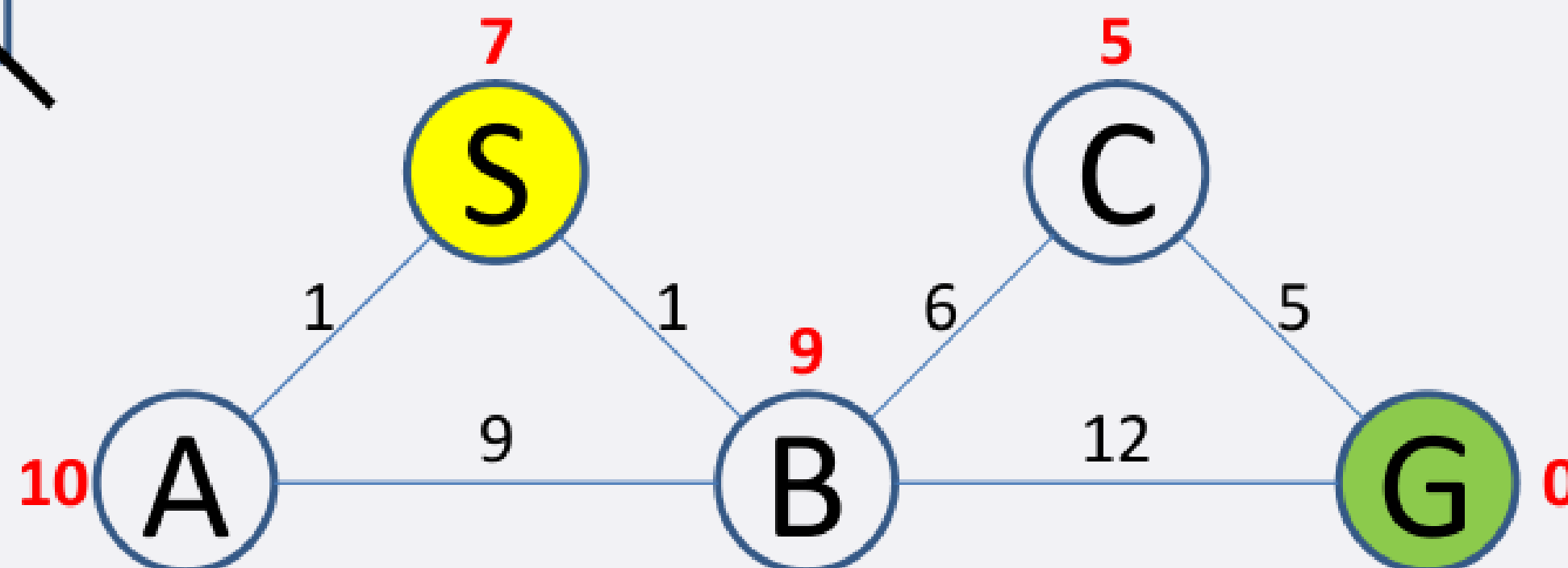
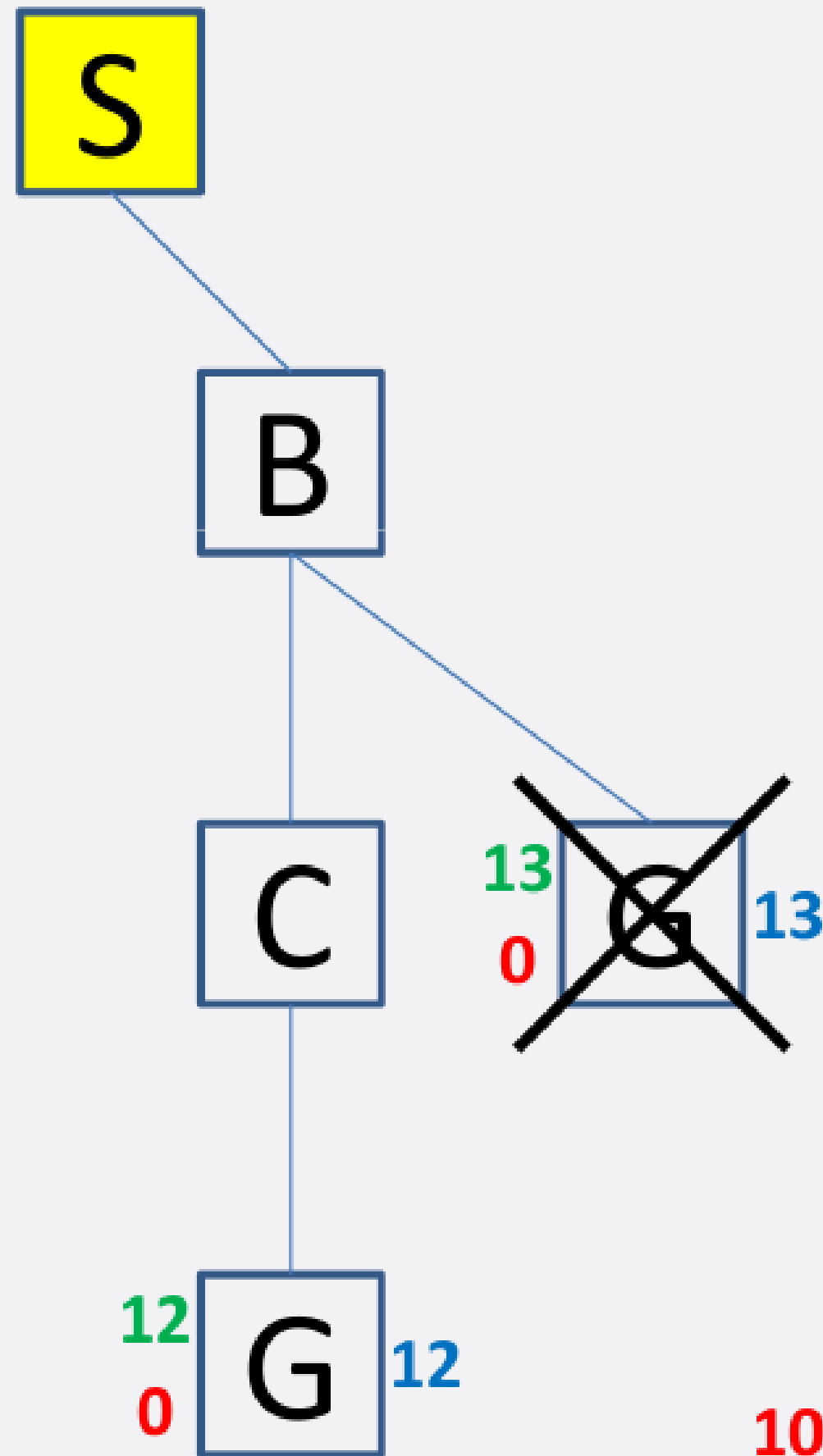


Exercise 3.12

$f = \text{accumulated path cost} + \text{heuristic}$

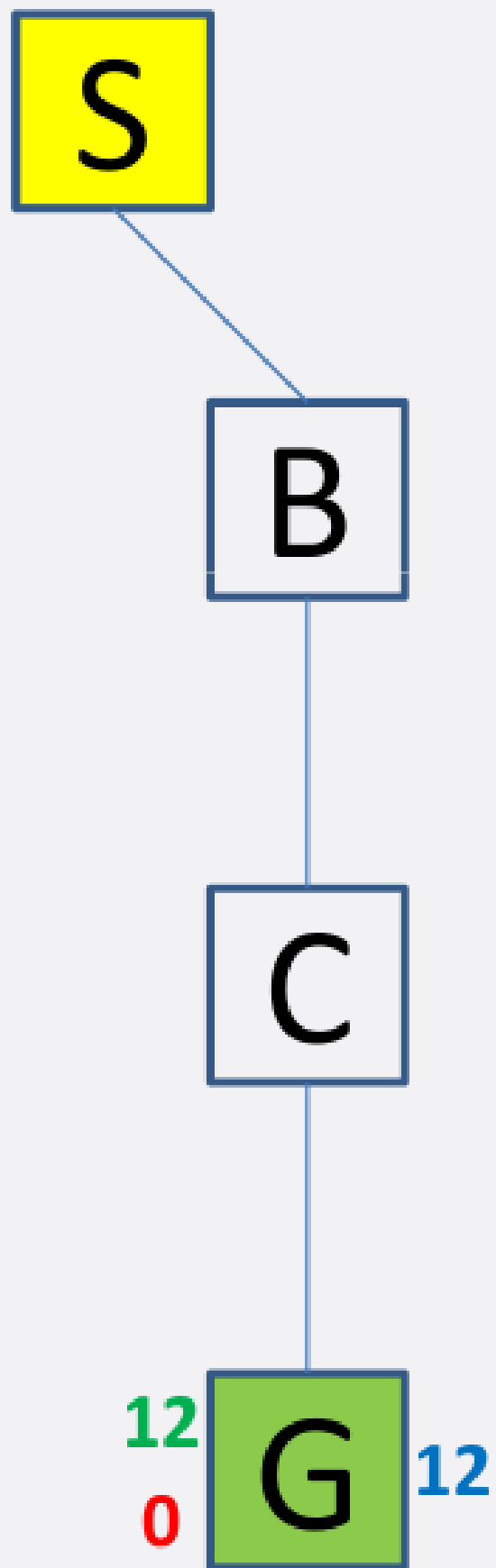
IF QUEUE contains paths: P, Q
 AND P ends in node Ni && Q contains node Ni
 AND $\text{cost}(P) \geq \text{cost}(Q)$
 THEN remove P

QUEUE = < SBCG, SBG >



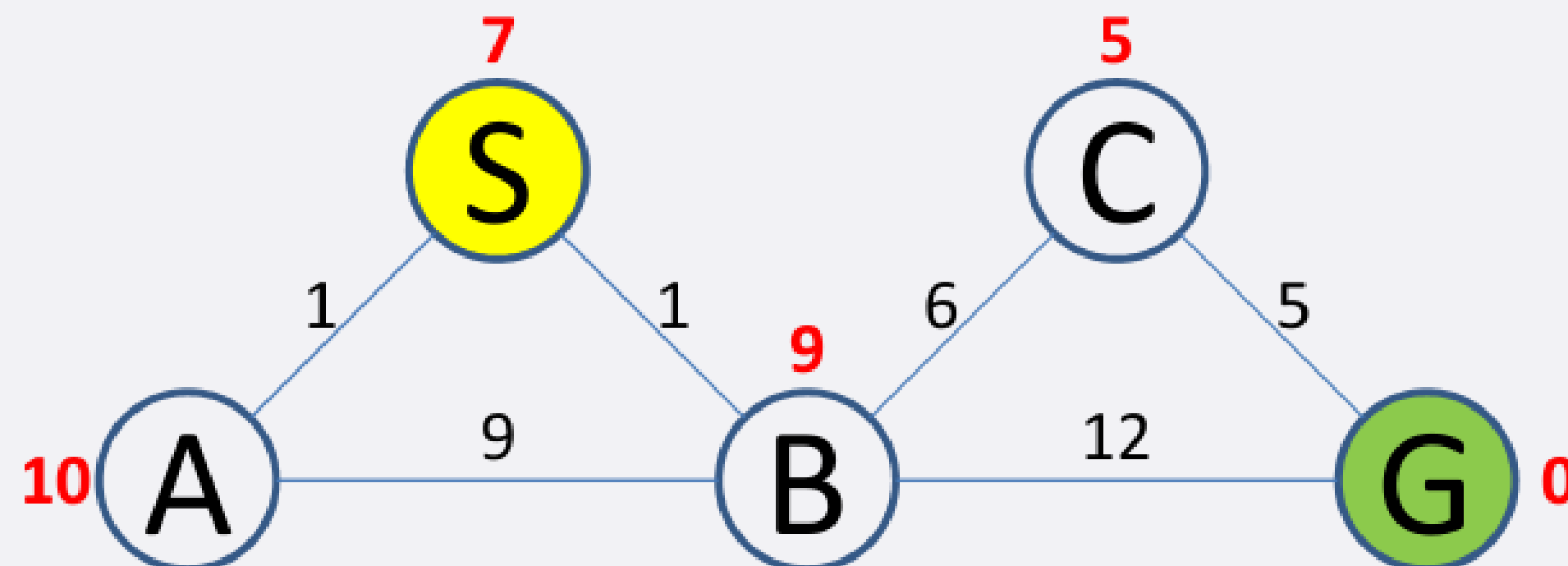
Exercise 3.12

$$f = \text{accumulated path cost} + \text{heuristic}$$



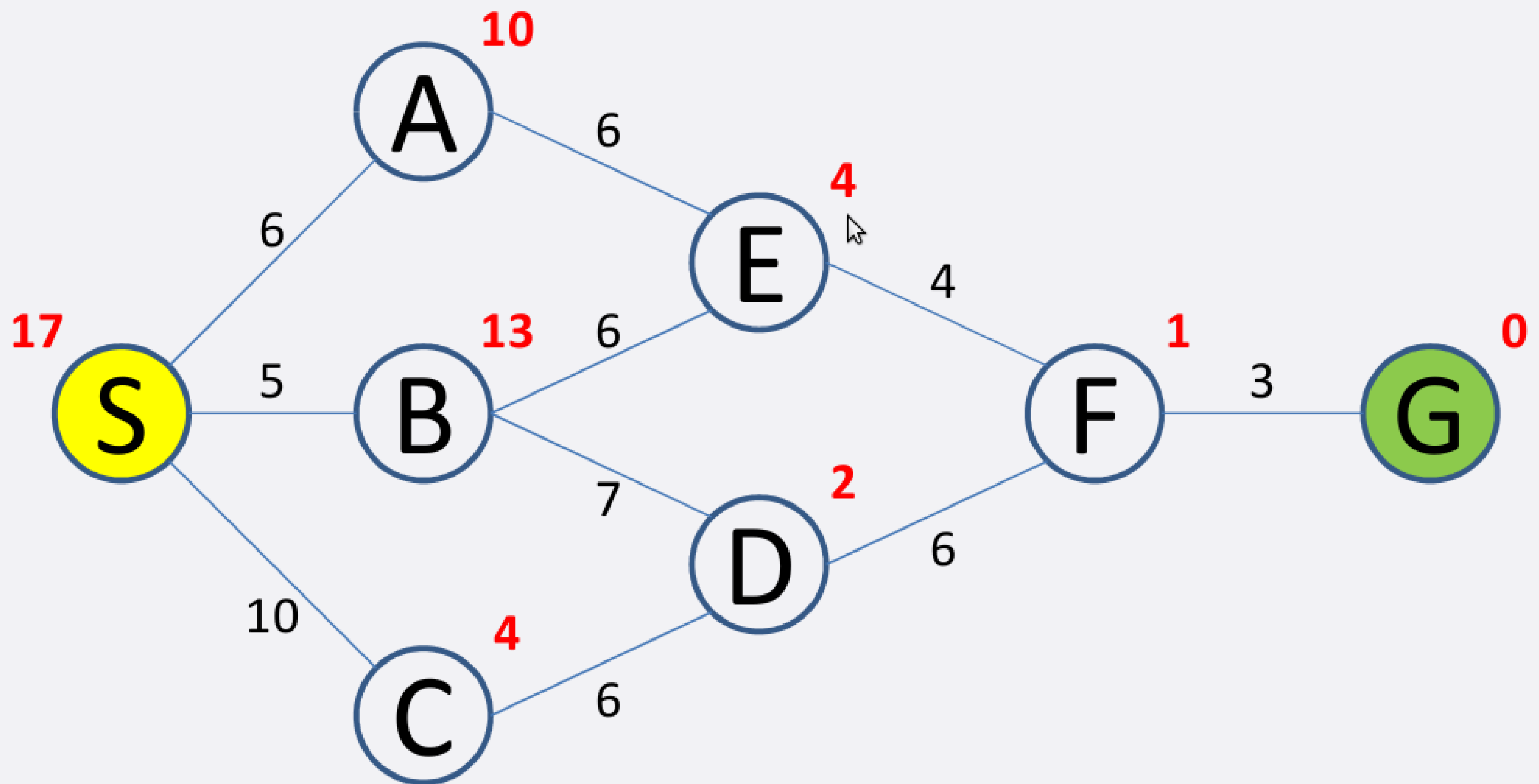
SUCCESS

QUEUE = < SBCG >



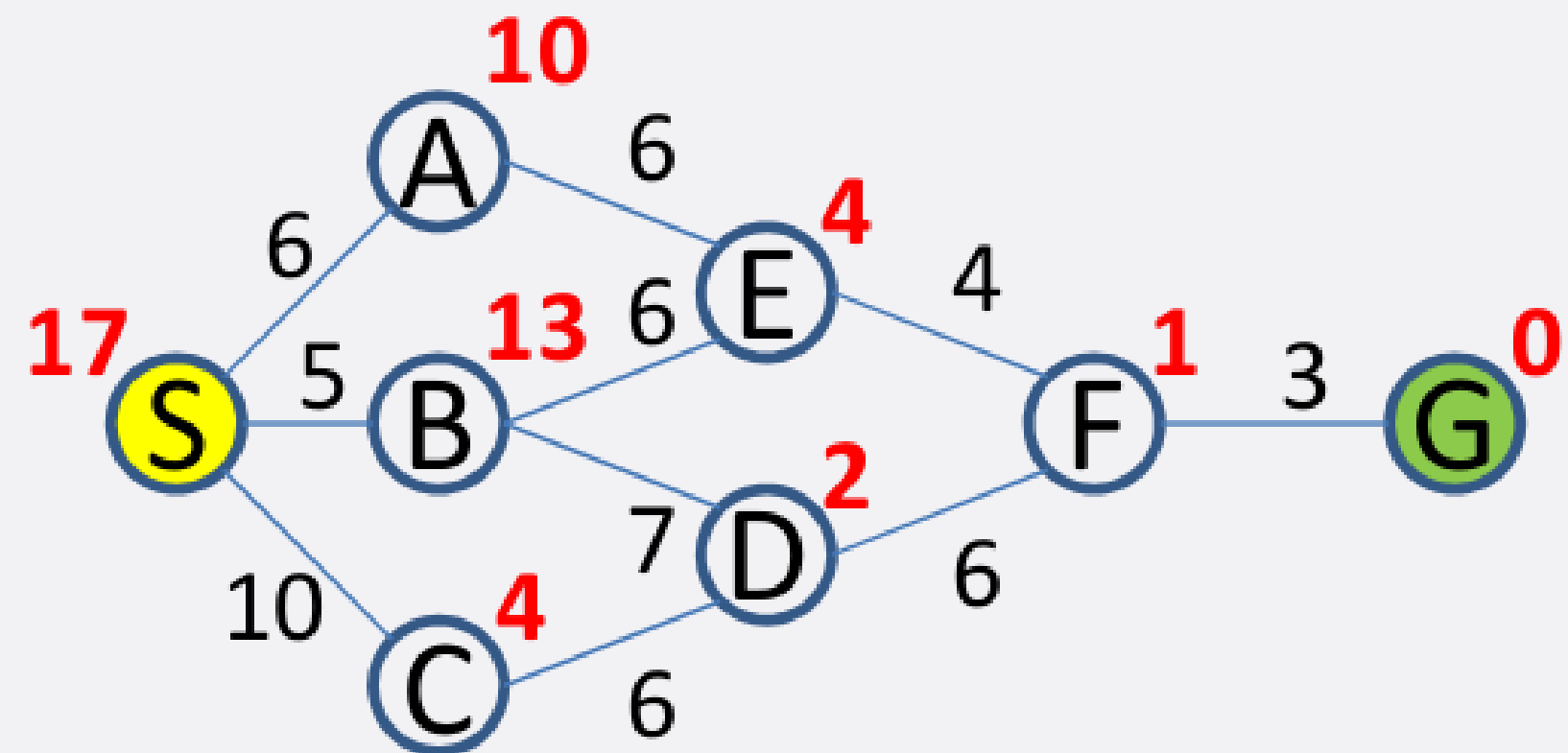
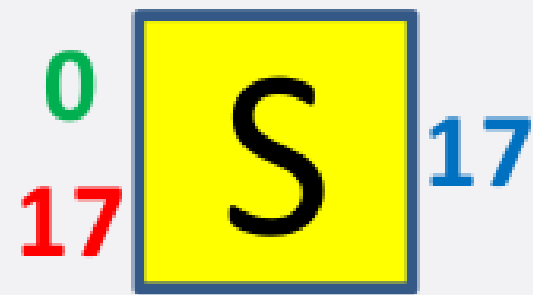
Exercise 3.13

- Perform the A* Algorithm on the following figure. Explicitly write down the queue at each step.



Exercise 3.13

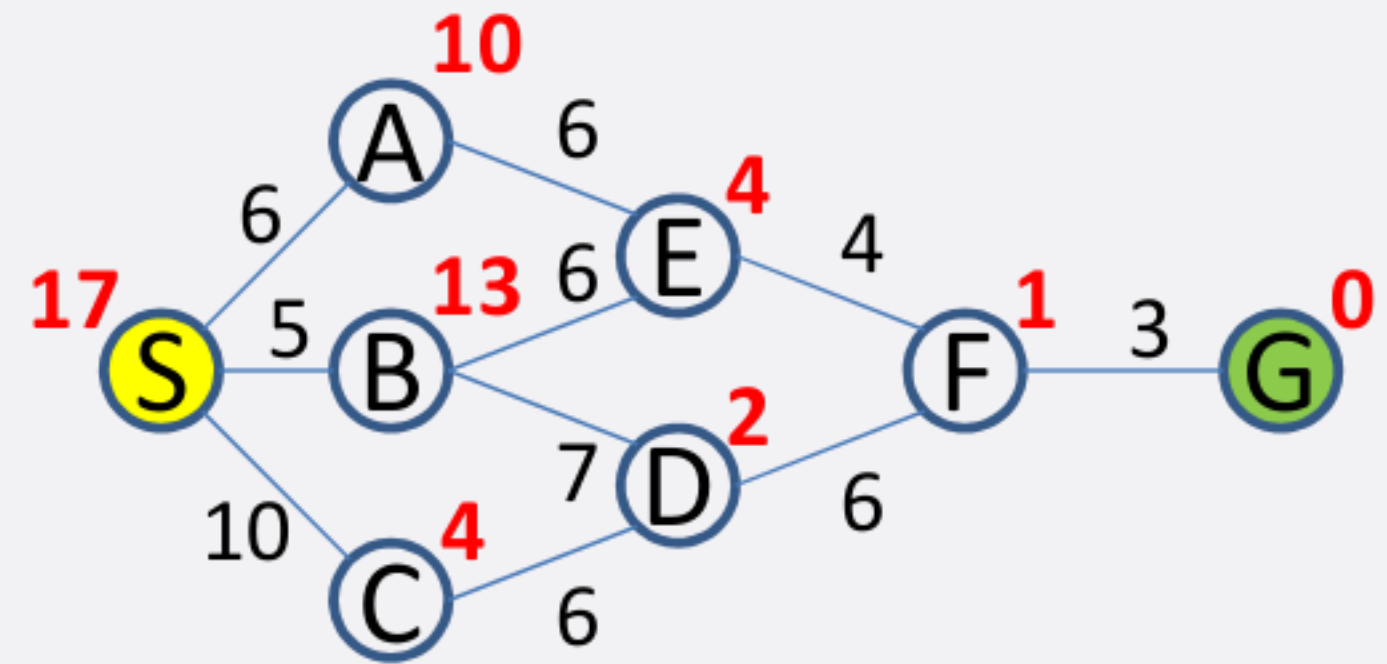
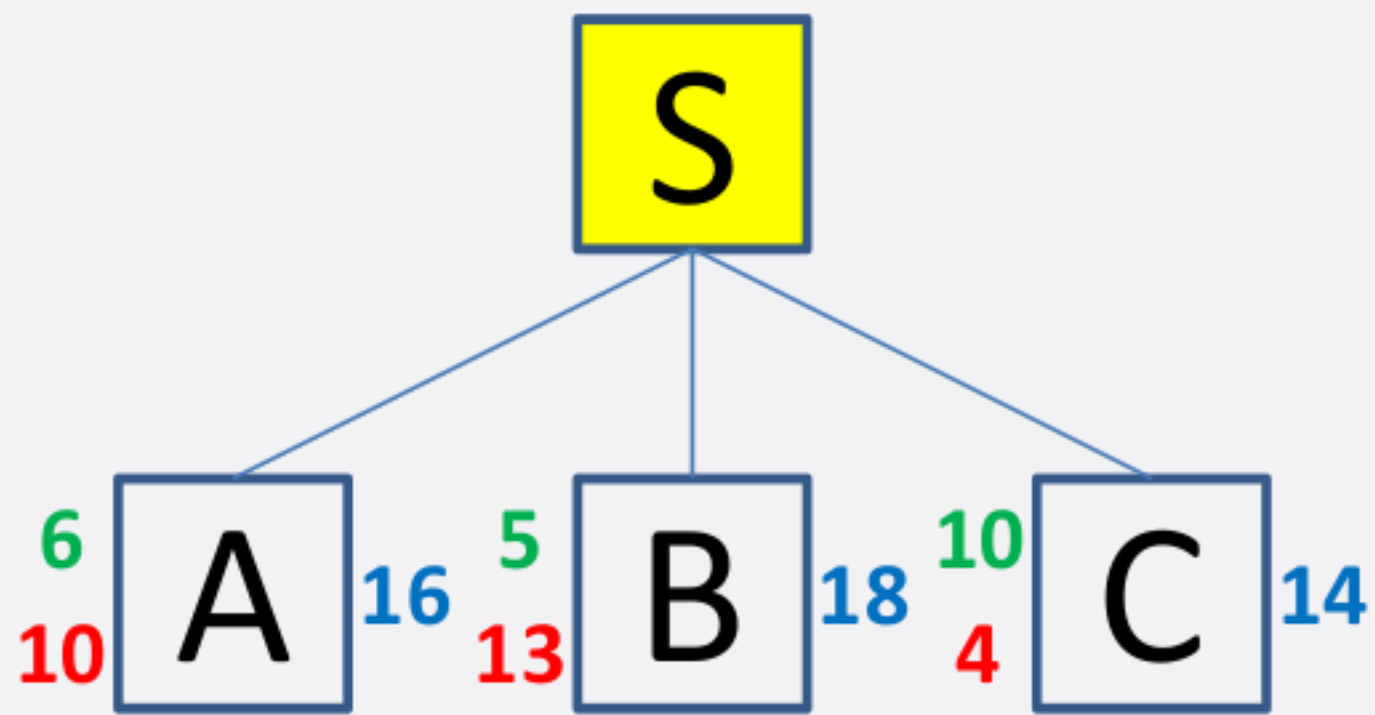
- Step 1



QUEUE:
S

Exercise 3.13

- Step 2



QUEUE:

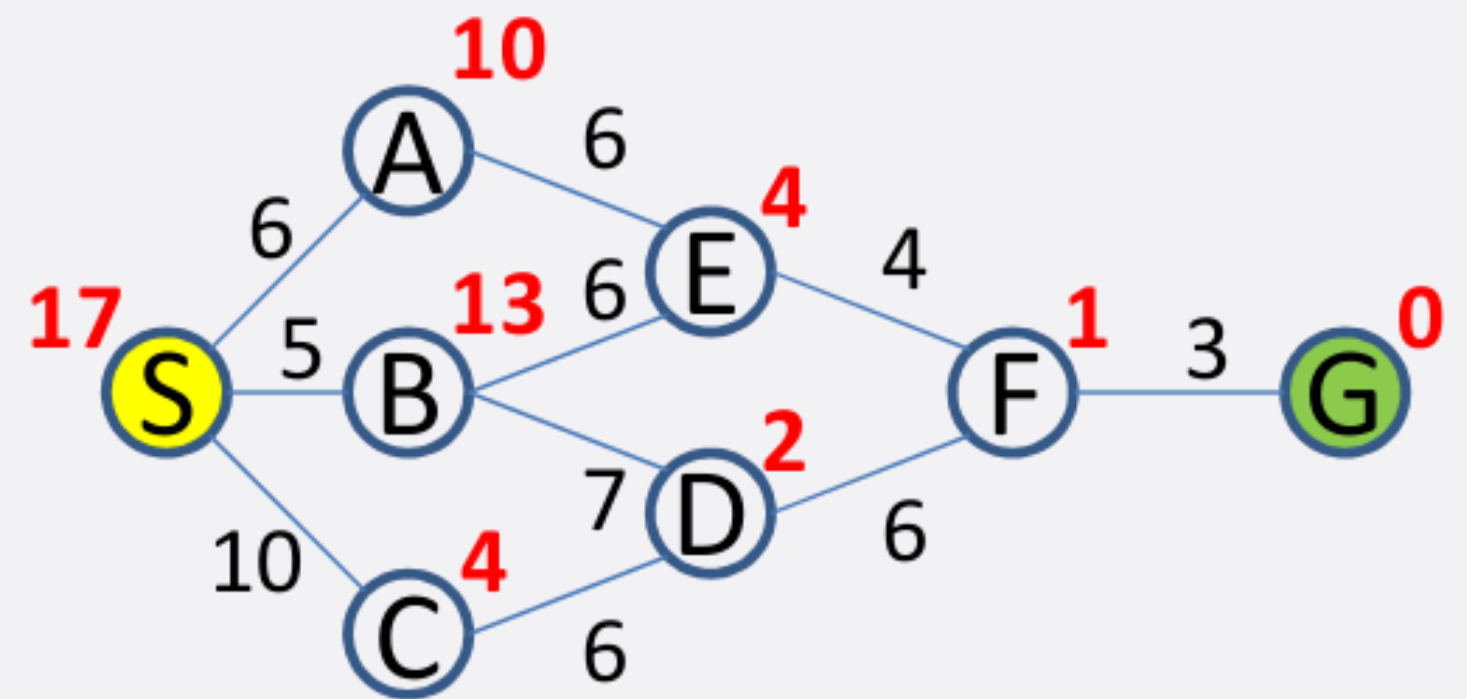
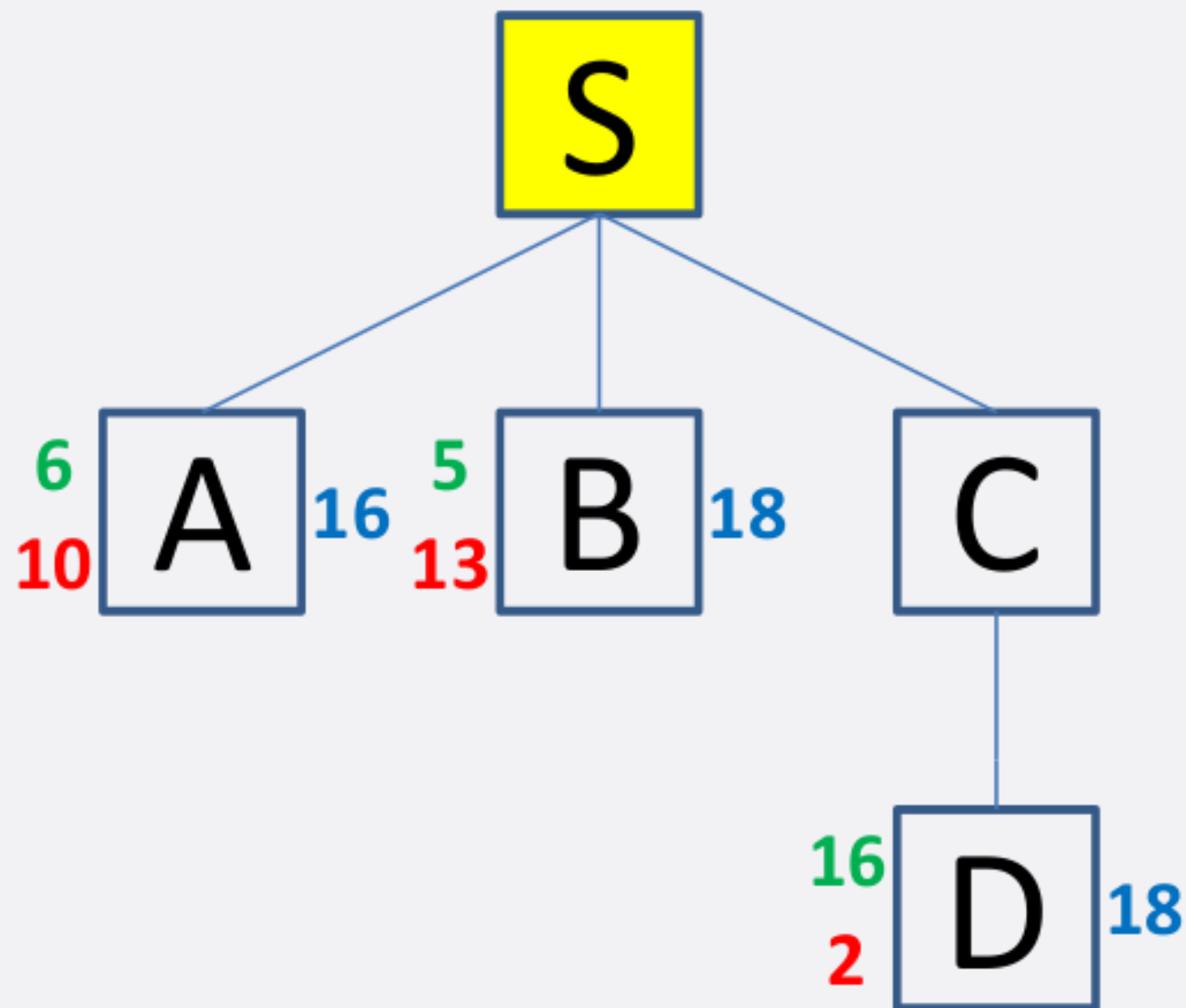
SC

SA

SB

Exercise 3.13

- Step 3



QUEUE:

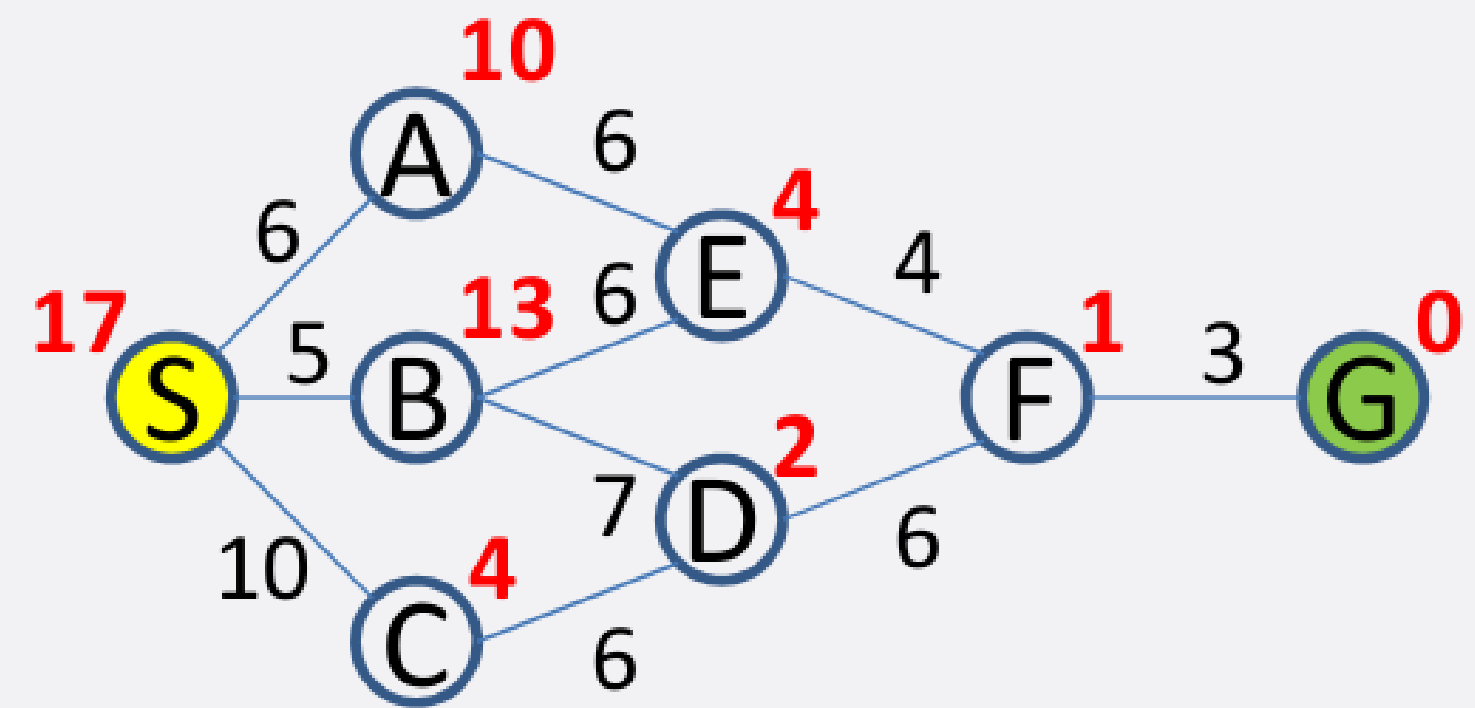
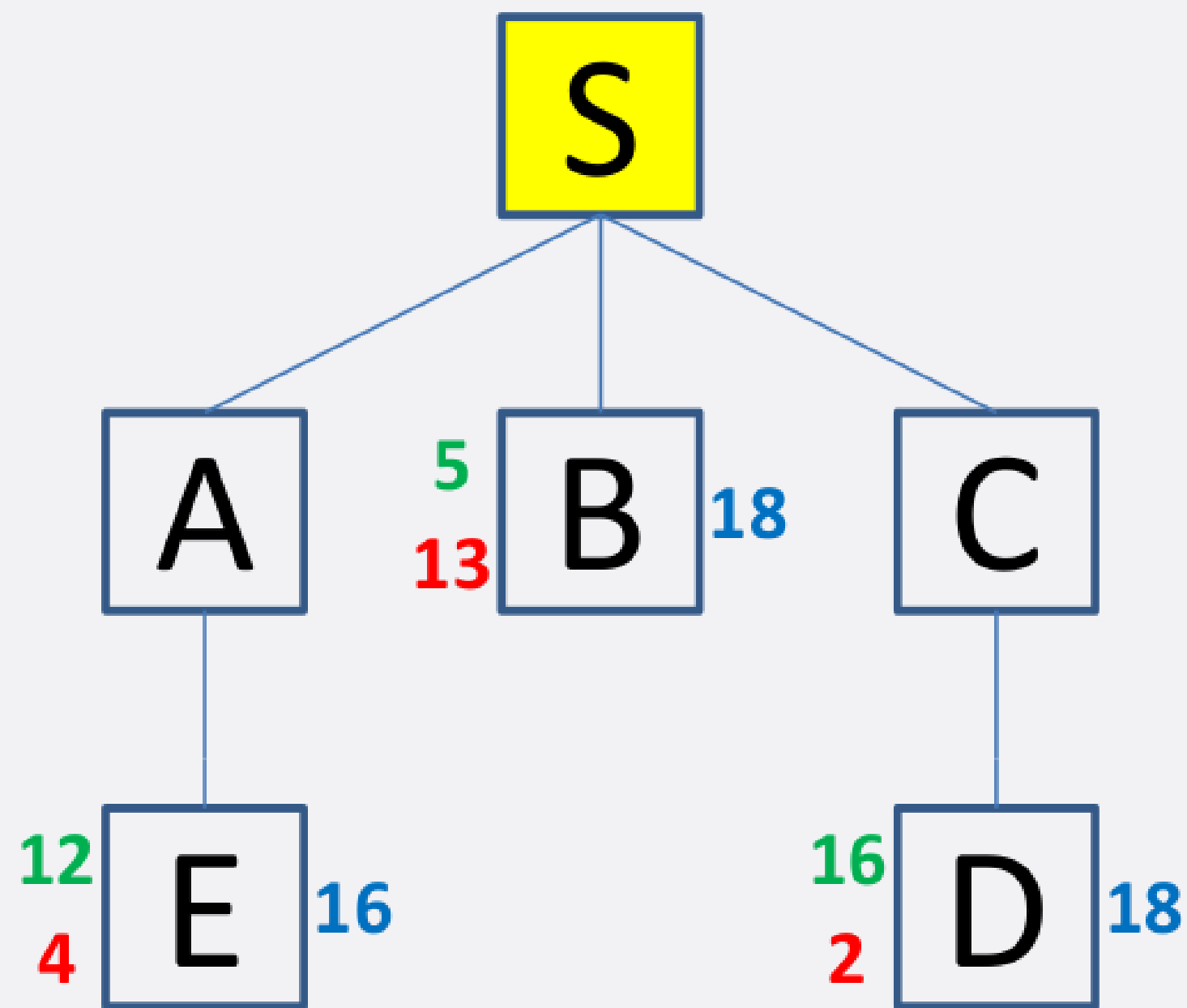
SA

SCD

SB

Exercise 3.13

- Step 4



QUEUE:

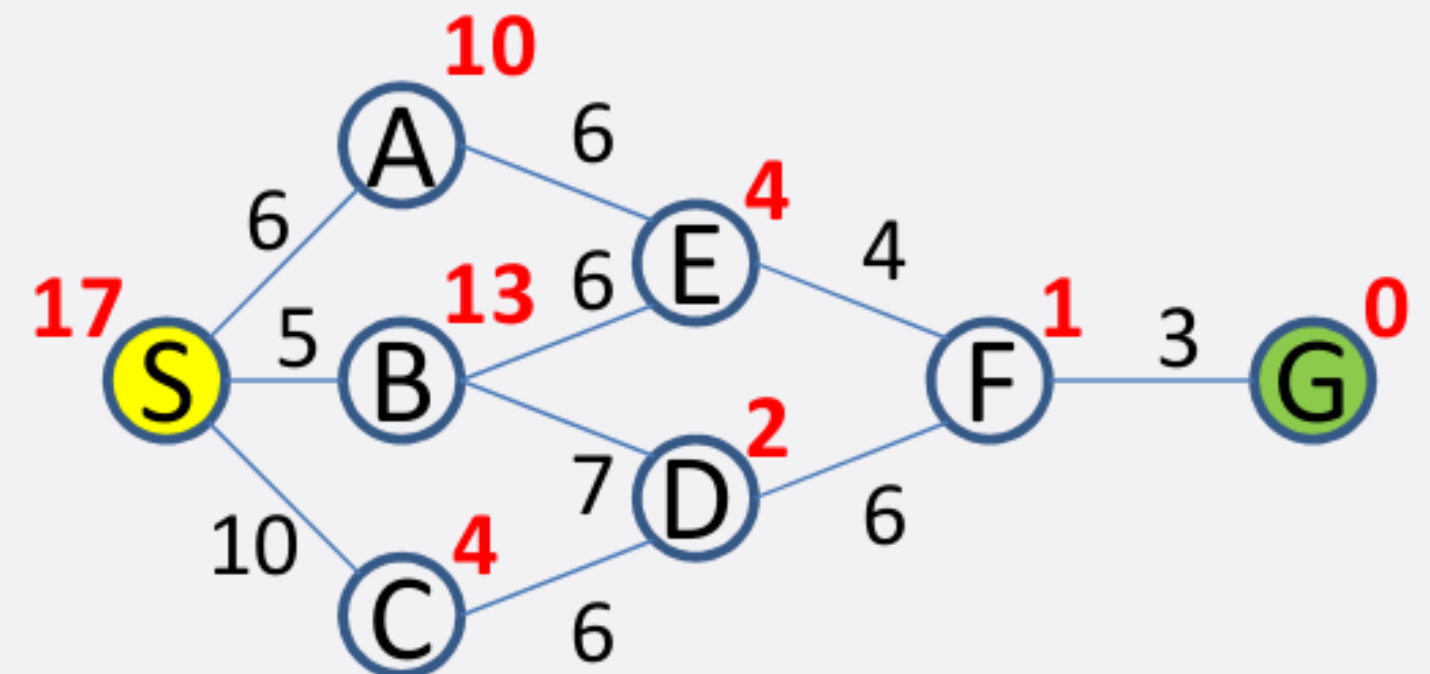
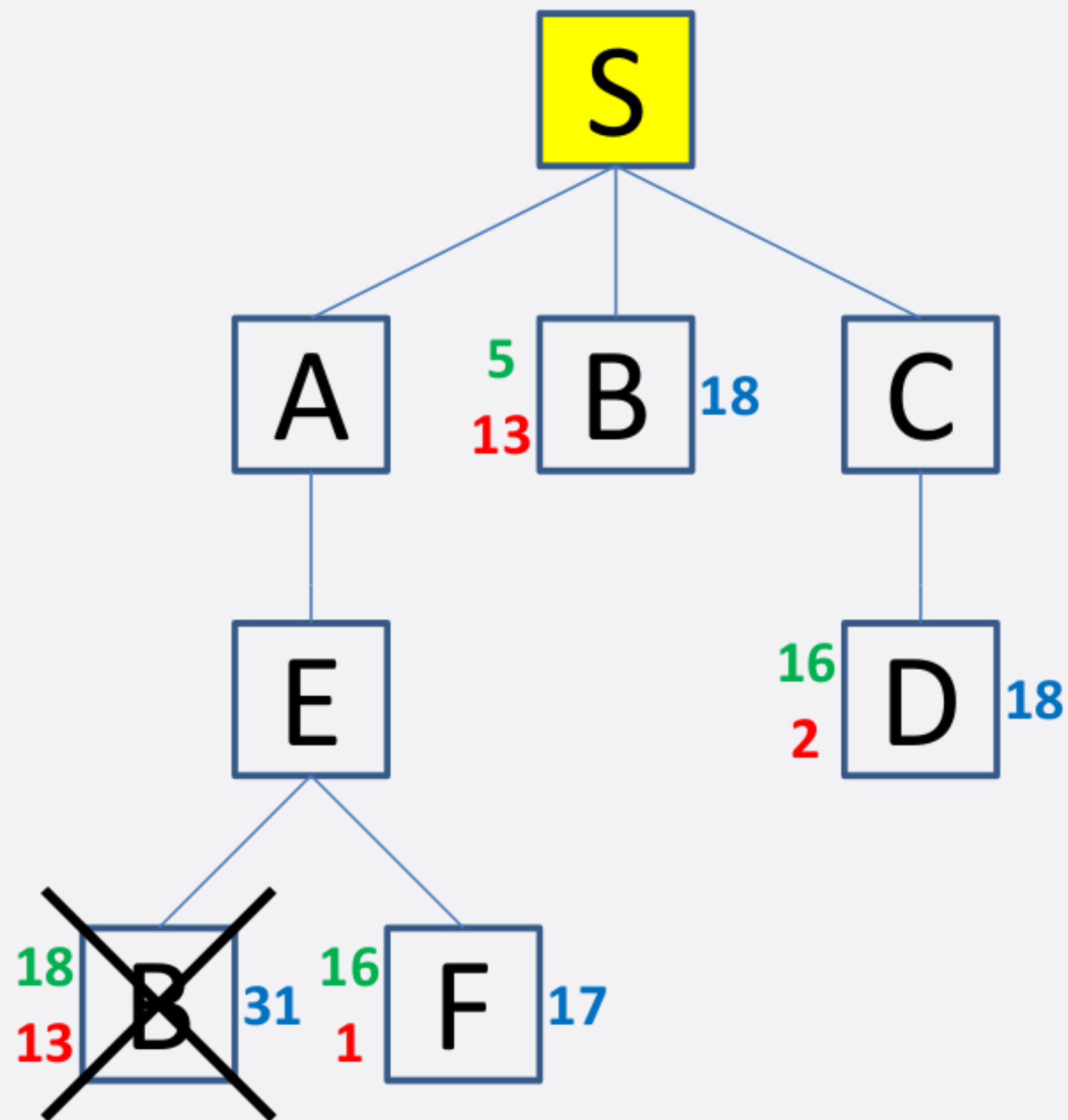
SAE

SCD

SB

Exercise 3.13

- Step 5



QUEUE:

SAEF

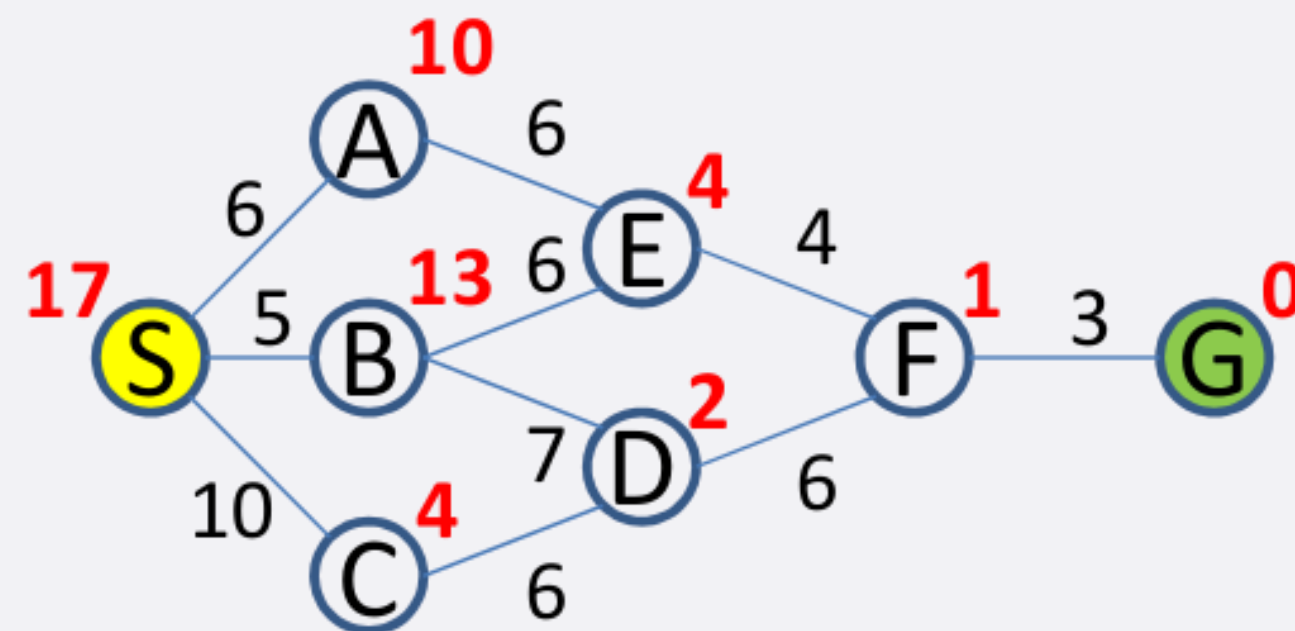
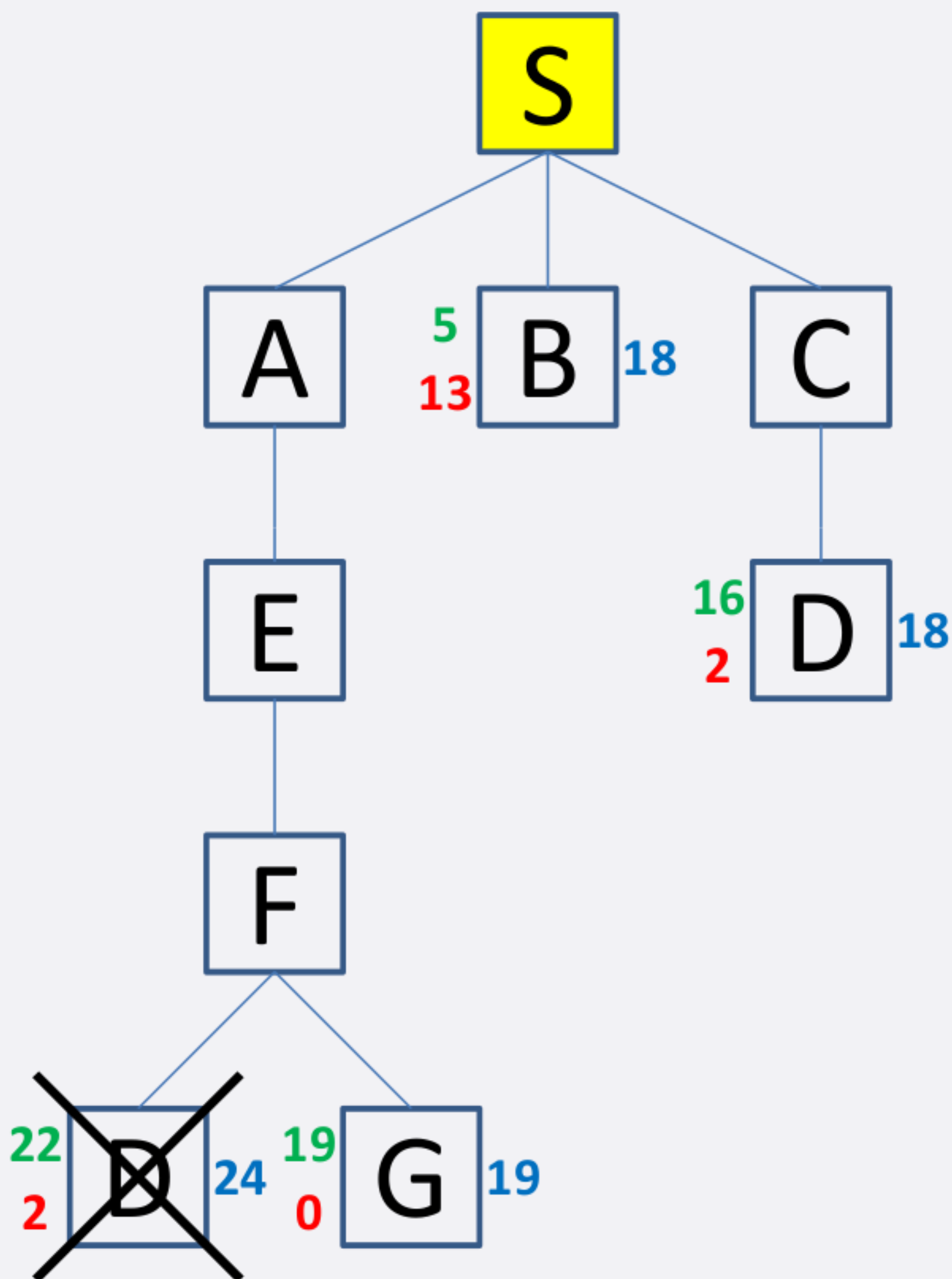
SCD

SB

SAEB

Exercise 3.13

- Step 6



QUEUE:

SCD

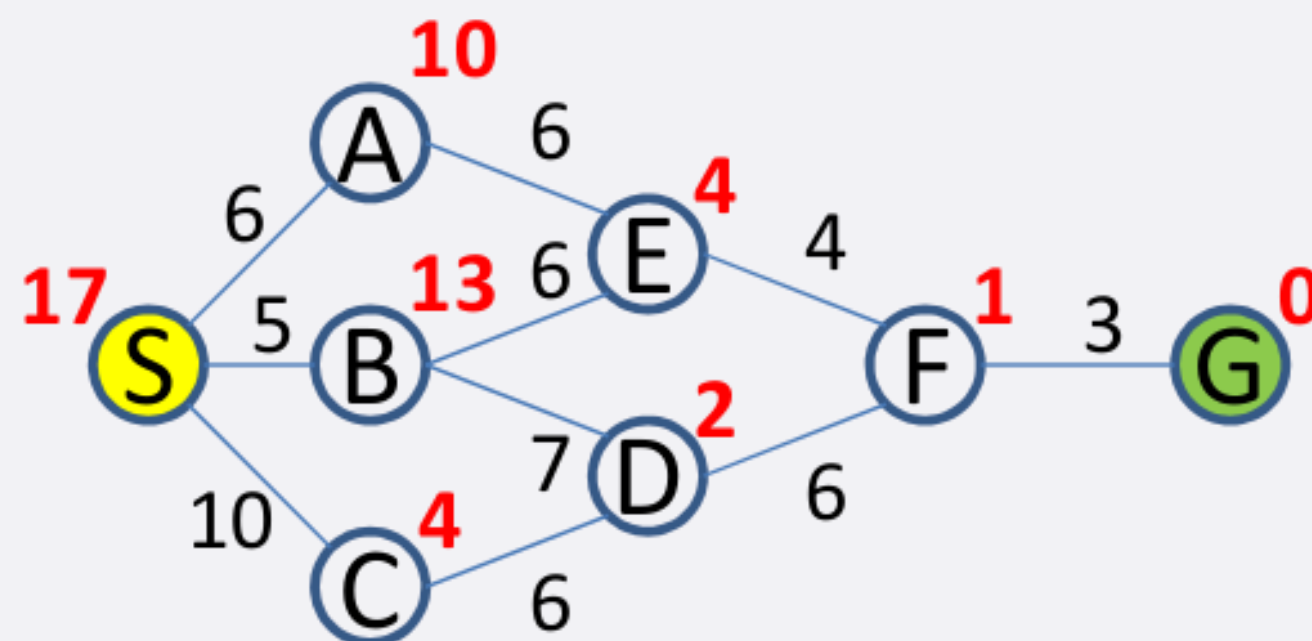
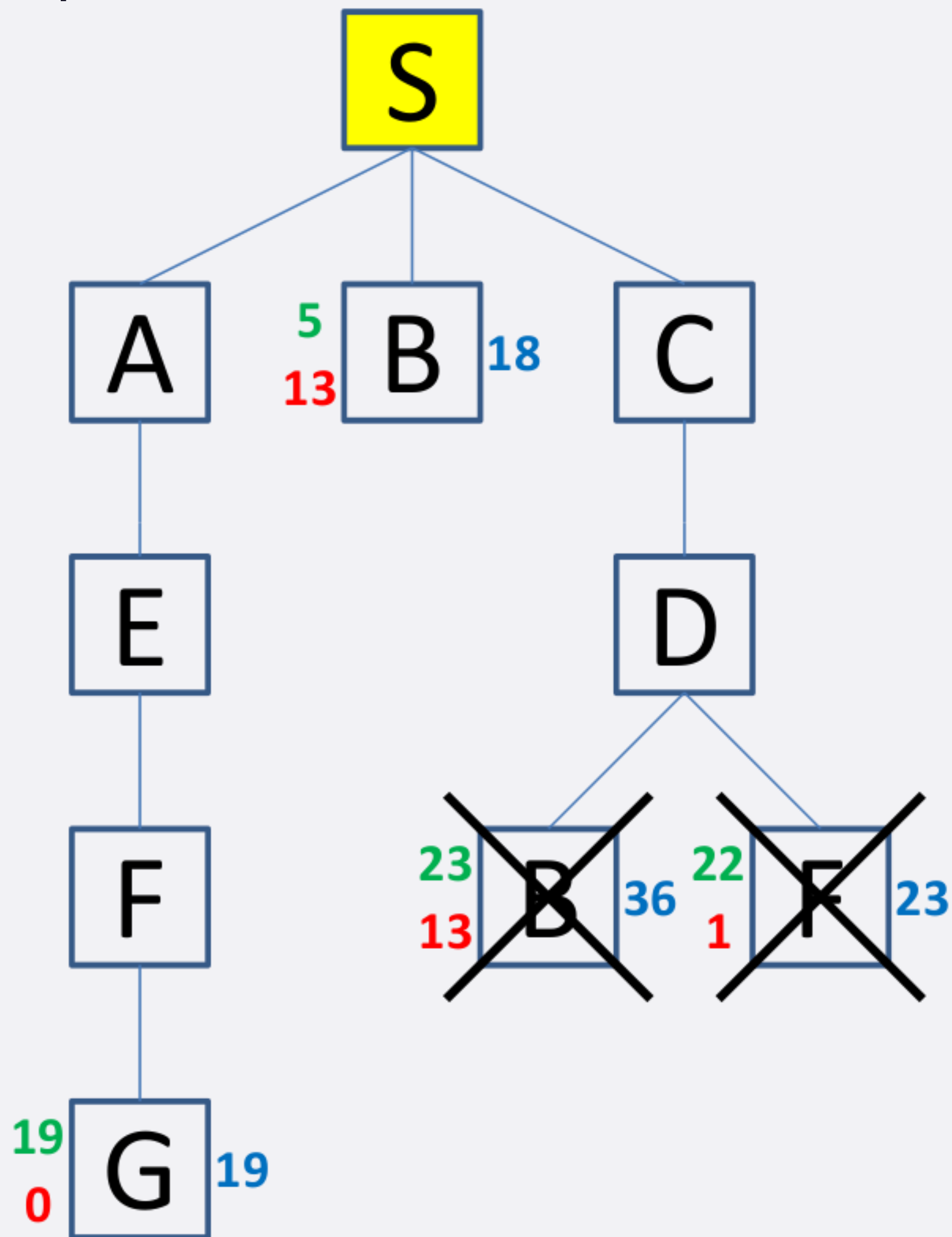
SB

SAEFG

SAEFD

Exercise 3.13

- Step 7



QUEUE:

SB

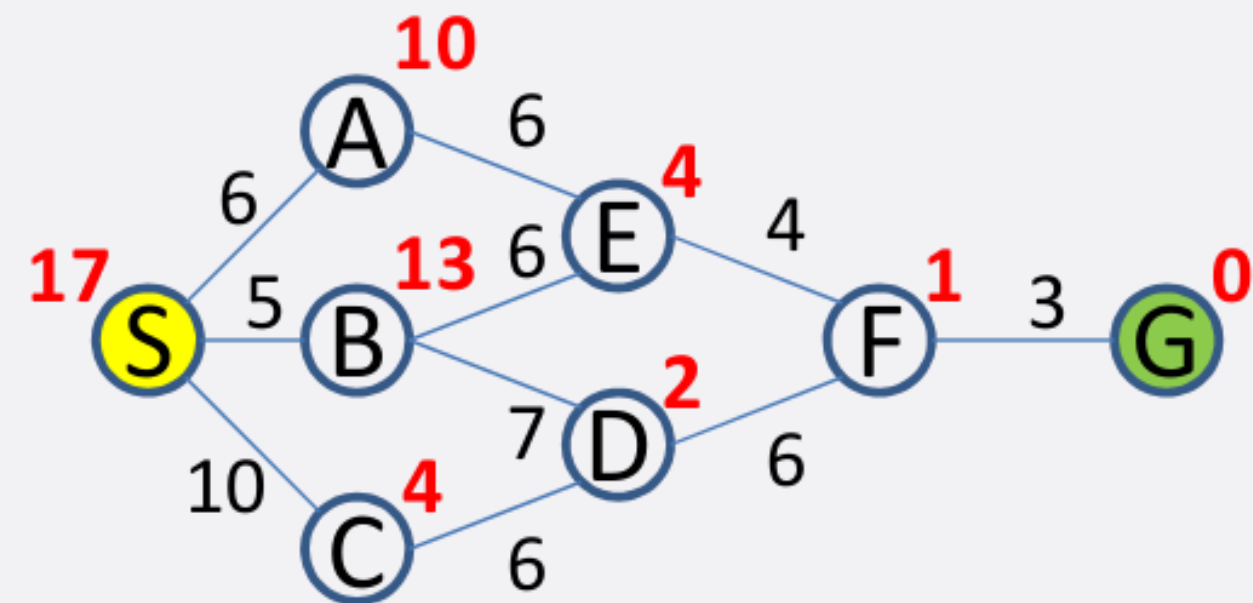
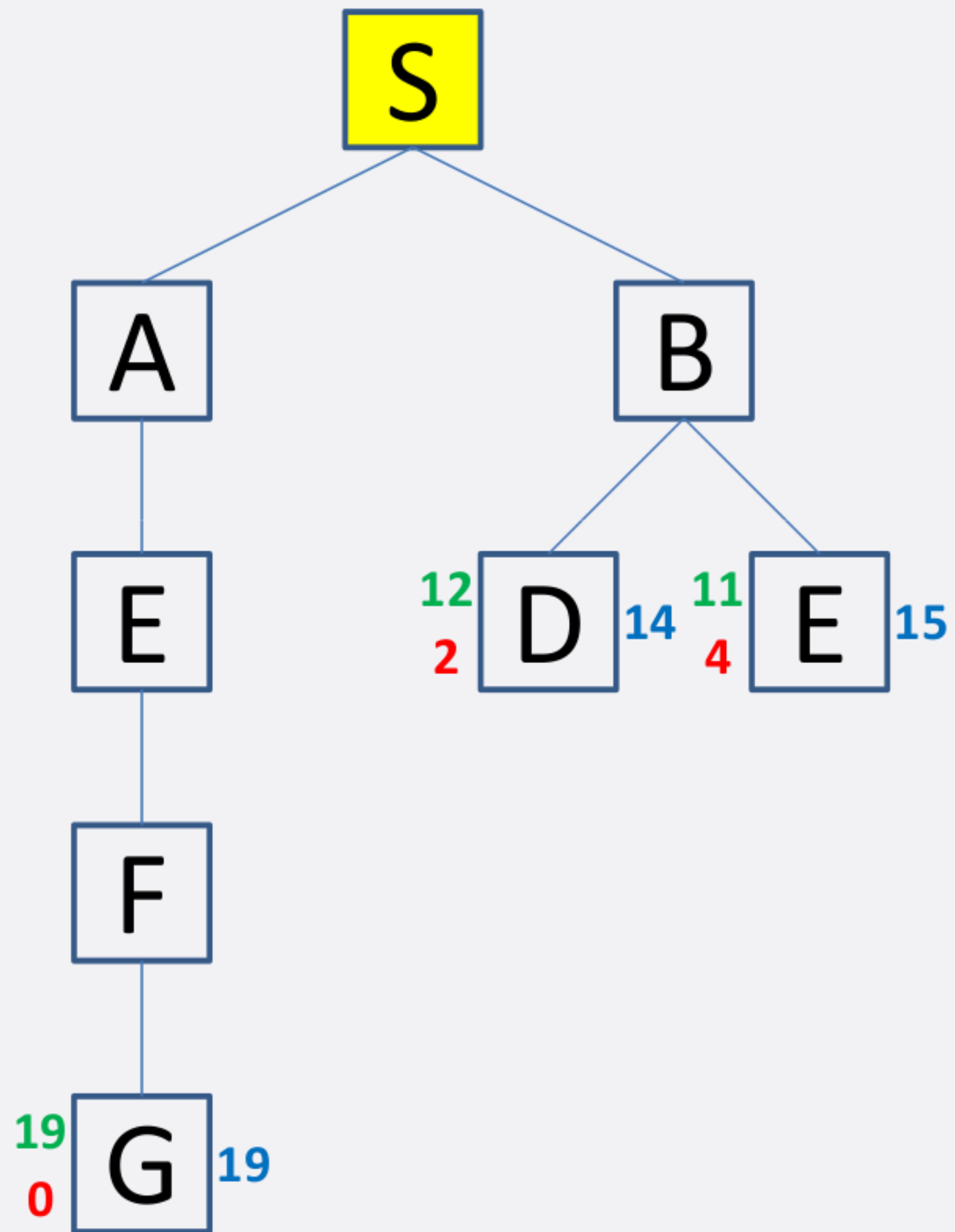
SAEFG

SCDF

SCDB

Exercise 3.13

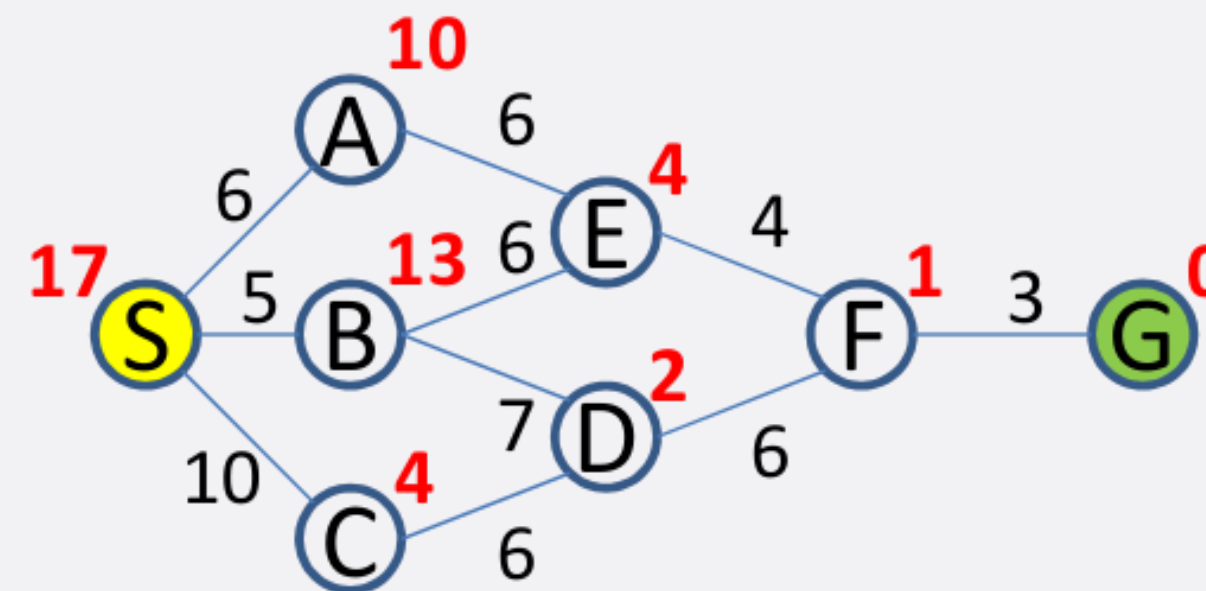
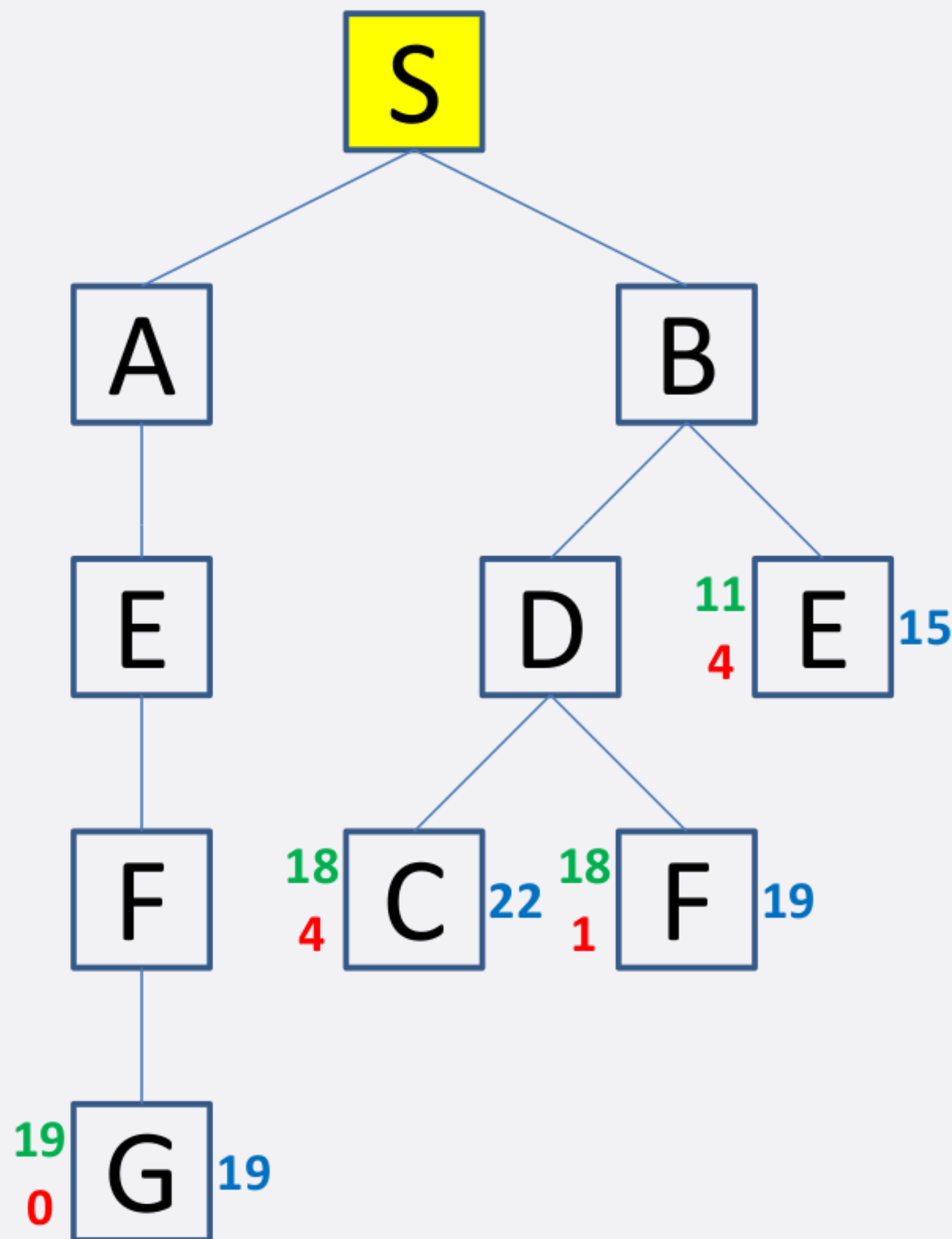
- Step 8



QUEUE:
 SBD
 SBE
 SAEFG

Exercise 3.13

- Step 9



QUEUE:

SBE

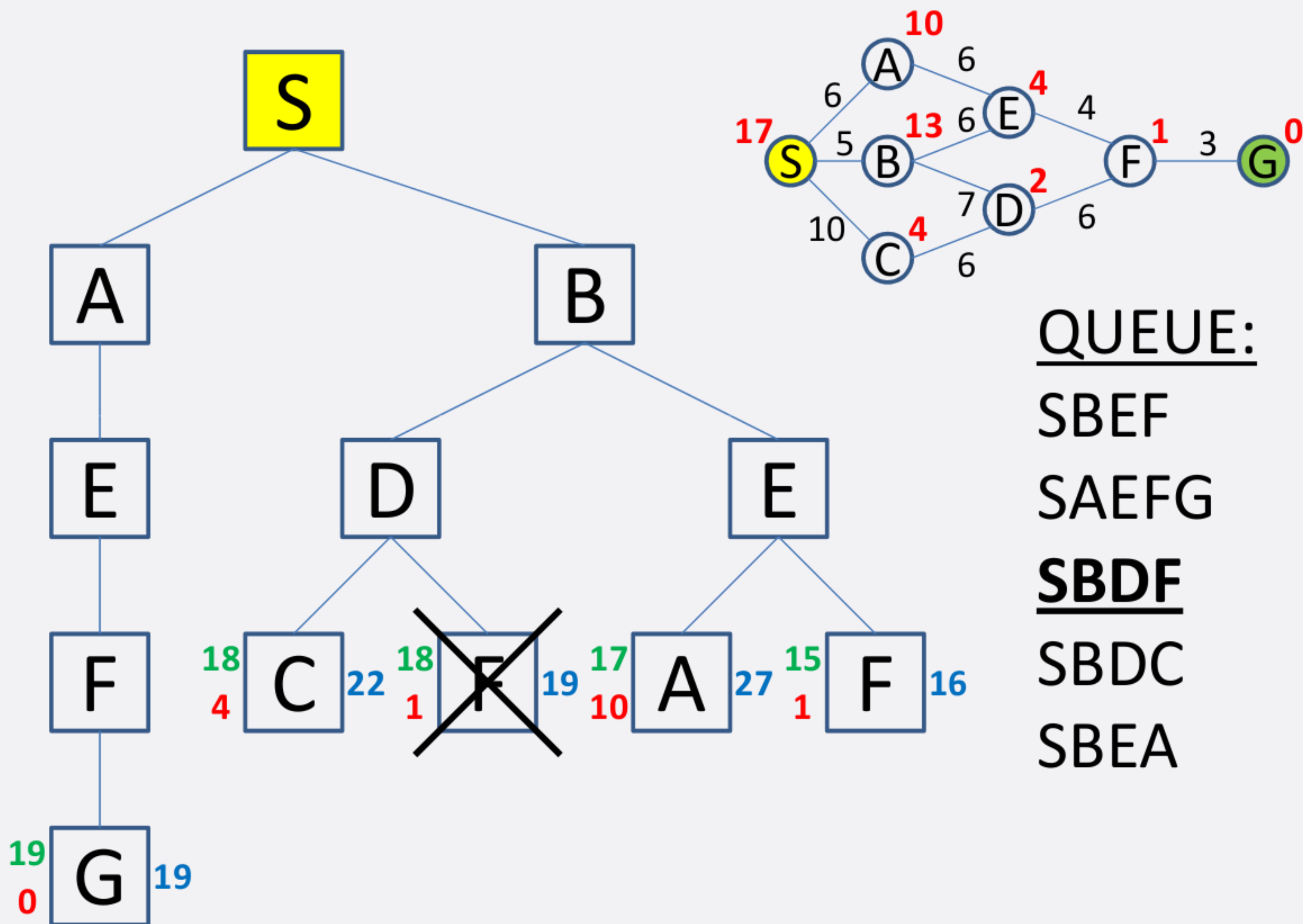
SBDF

SAEFG

SBDC

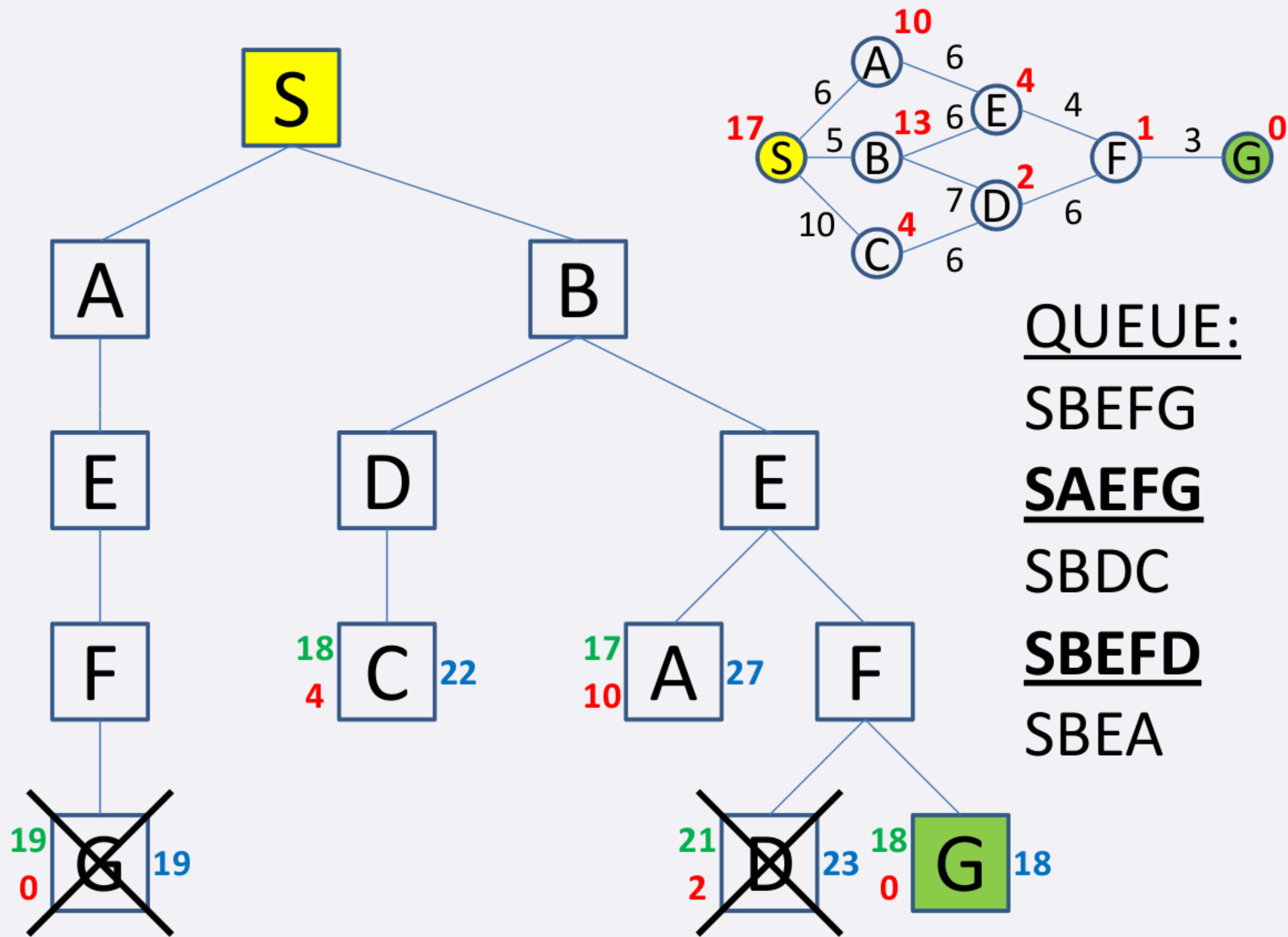
Exercise 3.13

- Step 10



Exercise 3.13

- Step 11



Exercise 3.14

- Design a genetic algorithm for solving a Sudoku puzzle.
 - Provide the data structure needed and define the parameters.
 - Define the fitness function.
 - Define the selection operator.
 - Define the crossover operator.
 - Define the mutation operator.

Exercise 3.14

- Design a genetic algorithm for solving a Sudoku puzzle.

						1	6	
					9	5		
				4				
	4	1		2				
			3			6		
	8							
7							2	4
3			9					
								8