# Profile Hidden Markov Models 

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Artificial Intelligence for Bioinformatics

## Profile HMM (Haussler et al., 1993)

## Motivation

- Biological sequences are typically grouped into families with a certain functionality
- A relevant task is that of detecting whether a target sequence belongs to a certain family
- This could be done aligning the sequence to each of the sequences from the family
- However, pairwise alignments alone can miss cases of distantly related sequences
- A better way to detect such relationship would be:
(1) building a model of the family
(2) testing whether the target sequence is compatible with the model


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## Multiple alignments

- A multiple alignment consists of the simultaneous alignment of a set of sequences
- All sequences from a certain family could be aligned to form a multiple alignment representing the family
- The family model should be a compact probabilistic representation of such multiple alignment


## Multiple alignment: example for the globin family



ELTHGGKIFG MKOHGNTMET ERKHGDTVLE IKAQADTVLE VKABGATVLE IKABCEAVAE PEALAMTVEA NGDOREALEN MEKQANLEGI MERQALDEGA IKHPARTLTE VRRHARLETS ENSHTKLLCE ERQHALVYTK ELGLSSTIQA ERSQALKEVG FEKGGTALLE EKKLGNQLL EKKLGSGLIt FDKGGRILL EAKQGQKitL EIKGGQNILL BAABGQALHW


ALGNILKQ . . . . . . KGNHAE
ALGNILKQ . . ....EGGHST
ALGNIVEK . . ....EGGNHSA
ELGELLKA. . ....BgDHAA
EIDQVVENE. .-DHLDNVTG
AAQNIENL. . ....P.AIEP
AIAA YASNI. .-ENLPALLP
MMTQEIDNE. . DDTTALNY
ILQEEVANL. .-NDPTALTL
AIVHMLREI. . -SNDAEDEK
ILhisveñ. DELEAQVap
ELDSEMTDE. .HQPAKIVEA
TLDEVIBNL. - DYPGKEEV
EFGKLIITYE E.-NDDQVRE TLAQVVENIY HMERTESELY
AVHVLANET. .-DNQAVEHG
SVHIAADTY. .-DNEMIERA
SVHILANTE. .-DNEDVERA
ACHLLANVY. . -TNEEVFEGG
ACHDLCATY. .- DDRETENA
ACHOLCATI. - DDEETEDA
MYGELDAQ-B ...AEEP有A

NLQSMapLhy
VLKPLAKSHA NVKELADTHI PQKALAATHI IEKPLATTHA ELMRIGRDHA AVKKIADKHC ADEKIAQKHT KISGLMATHE KIRGLCATHE IAAQ GKDHT TVEKYGERH KCODVGAAHE MEENLGERHE ACEQLGARHD MVGQKHVKEA FVRELMNBHE EVRDTIDRA CRETIDRHV vgRETINRHB ptrelldrha PGGEMARHE ELAQLGRDHB
$\square$
$\square$
or
$\frac{1}{8}$
8
T
$\stackrel{T}{T}$
I
S!
B.
N
A
B
$\square$
D K
$\square$
$\qquad$
G
$\square$

## Profile HMM

## Dealing with ungapped regions

- Large portions of multiple alignments for a protein family consist of ungapped sequences of residues
- Each position in such regions has a certain amino-acid profile, representing the frequencies with which each amino-acid occurs in the column of the alignment
- By normalizing such profiles, it is possible to derive a probability of observing a certain residue in that position.


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Probabilistic model for ungapped regions

- Each position in the region can be modelled with a match state with position specific emission probabilities
- The whole region can be modelled as a sequence of match states, with transitions only between successive states
- Beginning and end of the region can be modelled with special non-emitting begin and end states


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## Dealing with gaps

- Gaps in the alignment tend to occur at certain positions (i.e. gaps align columnwise)
- Gaps can be dealt with by modelling the two type of corresponding modifications:
- insertions of a sequence of residues
- deletions of a sequence of residues


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Probabilistic model with insertions

- An insertion should be modelled with a specific insertion state I (represented as a diamond)
- As insertions in different positions have different probabilities, transition probabilities should be position specific
- An insertion state should also have a self transition to account for insertions of sequences of residues
- Emission probabilities could instead be set for all insertion states equal to the background probability $q_{a}$ of observing a certain amino-acid a in an arbitrary sequence.


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## Probabilistic model with deletions

- Deletions should be modelled as special silent states $D$ which do not emit symbols (represented as a square)
- Allowing self transitions as in insertions would complicate inference algorithms
- Sequences of deletions are instead modelled as sequences of deletion states
- This also allows to specify different transition probabilities between deletion states



## Note

- We allow direct transitions between insertion and deletion states
- These situations are quite rare, but leaving such transitions out would give zero probability to these cases


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## Parameter estimation

- We assume a multiple alignment profile for the family of interest is available (created with multiple alignment algorithms, possibly relying on 3D information)
- We need to estimate transition probabilities between states, and emission probabilities for match states (those for insertion states are set to background probabilities for arbitrary sequences)
- We first decide which positions in the alignment correspond to match states, and which to insertions or deletions:
- A reasonable approach is that if half of the column elements in a position are gaps, the position is not a match state
- This allows to turn our alignment in a fully observed set of training examples: probabilities can be estimated from counts


## Profile HMM

$$
\begin{aligned}
& \text { HBA_HUMAN ...VGA--HAGEY... } \\
& \text { HBB_HUMAN ...V----NVDEV... } \\
& \text { MYG_PHYCA ...VEA--DVAGH... } \\
& \text { GLB3_CHITP ...VK G------D. . . } \\
& \text { GLB5_PETMA ...VYS--TYETS... } \\
& \text { LGB2_LUPLU ....FNA--NIPKH... } \\
& \text { GLB1_GLYDI . . . IA GADNGAGV . . . }
\end{aligned}
$$

match
insertion
deletion

## Parameter estimation: examples

- Non-zero emission probabilities for match state $M_{3}$ :

$$
e_{M_{3}}(V)=5 / 7 \quad e_{M_{3}}(F)=1 / 7 \quad e_{M_{3}}(I)=1 / 7
$$

- Non-zero transition probabilities from match state $M_{3}$ :

$$
a_{M_{3} M_{4}}=6 / 7 \quad a_{M_{3} D_{4}}=1 / 7
$$

- Non-zero transition probabilities from match state $M_{5}$ :

$$
a_{M_{5} M_{6}}=5 / 7 \quad a_{M_{5} / 5}=1 / 7 \quad a_{M_{5} D_{6}}=1 / 7
$$

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## Parameter estimation: adding pseudocounts

- All transitions and emissions never observed in the multiple alignment will be set to zero using only counts.
- This can be a problem if an unsufficient number of examples is available (i.e. always)
- A simple solution consists of adding a non-zero prior probability for any transition or emission, to be combined to the counts observed on data
- Such prior probability can be thought of coming from pseudocounts of hypothetical observations of emissions/transitions
- The simplest pseudocount (Laplace smoother) consists of adding a single hypothetical observation of any possible emission/transition

