

# CNN-aware Binary Map for General Semantic Segmentation

Mahdyar Ravanbakhsh, Hossein Mousavi, Moin Nabi, Mohammad Rastegari, Carlo Regazzoni



September 2016

# Low-level Segmentation VS. Semantic Segmentation



## Low-level Segmentation

Partitioning an image based on the low-level image features:

- Graph-based approaches (e.g, EGS [1])
- Gradient-ascent-based approaches (e.g., SLIC [2])

**Problems:** Lack of semantic, not invariant to illumination and occlusion.

## Semantic Segmentation

Partitioning a scene into semantic regions and a unique object label is assigned to each region:

- Supervised Fully Convolutional Neural Network[3].

**Problems:** Supervision is biased, non-comprehensive, and not scalable.

[1] Felzenszwalb, P. F. and Huttenlocher, D. P., "Efficient graph-based image segmentation", IJCV 2004.  
 [2] Achanta, R. et al., "SLIC superpixels compared to state-of-the-art superpixel methods", PAMI 2012.  
 [3] Long, J., Shelhamer, E. and Darrell, T., "Fully convolutional networks for semantic segmentation". CVPR 2015.

# General Semantic Segmentation



## General Semantic Segmentation

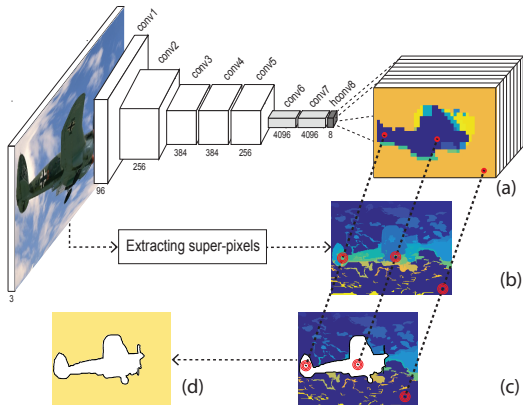
**Goal:** Narrow down the semantic gap between low-level segmentation and semantic segmentation

**By:** Inject semantics into general segmentation, while maintaining the method complexity in a manageable level.

# Overview

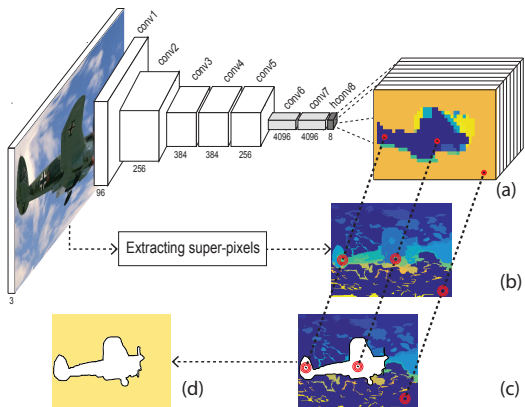
## General Idea

The nearby pixels should have similar *visual attributes* unless they undergo a large semantic change. We proposed a **Binary Convolutional Neural Network** which provide the means to represent the visual attributes as the binary patterns.



# Overview

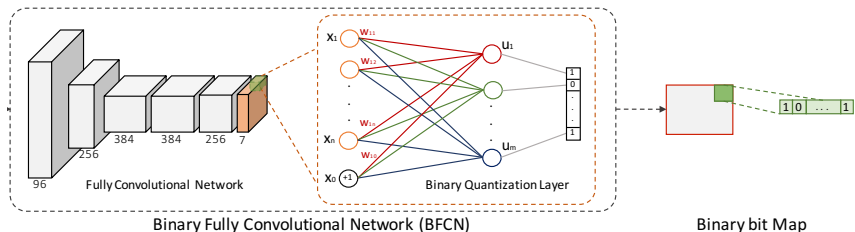
- Given input image to a Fully Convolutional Neural Network (FCN) obtaining a CNN feature map.
- Generate compact binary representation of the CNN features maps through the Binary Encoding Layer.
- Refine the binary bit maps by averaging over superpixels.
- Partition the image by merging the superpixels with the similar binary pattern.



# Binary Quantization Layer

**Strength:** Compact binary representation instead of high-dimensional CNN features, Efficient partitioning with hashing layer for training the network in an end-to-end fashion.

**Binary Encoding:** Binarizing CNN feature maps by a linear transformation where the weights are initialized with Locality Sensitive Hashing (LSH).

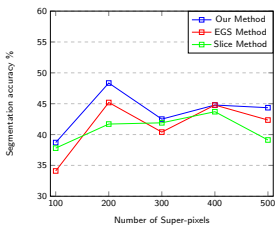


# Results

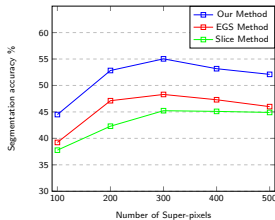
## Quantitative results on MSRC and Berkeley datasets

MSRC		Berkeley	
Method	IoU	Method	IoU
EGS [1]	50.3%	EGS [1]	45.19%
SLIC [2]	48.7%	SLIC [2]	43.70%
<b>Our method</b>	<b>55.03 %</b>	<b>Our method</b>	<b>48.35%</b>

## Segmentation-IoU over superpixel variation



(a) Berkeley

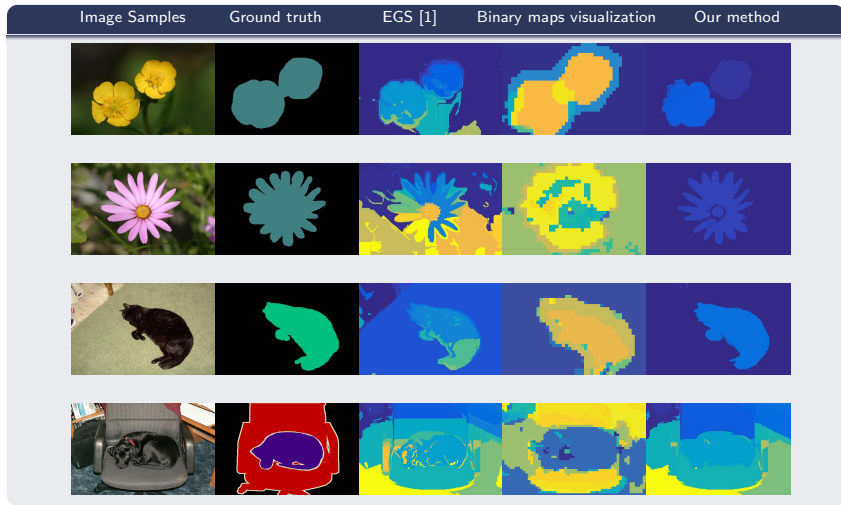


(b) MSRC

[1] Felzenszwalb, P. F. and Huttenlocher, D. P., "Efficient graph-based image segmentation", IJCV 2004.

[2] Achanta, R. et al., "SLIC superpixels compared to state-of-the-art superpixel methods", PAMI 2012.

# Results



[1] Felzenszwalb, P. F. and Huttenlocher, D. P., "Efficient graph-based image segmentation", IJCV 2004.