

Formal Methods:

Module II: Model Checking

Ch. 07: **SAT-Based Model Checking**

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- 1 SAT-based Model Checking: Generalities
- 2 Bounded Model Checking
 - Intuitions
 - General Encoding
 - Relevant Subcases
 - An Example
 - Computing Upper Bounds
 - Discussion
- 3 Inductive reasoning on invariants (aka “K-Induction”)
 - K-Induction
 - An Example
- 4 Exercises

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SAT-based Model Checking

- Key problems with BDD's:
 - they can explode in space
- A possible alternative:
 - Propositional Satisfiability Checking (SAT)
 - SAT technology is very advanced
- Advantages:
 - reduced memory requirements
 - limited sensitivity: one good setting, does not require expert users
 - much higher capacity (more variables) than BDD based techniques
- Various techniques: [Bounded Model Checking \(BMC\)](#), [K-induction](#), [Interpolant-based](#), [IC3/PDR](#),...

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SAT-based Bounded Model Checking & K-Induction

Key Ideas:

- **BMC**: look for counter-example paths of increasing length k
⇒ oriented to finding bugs
- **K-Induction**: look for an induction proofs of increasing length k
⇒ oriented to prove correctness
- BMC [resp. K-induction]: for each k , build a Boolean formula that is satisfiable [resp. unsatisfiable] iff there is a counter-example [resp. proof] of length k
 - can be expressed using $k \cdot |s|$ variables
 - formula construction is not subject to state explosion
- satisfiability of the Boolean formulas is checked by a **SAT solver**
 - can manage complex formulae on several 100K variables
 - returns satisfying assignment (i.e., a counter-example)
 - exploit incrementality

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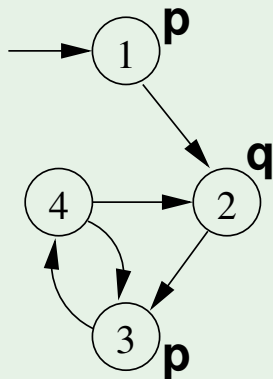
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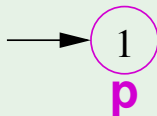
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Bounded Model Checking: Example

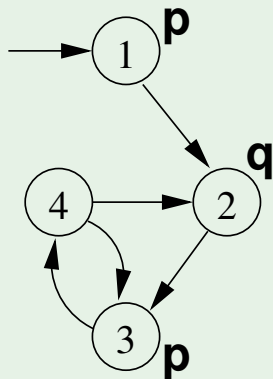


- LTL Formula: $\mathbf{G}(p \rightarrow \mathbf{F}q)$
- Negated Formula (violation): $\mathbf{F}(p \wedge \mathbf{G}\neg q)$
- $k = 0$:

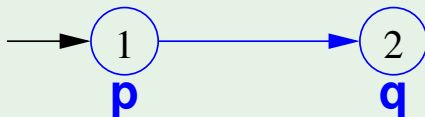


- No counter-example found.

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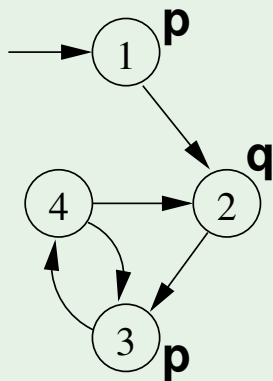


- LTL Formula: $\mathbf{G}(p \rightarrow \mathbf{F}q)$
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- $k = 1$:

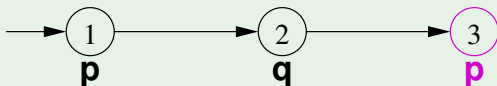


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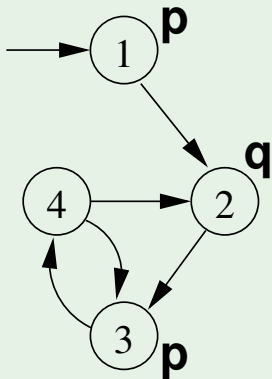


- LTL Formula: $\mathbf{G}(p \rightarrow \mathbf{F}q)$
- Negated Formula (violation): $\mathbf{F}(p \wedge \mathbf{G}\neg q)$
- $k = 2$:

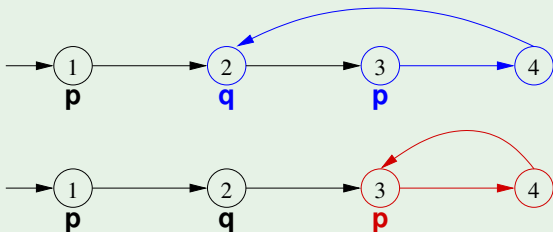


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Bounded Model Checking: Example



- LTL Formula: $\mathbf{G}(p \rightarrow \mathbf{F}q)$
- Negated Formula (violation): $\mathbf{F}(p \wedge \mathbf{G}\neg q)$
- $k = 3$:



- The 2nd trace is a counter-example!

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The problem [Biere et al, 1999]

Ingredients:

Assume states represented by an array s of n Boolean variables

- a **system** written as a Kripke structure $M := \langle I(s), R(s, s') \rangle$
- a **property** f written as a **LTL formula**
- an integer $k \geq 0$ (**bound**)

Problem

Is there an execution path π of M of length k satisfying the temporal property f ?

$$M \models_k \mathbf{E}f$$

Note: f is the negation of the property in the LTL model checking problem $M \models \neg f$, and π is a counter-example of length k (bug).

- The check is repeated for increasing values of $k = 0, 1, 2, 3, \dots$

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The encoding

Equivalent to the satisfiability problem of a Boolean formula $[[M, f]]_k$ defined as follows:

$$[[M, f]]_k := [[M]]_k \wedge [[f]]_k$$

$$[[M]]_k := I(s^0) \wedge \bigwedge_{i=0}^{k-1} R(s^i, s^{i+1}),$$

$$[[f]]_k := \left(\bigvee_{l=0}^k R(s^k, s^l) \wedge [[f]]_k^0 \right) \vee \bigvee_{l=0}^k (R(s^k, s^l) \wedge \neg [[f]]_k^0),$$

- The vector s of propositional variables is replicated $k+1$ times s^0, s^1, \dots, s^k
- $[[M]]_k$ encodes the fact that the k -path is an execution of M
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The Encoding [cont.]

The encoding for a formula f with k steps, $[[f]]_k$ is the disjunction of

- The constraints needed to express a model without loopback:

$$(\neg(\bigvee_{l=0}^k R(s^k, s^l)) \wedge [[f]]_k^0)$$

- $[[f]]_k^i, i \in [0, k]$: encodes the fact that f holds in s^i under the assumption that s^0, \dots, s^k is a no-loopback path
- The constraints needed to express a given loopback, for all possible points of loopback:
 - ${}_i[[f]]_k^i, i \in [0, k]$: encodes the fact that f holds in s^i under the assumption that s^0, \dots, s^k is a path with a loopback from s^k to s^i

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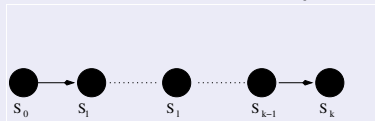
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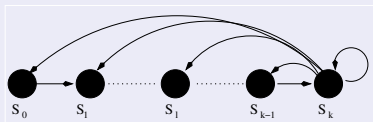
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$$\bigvee_{i=0}^k (R(s^k, s^i) \wedge i[[f]]_k^0)$$



- $i[[f]]_k^i, i \in [0, k]$: encodes the fact that f holds in s^i under the assumption that s^0, \dots, s^k is a path with a loopback from s^k to s^i

The Encoding of $[[f]]_k^i$ and ${}_i[[f]]_k^i$

f	$[[f]]_k^i$	${}_i[[f]]_k^i$
p	p_i	p_i
$\neg p$	$\neg p_i$	$\neg p_i$
$h \wedge g$	$[[h]]_k^i \wedge [[g]]_k^i$	${}_i[[h]]_k^i \wedge {}_i[[g]]_k^i$
$h \vee g$	$[[h]]_k^i \vee [[g]]_k^i$	${}_i[[h]]_k^i \vee {}_i[[g]]_k^i$
$\mathbf{X}g$	$[[g]]_k^{i+1}$ if $i < k$ \perp otherwise.	${}_i[[g]]_k^{i+1}$ if $i < k$ ${}_i[[g]]_k^i$ otherwise.
$\mathbf{G}g$	\perp	$\bigwedge_{j=\min(i,l)}^k {}_i[[g]]_k^j$
$\mathbf{F}g$	$\bigvee_{j=i}^k [[g]]_k^j$	$\bigvee_{j=\min(i,l)}^k {}_i[[g]]_k^j$
$h\mathbf{U}g$	$\bigvee_{j=i}^k \left([[g]]_k^j \wedge \bigwedge_{n=i}^{j-1} [[h]]_k^n \right)$	$\bigvee_{j=i}^k \left({}_i[[g]]_k^j \wedge \bigwedge_{n=i}^{j-1} {}_i[[h]]_k^n \right) \vee$ $\bigvee_{j=l}^{i-1} \left({}_i[[g]]_k^j \wedge \bigwedge_{n=i}^k {}_i[[h]]_k^n \wedge \bigwedge_{n=l}^{j-1} {}_i[[h]]_k^n \right)$
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Relevant Subcase: $\mathbf{F}p$ (reachability)

- $f := \mathbf{F}p$, s.t. p Boolean:
is there a reachable state in which p holds?
- a finite path can show that the property holds
- $[[M, f]]_k$ is:

$$I(s^0) \wedge \bigwedge_{i=0}^{k-1} R(s^i, s^{i+1}) \wedge \bigvee_{j=0}^k p^j$$



Important: incremental encoding

if done for increasing value of k , then it suffices that $[[M, f]]_k$ is:

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Relevant Subcase: $\mathbf{G}p$

- $f := \mathbf{G}p$, s.t. p Boolean: **is there a path where p holds forever?**
- We need to produce an infinite behaviour, with a finite number of transitions
- We can do it by imposing that the path loops back

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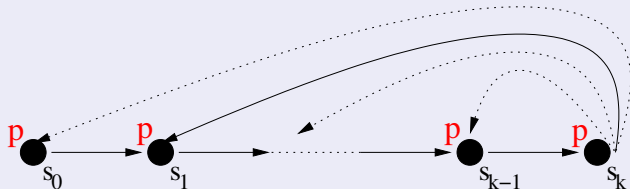
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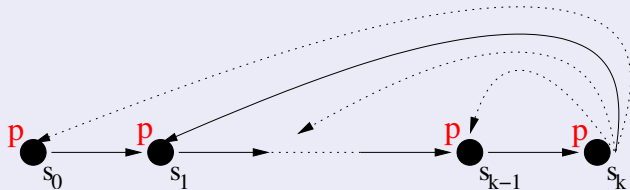


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Relevant Subcase: $\mathbf{GF}q$ (fair states)

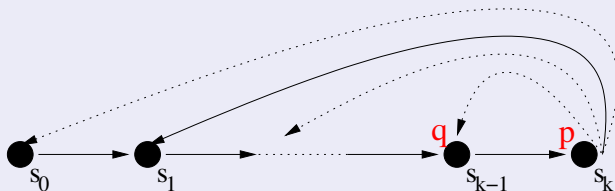
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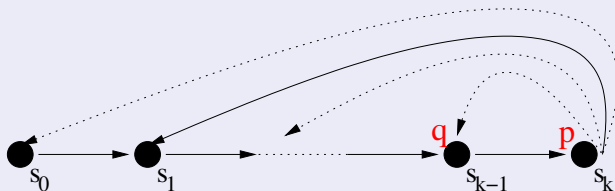


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Subcase Combination: $\mathbf{GF}q \wedge \mathbf{F}p$ (fair reachability)

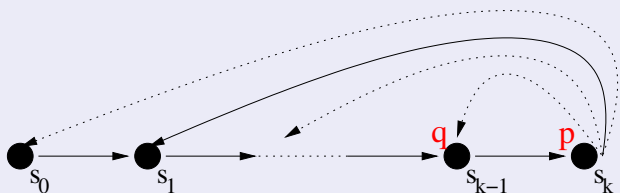
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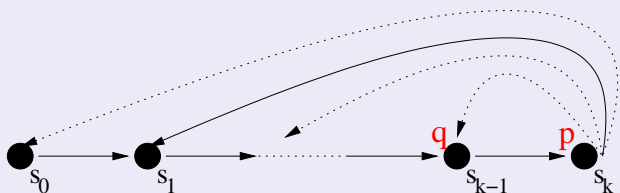


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Example: a bugged 3-bit shift register

- System M :

- $I(x) := \neg x[0] \wedge \neg x[1] \wedge x[2]$
- Correct R : $R(x, x') := (x'[0] \leftrightarrow x[1]) \wedge (x'[1] \leftrightarrow x[2]) \wedge (x'[2] \leftrightarrow 0)$
- Bugged R : $R(x, x') := (x'[0] \leftrightarrow x[1]) \wedge (x'[1] \leftrightarrow x[2]) \wedge (x'[2] \leftrightarrow 1)$

- Property: $\mathbf{F}(\neg x[0] \wedge \neg x[1] \wedge \neg x[2])$

- BMC Problem: is there an execution π of M of length k s.t.
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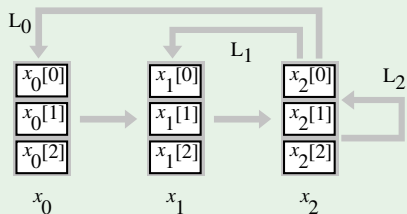
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Example: a bugged 3-bit shift register [cont.]

$k = 0$:



I : $(\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge$

$\bigvee_{i=0}^0 L_i$: $(((x_0[0] \leftrightarrow x_0[1]) \wedge (x_0[1] \leftrightarrow x_0[2]) \wedge (x_0[2] \leftrightarrow 1))) \wedge$

$\bigwedge_{i=0}^0 (x \neq 0)$: $((x_0[0] \vee x_0[1] \vee x_0[2]))$

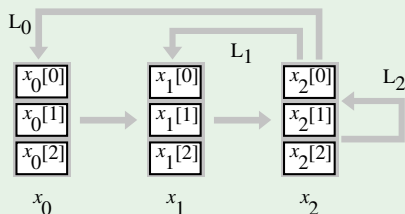
\Rightarrow UNSAT: unit propagation:

$\neg x_0[0], \neg x_0[1], x_0[2]$

\Rightarrow loop violated

Example: a bugged 3-bit shift register [cont.]

$k = 0$:



$$I: \quad (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge$$
$$\bigvee_{l=0}^0 L_l: \quad (((x_0[0] \leftrightarrow x_0[1]) \wedge (x_0[1] \leftrightarrow x_0[2]) \wedge (x_0[2] \leftrightarrow 1))) \wedge$$
$$\bigwedge_{i=0}^0 (x \neq 0): \quad ((x_0[0] \vee x_0[1] \vee x_0[2]))$$

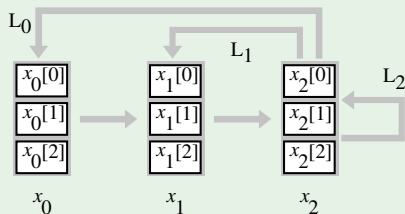
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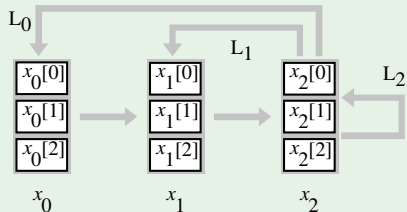
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Example: a bugged 3-bit shift register [cont.]

$k = 1$:



$$\begin{aligned} I : & (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge \\ [[M]]_1 : & ((x_1[0] \leftrightarrow x_0[1]) \wedge (x_1[1] \leftrightarrow x_0[2]) \wedge (x_1[2] \leftrightarrow 1)) \wedge \\ \bigvee_{l=0}^1 L_l : & \left(\begin{aligned} & ((x_0[0] \leftrightarrow x_1[1]) \wedge (x_0[1] \leftrightarrow x_1[2]) \wedge (x_0[2] \leftrightarrow 1)) \vee \\ & ((x_1[0] \leftrightarrow x_1[1]) \wedge (x_1[1] \leftrightarrow x_1[2]) \wedge (x_1[2] \leftrightarrow 1)) \end{aligned} \right) \wedge \\ \bigwedge_{i=0}^1 (x \neq 0) : & \left(\begin{aligned} & (x_0[0] \vee x_0[1] \vee x_0[2]) \wedge \\ & (x_1[0] \vee x_1[1] \vee x_1[2]) \end{aligned} \right) \end{aligned}$$

\Rightarrow UNSAT: unit propagation:

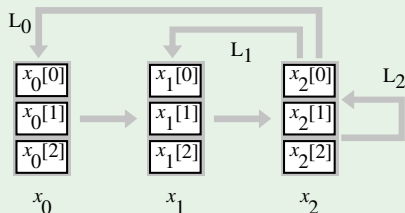
$$\neg x_0[0], \neg x_0[1], x_0[2]$$

$$\neg x_1[0], x_1[1], x_1[2]$$

\Rightarrow both loop disjuncts violated

Example: a bugged 3-bit shift register [cont.]

$k = 1$:



$$\begin{aligned} I : & (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge \\ [[M]]_1 : & ((x_1[0] \leftrightarrow x_0[1]) \wedge (x_1[1] \leftrightarrow x_0[2]) \wedge (x_1[2] \leftrightarrow 1)) \wedge \\ \bigvee_{l=0}^1 L_l : & \left(\begin{array}{l} ((x_0[0] \leftrightarrow x_1[1]) \wedge (x_0[1] \leftrightarrow x_1[2]) \wedge (x_0[2] \leftrightarrow 1)) \vee \\ ((x_1[0] \leftrightarrow x_1[1]) \wedge (x_1[1] \leftrightarrow x_1[2]) \wedge (x_1[2] \leftrightarrow 1)) \end{array} \right) \wedge \\ \bigwedge_{i=0}^1 (x \neq 0) : & \left(\begin{array}{l} (x_0[0] \vee x_0[1] \vee x_0[2]) \wedge \\ (x_1[0] \vee x_1[1] \vee x_1[2]) \end{array} \right) \end{aligned}$$

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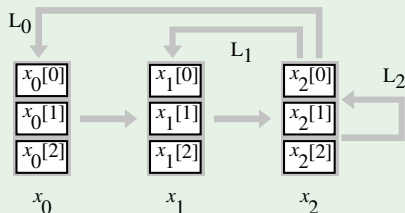
$$\neg x_0[0], \neg x_0[1], x_0[2]$$

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Example: a bugged 3-bit shift register [cont.]

$k = 1$:



$$\begin{aligned}
 I : & \quad (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge \\
 [[M]]_1 : & \quad ((x_1[0] \leftrightarrow x_0[1]) \wedge (x_1[1] \leftrightarrow x_0[2]) \wedge (x_1[2] \leftrightarrow 1)) \wedge \\
 \bigvee_{l=0}^1 L_l : & \quad \left(\begin{aligned} & ((x_0[0] \leftrightarrow x_1[1]) \wedge (x_0[1] \leftrightarrow x_1[2]) \wedge (x_0[2] \leftrightarrow 1)) \vee \\ & ((x_1[0] \leftrightarrow x_1[1]) \wedge (x_1[1] \leftrightarrow x_1[2]) \wedge (x_1[2] \leftrightarrow 1)) \end{aligned} \right) \wedge \\
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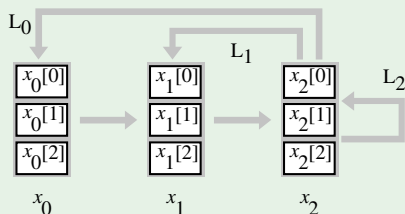
$$\neg x_0[0], \neg x_0[1], x_0[2]$$

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Example: a bugged 3-bit shift register [cont.]

$k = 2$:

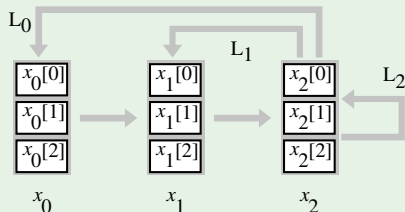


$$\begin{aligned} I: & (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge \\ [[M]]_2: & \left(\begin{array}{l} (x_1[0] \leftrightarrow x_0[1]) \wedge (x_1[1] \leftrightarrow x_0[2]) \wedge (x_1[2] \leftrightarrow 1) \wedge \\ (x_2[0] \leftrightarrow x_1[1]) \wedge (x_2[1] \leftrightarrow x_1[2]) \wedge (x_2[2] \leftrightarrow 1) \end{array} \right) \wedge \\ \bigvee_{i=0}^2 L_i: & \left(\begin{array}{l} ((x_0[0] \leftrightarrow x_2[1]) \wedge (x_0[1] \leftrightarrow x_2[2]) \wedge (x_0[2] \leftrightarrow 1)) \vee \\ ((x_1[0] \leftrightarrow x_2[1]) \wedge (x_1[1] \leftrightarrow x_2[2]) \wedge (x_1[2] \leftrightarrow 1)) \vee \\ ((x_2[0] \leftrightarrow x_2[1]) \wedge (x_2[1] \leftrightarrow x_2[2]) \wedge (x_2[2] \leftrightarrow 1)) \end{array} \right) \wedge \\ \bigwedge_{i=0}^2 (x \neq 0): & \left(\begin{array}{l} (x_0[0] \vee x_0[1] \vee x_0[2]) \wedge \\ (x_1[0] \vee x_1[1] \vee x_1[2]) \wedge \\ (x_2[0] \vee x_2[1] \vee x_2[2]) \end{array} \right) \end{aligned}$$

\implies SAT: $x_0[0] = x_0[1] = x_1[0] = 0$; $x_i[j] := 1 \forall i, j$

Example: a bugged 3-bit shift register [cont.]

$k = 2$:



$$I: (\neg x_0[0] \wedge \neg x_0[1] \wedge x_0[2]) \wedge$$

$$[[M]_2: \left(\begin{array}{l} (x_1[0] \leftrightarrow x_0[1]) \wedge (x_1[1] \leftrightarrow x_0[2]) \wedge (x_1[2] \leftrightarrow 1) \wedge \\ (x_2[0] \leftrightarrow x_1[1]) \wedge (x_2[1] \leftrightarrow x_1[2]) \wedge (x_2[2] \leftrightarrow 1) \end{array} \right) \wedge$$

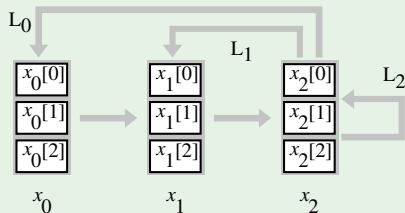
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Basic bounds for k

Theorem [Biere et al. TACAS 1999]

Let f be a LTL formula. $M \models \mathbf{E}f \iff M \models_k \mathbf{E}f$ for some $k \leq |M| \cdot 2^{|f|}$.

- $|M| \cdot 2^{|f|}$ is always a bound of k .
 - $|M|$ huge!
 \implies not so easy to compute in a symbolic setting.
- \implies need to find better bounds!

Note: [Biere et al. TACAS 1999] use “ $M \models \mathbf{E}f$ ” as “there exists a path of M verifying f ”, so that $M \not\models \neg f \iff M \models \mathbf{E}f$

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Other bounds for k

ACTL & ECTL

- **ACTL** is a subset of CTL in which “**A...**” (resp. “**E...**”) sub-formulas occur only positively (resp. negatively) in each formula. (e.g. **AG**($p \rightarrow$ **AGAF** q))
- Many frequently-used LTL properties $\neg f$ have equivalent ACTL representations **A** $\neg f'$
 - e.g. **X** $q \iff$ **AX** q , **G** $q \iff$ **AG** q , **F** $q \iff$ **AF** q , p **U** $q \iff$ **A**(p **U** q), **GF** $q \iff$ **AGAF** q , **G**($p \rightarrow$ **GF** q) \iff **AG**($p \rightarrow$ **AGAF** q)
- **ECTL** is a subset of CTL in which “**E...**” (resp. “**A...**”) sub-formulas occur only positively (resp. negatively) in each formula. (e.g. **EF**($p \wedge$ **EFEG** $\neg q$))
- ECTL is the dual subset of ACTL: $\phi \in$ **ECTL** \iff $\neg\phi \in$ **ACTL**.

Theorem [Biere et al. TACAS 1999]

Let f be an ECTL formula. $M \models$ **E** $f \iff M \models_k$ **E** f for some $k \leq |M|$.

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 - e.g. **X** $q \iff$ **AX** q , **G** $q \iff$ **AG** q , **F** $q \iff$ **AF** q , p **U** $q \iff$ **A**(p **U** q), **GF** $q \iff$ **AGAF** q , **G**($p \rightarrow$ **GF** q) \iff **AG**($p \rightarrow$ **AGAF** q)
- **ECTL** is a subset of CTL in which “**E...**” (resp. “**A...**”) sub-formulas occur only positively (resp. negatively) in each formula. (e.g. **EF**($p \wedge$ **EFEG** $\neg q$))
- ECTL is the dual subset of ACTL: $\phi \in \text{ECTL} \iff \neg\phi \in \text{ACTL}$.

Theorem [Biere et al. TACAS 1999]

Let f be an ECTL formula. $M \models \mathbf{E}f \iff M \models_k \mathbf{E}f$ for some $k \leq |M|$.

Other bounds for k (cont)

Theorem [Biere et al. TACAS 1999]

Let p be a Boolean formula and d be the **diameter** of M . Then $M \models \mathbf{EF}p \iff M \models_k \mathbf{EF}p$ for some $k \leq d$.

Theorem [Biere et al. TACAS 1999]

Let f be an ECTL formula and d be the **recurrence diameter** of M . Then $M \models \mathbf{E}f \iff M \models_k \mathbf{E}f$ for some $k \leq d$.

The diameter

Definition: Diameter

Given M , the **diameter** of M is the smallest integer d s.t. for every path s_0, \dots, s_{d+1} there exist a path t_0, \dots, t_l s.t. $l \leq d$, $t_0 = s_0$ and $t_l = s_{d+1}$.

- Intuition: if u is reachable from v , then there is a path from v to u of length d or less.

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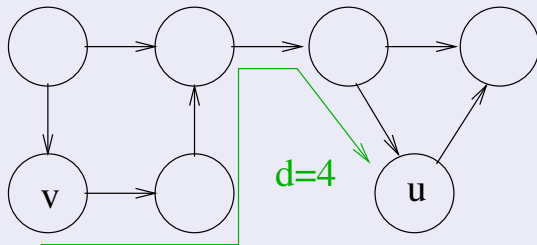
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Definition: recurrence diameter

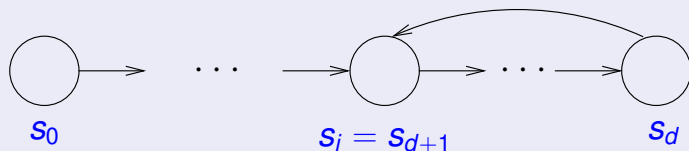
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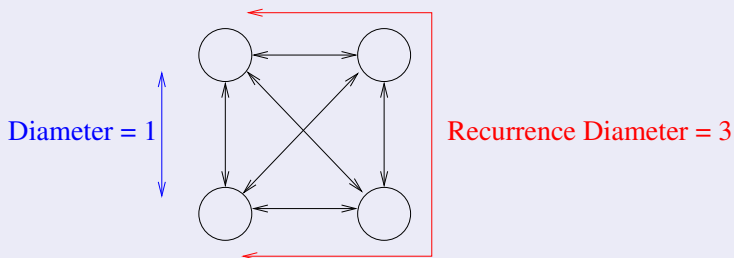
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Other Successful SAT-based MC Techniques

- Inductive reasoning on invariants (aka “K-Induction”)
- Counter-example guided abstraction refinement (CEGAR)
[Clarke et al. CAV 2002]
- Interpolant-based MC
[Mc Millan, TACAS 2005]
- IC3/PDR
[Bradley, VMCAI 2011]
- ...

For a survey see e.g.

[Amla et al., CHARME 2005, Prasad et al. STTT 2005].

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Inductive Reasoning on Invariants

Invariant: “**G***Good*”, *Good* being a Boolean formula

- (i) If all the initial states are good,
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- then the system is correct for all reachable states

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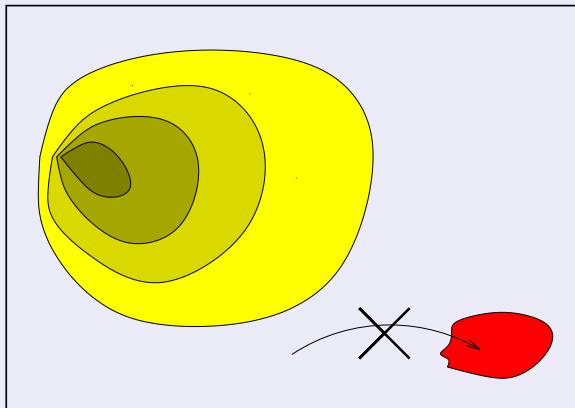
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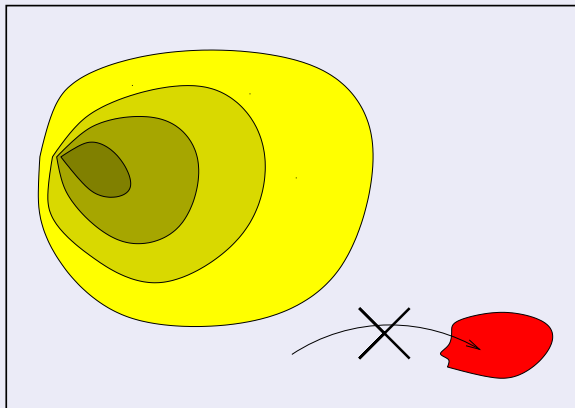
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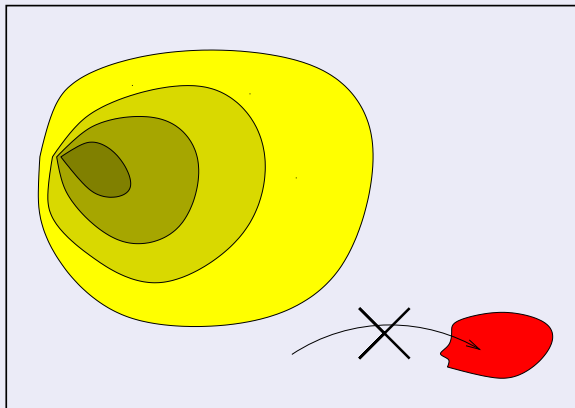
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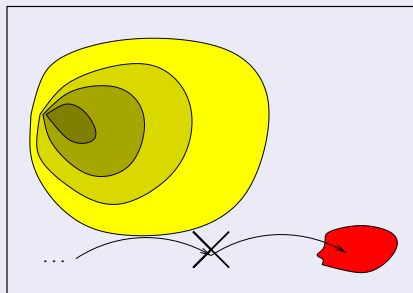


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Solution (once you know you cannot reach $\neg\text{Good}$ in up to 1 step):

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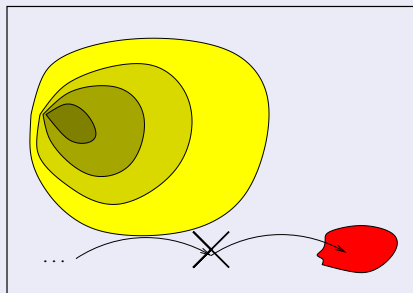
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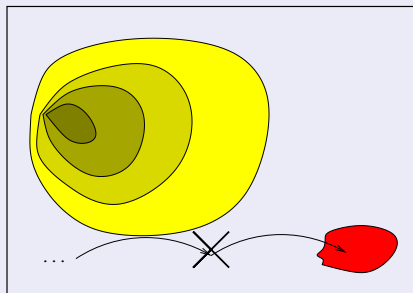
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...

- repeat for increasing values of the gap 1, 2, 3, 4,
- **intuition**: increasingly tighten the constraint for “spurious” counterexamples: a spurious counterexample must be a chain s_{k-n}, \dots, s_k of **unreachable** and **different** states s.t. $\neg \text{Good}(s_k)$ and $R(s_i, s_{i+1}), \forall i$.
- dual to –and interleaved with– **bounded model checking steps**
- K-Induction steps can be shifted ($k \stackrel{\text{def}}{=} 0$) to share the subformulas: $\bigwedge_{i=0}^{k-1} (R(s^i, s^{i+1}) \wedge \text{Good}(s^i)) \wedge \neg \text{Good}(s^{k-2})$

Strengthening of Invariants [cont.]

⇒ Check for the [un]satisfiability of the Boolean formulas:

$I(s^0) \wedge \neg \text{Good}(s^0)$; [BMC₀]

$(\text{Good}(s^0) \wedge R(s^0, s^1)) \wedge \neg \text{Good}(s^1)$; [Kind₀]

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K-Induction Algorithm [Sheeran et al. 2000]

Algorithm

Given:

$$Base_n := I(\mathbf{s}_0) \wedge \bigwedge_{i=0}^{n-1} (R(\mathbf{s}_i, \mathbf{s}_{i+1}) \wedge \varphi(\mathbf{s}_i)) \wedge \neg\varphi(\mathbf{s}_n)$$

$$Step_n := \bigwedge_{i=0}^n (R(\mathbf{s}_i, \mathbf{s}_{i+1}) \wedge \varphi(\mathbf{s}_i)) \wedge \neg\varphi(\mathbf{s}_{n+1})$$

$$Unique_n := \bigwedge_{0 \leq i < j \leq n} \neg(\mathbf{s}_i = \mathbf{s}_{j+1})$$

1. **function** CHECK_PROPERTY (I, R, φ)
2. **for** $n := 0, 1, 2, 3, \dots$ **do**
3. **if** (DPLL($Base_n$) == SAT)
4. **then return** PROPERTY_VIOLATED;
5. **else if** (DPLL($Step_n \wedge Unique_n$) == UNSAT)
6. **then return** PROPERTY_VERIFIED;
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⇒ reuses previous search if DPLL is incremental!!

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 - Discussion
- 3 Inductive reasoning on invariants (aka “K-Induction”)**
 - K-Induction
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- 4 Exercises

Example: a correct 3-bit shift register

- System M :

- $I(x) := (\neg x[0] \wedge \neg x[1] \wedge \neg x[2])$

- $R(x, x') := ((x'[0] \leftrightarrow x[1]) \wedge (x'[1] \leftrightarrow x[2]) \wedge (x'[2] \leftrightarrow 0))$

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- Init (BMC Step 0): $((\neg x^0[0] \wedge \neg x^0[1] \wedge \neg x^0[2]) \wedge x^0[0]) \implies \text{unsat}$

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\implies (partly by unit-propagation)

$$\text{sat: } \left\{ \begin{array}{lll} \neg x^0[0], & x^0[1], & x^0[2], \\ x^1[0], & x^1[1], & \neg x^1[2] \end{array} \right\}$$

\implies not proved

Remark

Both $\{\neg x^0[0], x^0[1], x^0[2]\}$ and $\{x^1[0], x^1[1], \neg x^1[2]\}$ are non-reachable.

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Example: a correct 3-bit shift register [cont.]

- BMC Step 1: (...) \implies unsat
- K-Induction Step 2:

$$\left(\begin{array}{l} (\neg x^0[0] \wedge ((x^1[0] \leftrightarrow x^0[1]) \wedge (x^1[1] \leftrightarrow x^0[2]) \wedge (x^1[2] \leftrightarrow 0)) \wedge \\ \neg x^1[0] \wedge ((x^2[0] \leftrightarrow x^1[1]) \wedge (x^2[1] \leftrightarrow x^1[2]) \wedge (x^2[2] \leftrightarrow 0)) \\) \wedge x^2[0] \end{array} \right) \wedge \neg((x^1[0] \leftrightarrow x^0[0]) \wedge (x^1[1] \leftrightarrow x^0[1]) \wedge (x^1[2] \leftrightarrow x^0[2]))$$

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Example: a correct 3-bit shift register [cont.]

- BMC Step 2: (...) \implies unsat
- K-Induction Step 3:

$$\left(\begin{array}{l} (\neg x^0[0] \wedge ((x^1[0] \leftrightarrow x^0[1]) \wedge (x^1[1] \leftrightarrow x^0[2]) \wedge (x^1[2] \leftrightarrow 0)) \wedge \\ \neg x^1[0] \wedge ((x^2[0] \leftrightarrow x^1[1]) \wedge (x^2[1] \leftrightarrow x^1[2]) \wedge (x^2[2] \leftrightarrow 0)) \wedge \\ \neg x^2[0] \wedge ((x^3[0] \leftrightarrow x^2[1]) \wedge (x^3[1] \leftrightarrow x^2[2]) \wedge (x^3[2] \leftrightarrow 0)) \\) \wedge x^3[0] \end{array} \right)$$
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Ex: Bounded Model Checking

Given the symbolic representation of a FSM M , expressed in terms of the two

Boolean formulas: $I(x, y) \stackrel{\text{def}}{=} \neg x \wedge y$,

$T(x, y, x', y') \stackrel{\text{def}}{=} (x' \leftrightarrow (x \leftrightarrow \neg y)) \wedge (y' \leftrightarrow \neg y)$, and the LTL property:

$\varphi \stackrel{\text{def}}{=} \neg \mathbf{F}(x \wedge y)$,

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[Solution: The question corresponds to the Bounded Model Checking problem

$M \models_2 \mathbf{E F}f$, s.t. $f(x, y) \stackrel{\text{def}}{=} (x \wedge y)$. Thus we have:

$$\begin{array}{llll} \neg x_0 \wedge y_0 & \wedge & // & I(x_0, y_0) \wedge \\ (x_1 \leftrightarrow (x_0 \leftrightarrow \neg y_0)) \wedge (y_1 \leftrightarrow \neg y_0) & \wedge & // & T(x_0, y_0, x_1, y_1) \wedge \\ (x_2 \leftrightarrow (x_1 \leftrightarrow \neg y_1)) \wedge (y_2 \leftrightarrow \neg y_1) & \wedge & // & T(x_1, y_1, x_2, y_2) \wedge \\ ((x_0 \wedge y_0) & \vee & // & (f(x_0, y_0) \vee \\ (x_1 \wedge y_1) & \vee & // & f(x_1, y_1) \vee \\ (x_2 \wedge y_2)) & & // & f(x_2, y_2)) \end{array}$$

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$\varphi \stackrel{\text{def}}{=} \neg \mathbf{F}(x \wedge y)$,

1. Write a Boolean formula whose solutions (if any) represent executions of M of length 2 which violate φ .

[Solution: The question corresponds to the Bounded Model Checking problem

$M \models_2 \mathbf{E F}f$, s.t. $f(x, y) \stackrel{\text{def}}{=} (x \wedge y)$. Thus we have:

$$\begin{array}{llll} \neg x_0 \wedge y_0 & \wedge & // & I(x_0, y_0) \wedge \\ (x_1 \leftrightarrow (x_0 \leftrightarrow \neg y_0)) \wedge (y_1 \leftrightarrow \neg y_0) & \wedge & // & T(x_0, y_0, x_1, y_1) \wedge \\ (x_2 \leftrightarrow (x_1 \leftrightarrow \neg y_1)) \wedge (y_2 \leftrightarrow \neg y_1) & \wedge & // & T(x_1, y_1, x_2, y_2) \wedge \\ ((x_0 \wedge y_0) & \vee & // & (f(x_0, y_0) \vee \\ (x_1 \wedge y_1) & \vee & // & f(x_1, y_1) \vee \\ (x_2 \wedge y_2)) & & // & f(x_2, y_2)) \end{array}$$

]

2. Is there a solution? If yes, find the corresponding execution; if no, show why.

Ex: Bounded Model Checking

Given the symbolic representation of a FSM M , expressed in terms of the two

Boolean formulas: $I(x, y) \stackrel{\text{def}}{=} \neg x \wedge y$,

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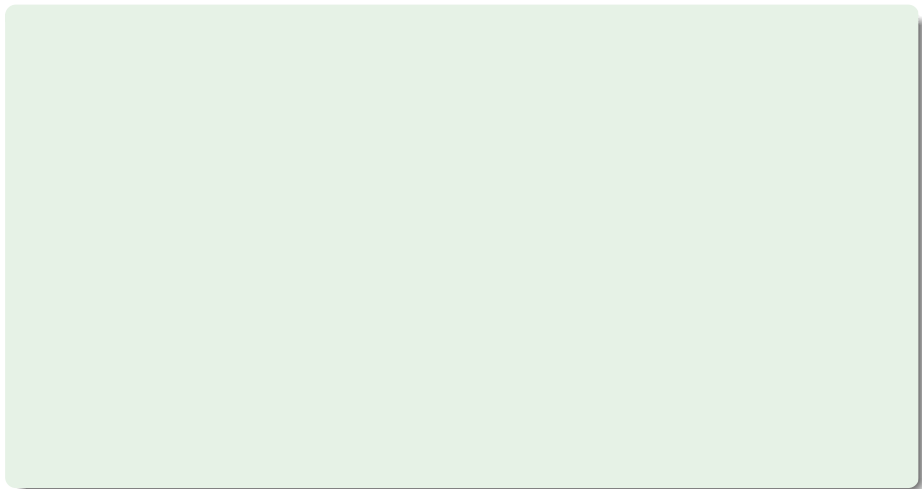
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]

2. Is there a solution? If yes, find the corresponding execution; if no, show why.

[Solution: Yes: $\{\neg x_0, y_0, x_1, \neg y_1, x_2, y_2\}$, corresponding to the execution:
 $(0, 1) \rightarrow (1, 0) \rightarrow (1, 1)$]

Ex: Bounded Model Checking



Ex: Bounded Model Checking

3. From the solutions to question #1 and #2 we can conclude that:

(a) $M \models \varphi$

(b) $M \not\models \varphi$

(c) we can conclude nothing.

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4. What are the diameter and the recurrence diameter of this system?

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[Solution:

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Ex: Bounded Model Checking

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[Solution: b)]

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[Solution:

