Formal Verification of Requirements using SPIN: A case Study on Web Services

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Introduction

- Integration of distributed business process is an emerging problem...
 - participants from different organizations
 - heterogeneity among services
 - autonomous evolution of processes
- **Description** Web Services (WS) offer the technology for business process integration:
 - languages for WS interoperability (SOAP, WSDL, UDDI,...)
 - In particular BPEL4WS (Business Process Execution Language)
 - tools for the design and the execution of WS
- Nevertheless, there is a need for advanced techniques for supporting the most complex aspects of business process integration:

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- simulation and (formal) verification
- monitoring and diagnosis
- (automated) support for composition and evolution

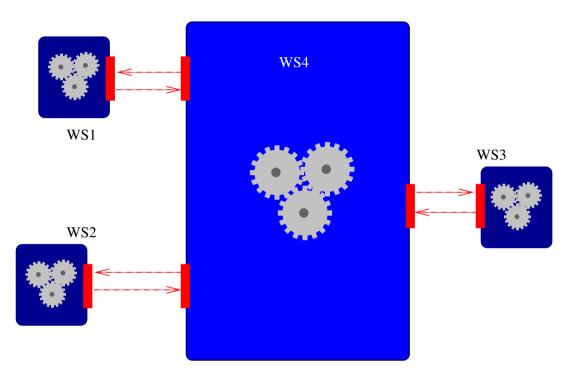


Outline

- Introduction to WS and related problems
- The need for business requirements
- A methodology for defining business requirements and for deriving executable code
- Verification of Business Requirements/Processes
- The tool supporting the methodology using SPIN
- Some experimental results
- Conclusions and Future works



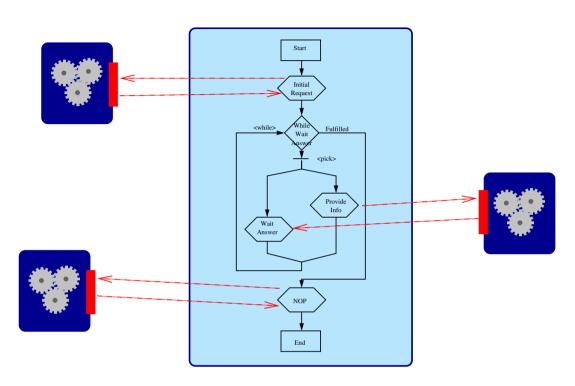
Web Services



Several web services participate to a business interaction.



WS: Executable Processes...

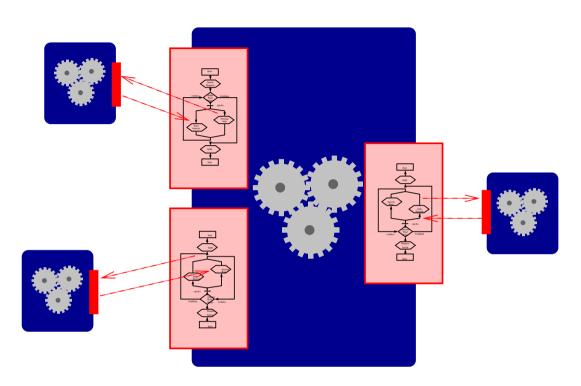


- WS languages (BPEL4WS) offers a set of core concepts for process description that can be used for:
 - the definition and the execution of the internal business process of a participant to a business interaction.



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WS: ... and Interaction Protocols



- WS languages (e.g. BPEL4WS) offers a set of core concepts for process description that can be used for:
 - the definition and the execution of the internal business process of a participant to a business interaction.
 - the description and publication of the external business protocol that define the interaction behavior of a participant.



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- At design time:
 - Is the internal BPEL4WS process specification **consistent** with the published protocol interfaces?
 - Given two or more BPEL4WS interfaces aiming to communicate, do they define a correct (e.g., **deadlock free**) protocol?



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At execution time:

• Do the other participants respect the protocol interface that they have published?

In order to do advanced verification based on specific properties on the behavior, a requirements language is needed.

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 - focus on early phases of requirements analysis, aiming to the understanding of the operational environment of the software system



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- Tropos has been applied in several case studies on information systems and agent-based software systems



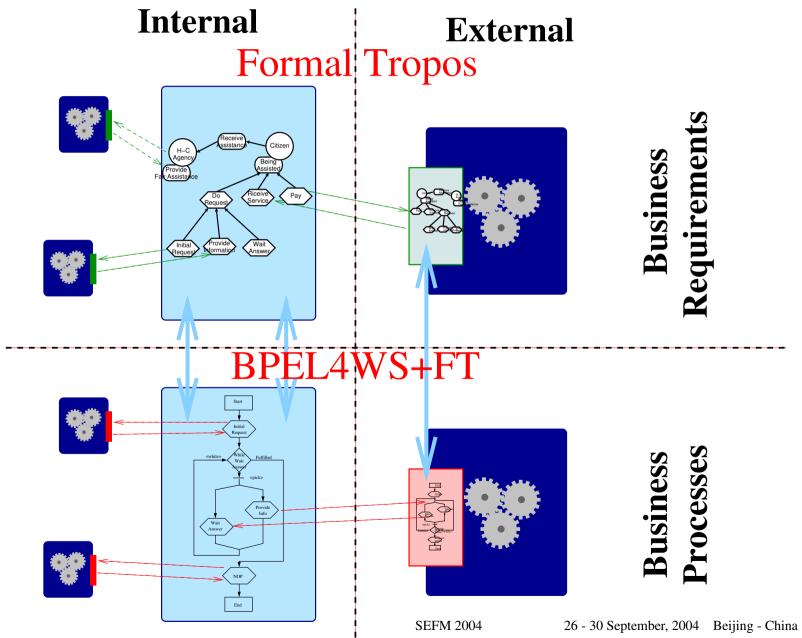
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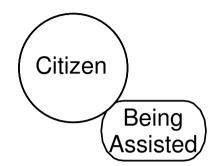
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- Formal Tropos extends Tropos with a formal specification language and with verification based on Model Checking



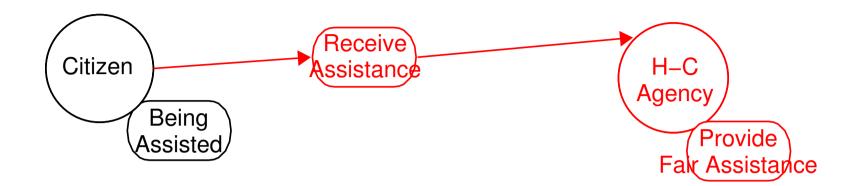
Proposed methodology: Tropos4WS



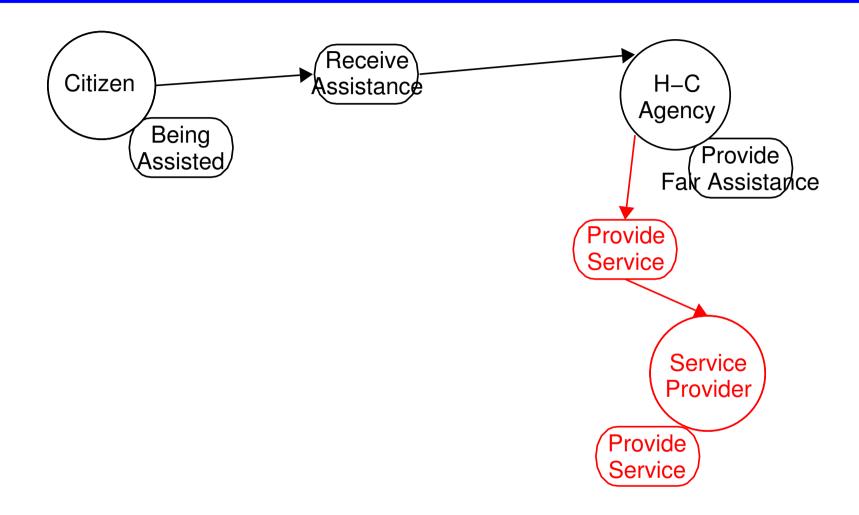




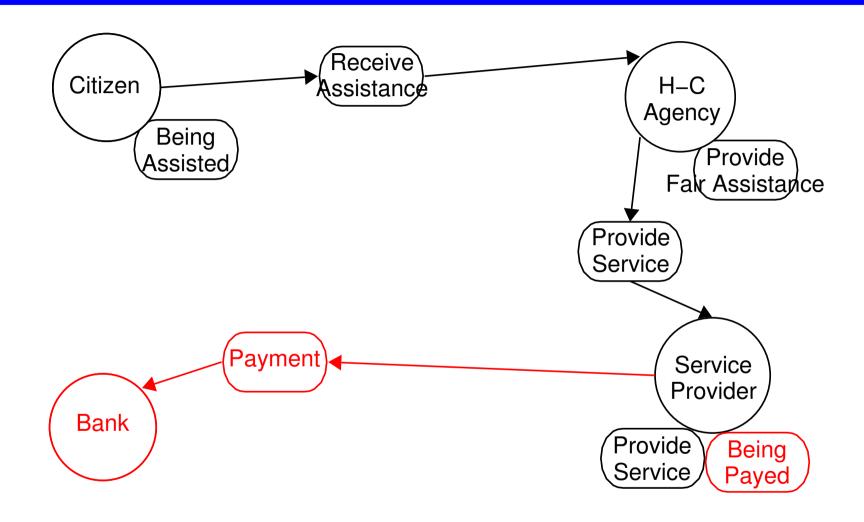






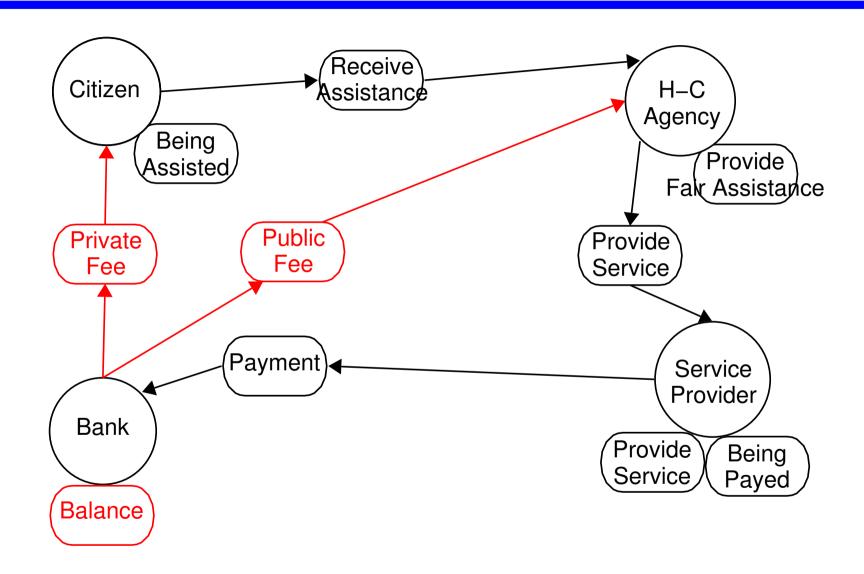




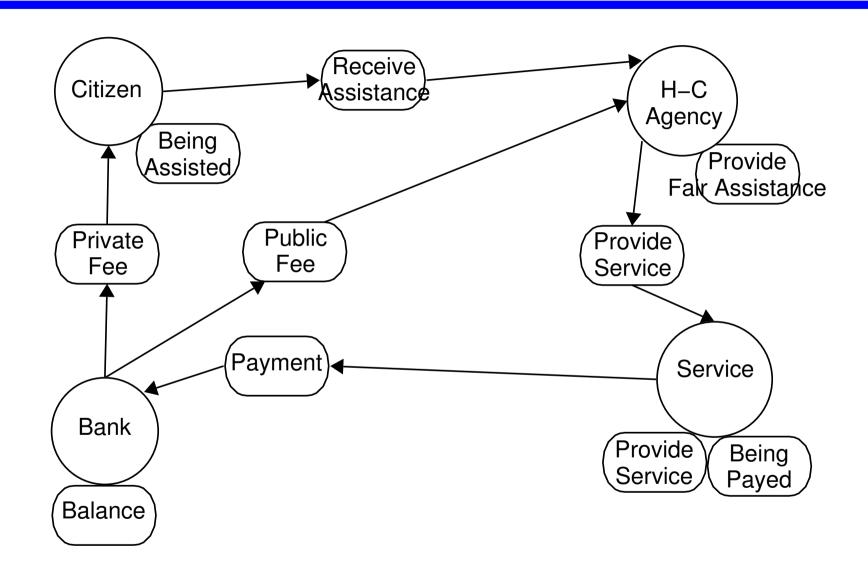


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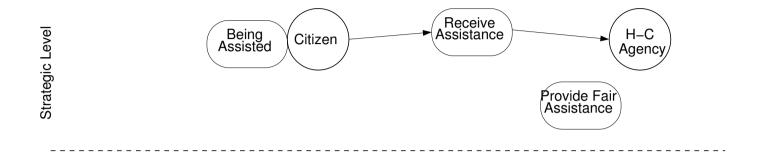




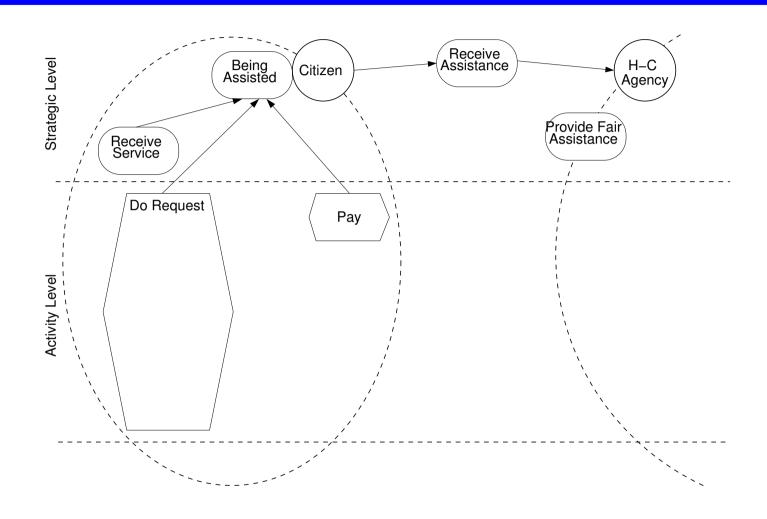




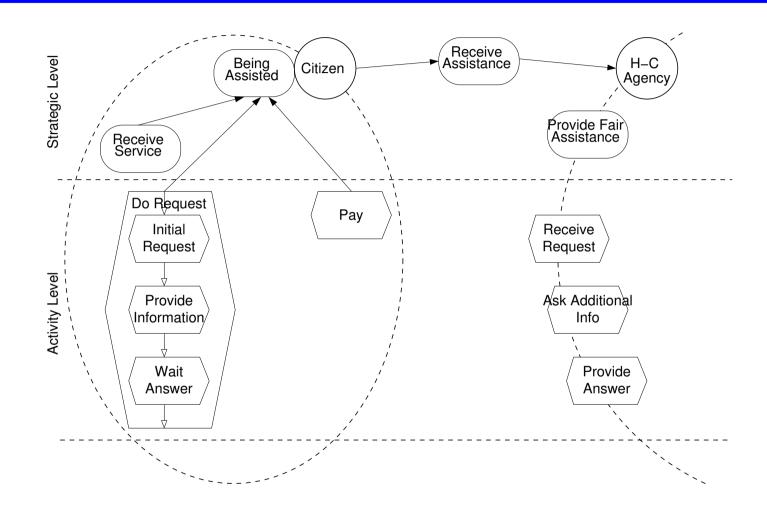




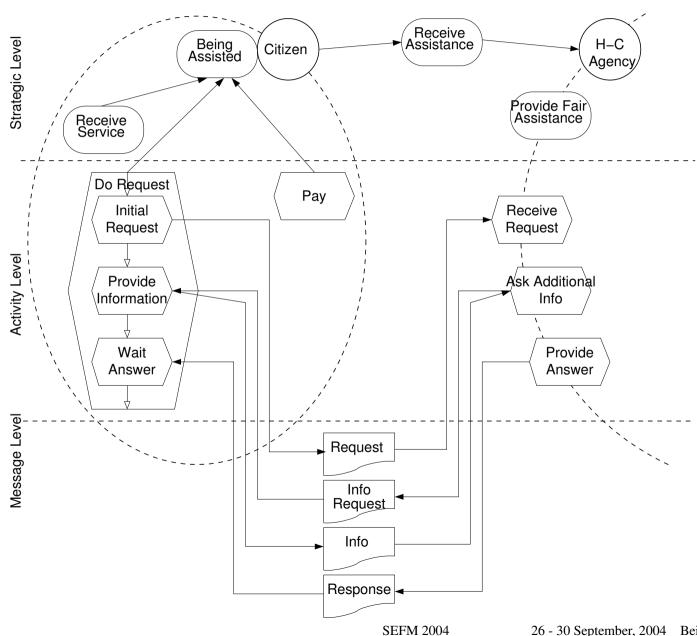












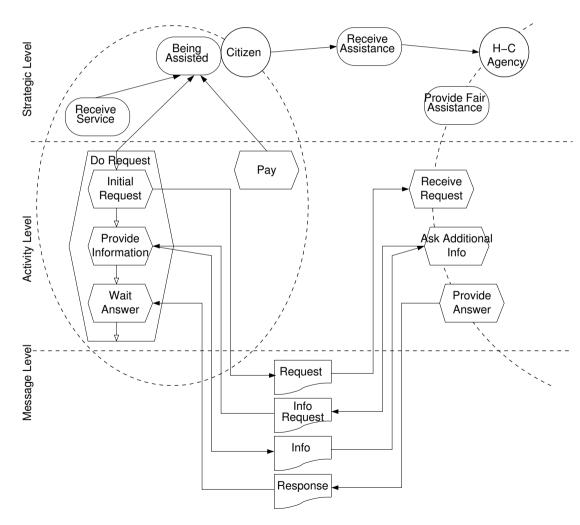


Formal Tropos

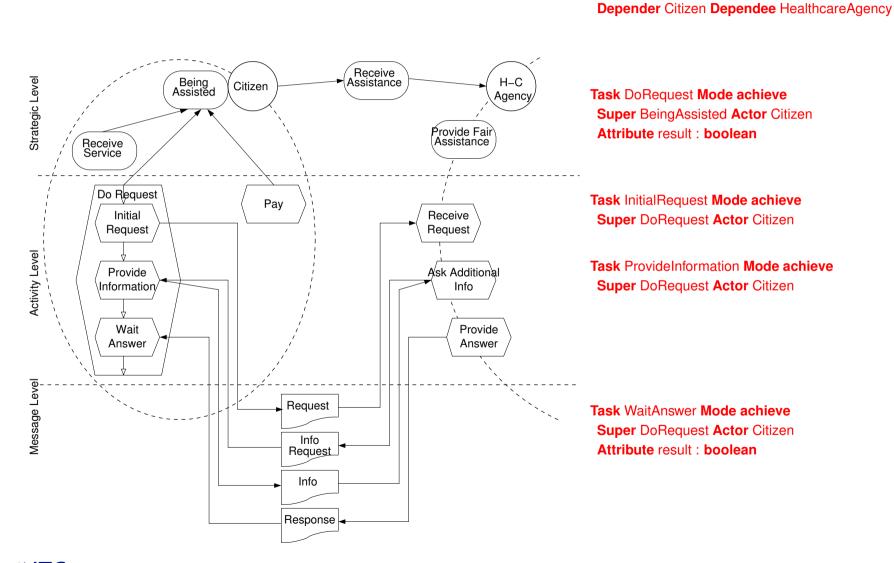
Formal Tropos:

- first-order linear-time temporal constraints on the evolutions of the model:
 - (past and future) temporal operators: $\mathbf{G}\phi$, $\mathbf{F}\phi$, $\mathbf{H}\phi$, $\mathbf{O}\phi$...
 - quantification on class instances: $\forall c : C..., \exists c : C...$
- focus on **creation** and **fulfillment** of activities:
 - FT can describe the **state diagram** defining the behavior of services
 - ▶ FT can describe the **activity diagram** defining the interaction of services



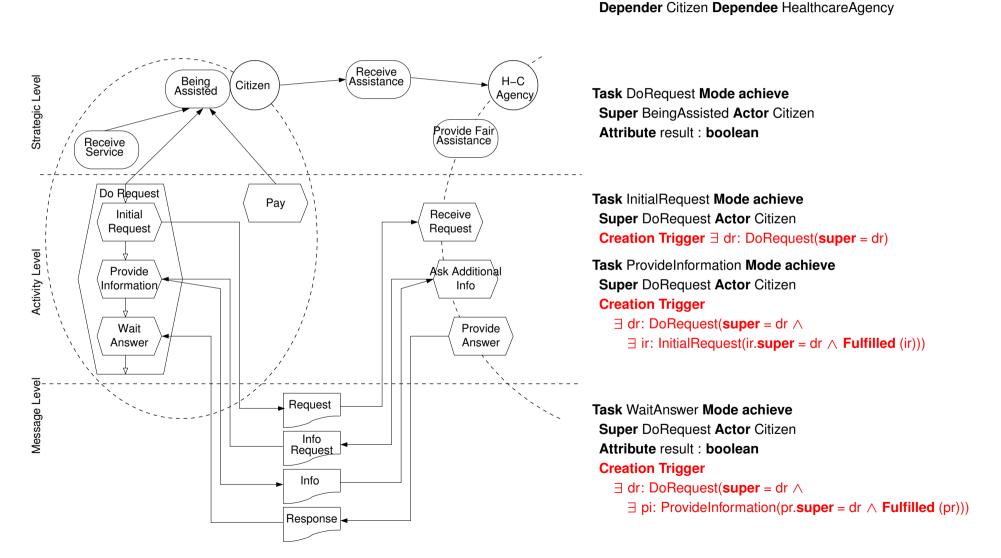






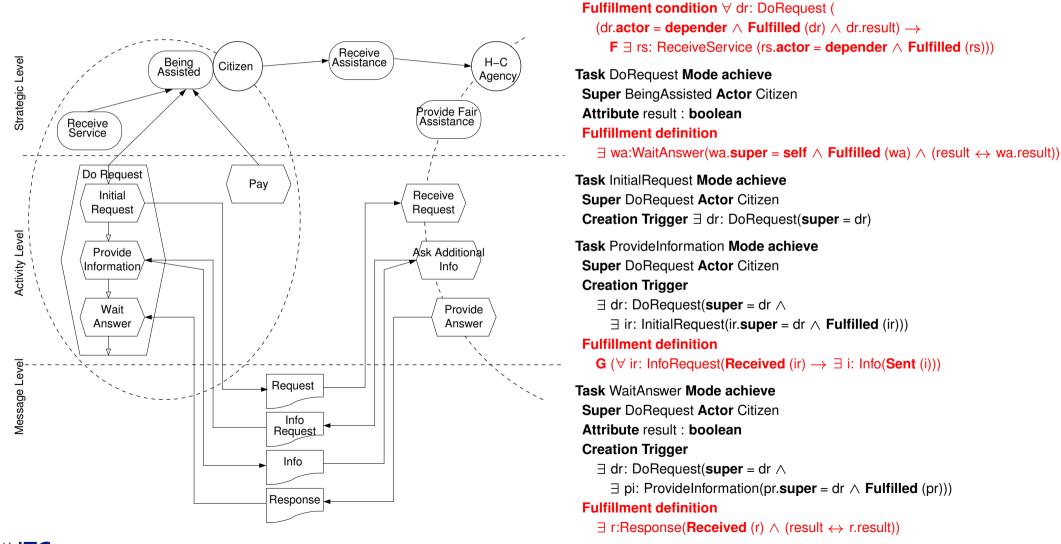


Goal Dependency ReceiveAssistance Mode maintain





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Depender Citizen Dependee HealthcareAgency

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Possibility P1 /* It is possible to fulfill request */
∃ dr: DoRequest (Fulfilled (dr))



Formal Analysis of Requirements

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Formal Analysis of Requirements

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Implementing Business Requirements in Promela

```
Task DoReguest Mode achieve
 Super BeingAssisted Actor Citizen
 Attribute result : boolean
 Fulfillment definition
    \exists wa:WaitAnswer(wa.super = self \land Fulfilled (wa) \land
      (result \leftrightarrow wa.result))
Task InitialRequest Mode achieve
 Super DoRequest Actor Citizen
 Creation Trigger ∃ dr: DoReguest(super = dr)
Task ProvideInformation Mode achieve
 Super DoRequest Actor Citizen
 Creation Trigger
   \exists dr: DoRequest(super = dr \land
      \exists ir: InitialRequest(ir.super = dr \land Fulfilled (ir)))
 Fulfillment definition
   G (\forall ir: InfoReguest(Received (ir) \rightarrow \exists i: Info(Sent (i)))
Task WaitAnswer Mode achieve
 Super DoRequest Actor Citizen
 Attribute result : boolean
 Creation Trigger
   \exists dr: DoRequest(super = dr \land
      \exists pi: ProvideInformation(pr.super = dr \land Fulfilled (pr)))
 Fulfillment definition
    \exists r:Response(Received (r) \land (result \leftrightarrow r.result))
```

DoRequest process specification in Promela

```
bool waitResponse;
atomic{
 CREATE ri: InitialRequest;
 ri.super = self;
 waitResponse = true};
at.omic{
 CREATEMESSAGE vRequest: Request;
 Request_channel ! vRequest};
atomic{
 FULFILL ir: InitialRequest [ir.super == self];
 CREATE pi: ProvideInformation; pi.super = self};
do::atomic{ waitResponse ->
    if::InfoRequest channel ? vInfoRequest;
        CREATEMESSAGE vinfo: Info:
        vInfo.reference = vInfoReguest;
        Info_channel ! vInfo;
      :: Response_channel ? vResponse;
        FULFILL pi: ProvideInformation [pi.super==self];
        CREATE wa: WaitAnswer; wa.super = self;
        waitResponse = false;
        self.result = vResponse.result;
    fi};
  ::else break;
od;
atomic{
 FULFILL wait: WaitAnswer [wait.super == self];
 FULFILL self);
```



Implementing Business Requirements in BPEL4WS

```
Task DoReguest Mode achieve
 Super BeingAssisted Actor Citizen
 Attribute result : boolean
 Fulfillment definition
    \exists wa:WaitAnswer(wa.super = self \land Fulfilled (wa) \land
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   \exists dr: DoRequest(super = dr \land
      \exists pi: ProvideInformation(pr.super = dr \land Fulfilled (pr)))
 Fulfillment definition
   \exists r:Response(Received (r) \land (result \leftrightarrow r.result))
```

```
<sequence name="DoReguestBody">
  <assign name="Initialization"</pre>
    event="Create ir: InitialRequest (ir. super=self) ">
    <copy> <from expression="true()"/><to variable="waitResponse"/> </copy>
  </assign>
  <invoke operation="oRequest" inputVariable="vRequest"/>
  <empty name="PhaseSwitch"</pre>
   event="Fulfill ir:InitialRequest(ir.super=self) &
           Create pi:ProvideInformation(pi.super=self)"/>
  <while condition="getVariableData('waitResponse')">
    <pick name="WaitMessage">
      <onMessage operation="oInfoRequest" variable="vInfoRequest">
        <reply operation="oInfo" variable="vInfo"/>
      </onMessage>
      <onMessage operation="oResponse" variable="vResponse"</pre>
        event="Fulfill pi:ProvideInformation(pi.super=self) &
               Create wa:WaitAnswer(wa.super=self)">
        <assign name="LeaveLoop">
          <copy> <from expression="false()"/><to variable="waitResponse"/> </copy>
          <copy> <from variable="vResponse" part="result"/><to variable="result"/>
        </assign>
      </onMessage>
    </pick>
  </while>
  <empty name="DoRequestFulfilled"</pre>
    event="Fulfill wa:WaitAnswer(wa.super=self)"
    constraint="Forall wa:WaitAnswer(wa.super=self \rightarrow
                G(wa.result ↔ self.result))"/>
</sequence>
```



Task DoRequest

Actor Citizen

Super BeingAssisted

Attribute result : boolean



Task DoRequest **Actor** Citizen Super BeingAssisted Attribute result : boolean

```
typedef DoRequestType{
  byte actor;
  byte super;
  bool result;
```

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Task DoRequest
Actor Citizen
Super BeingAssisted
Attribute result: boolean

```
typedef DoRequestType{
   byte actor;
   byte super;
   bool result;
   bool justcreated, exists;
   bool justfulfilled, fulfilled;
}
DoRequestType DoRequest[2];
```



Task DoRequest
Actor Citizen
Super BeingAssisted
Attribute result: boolean

```
typedef DoRequestType{
  byte actor;
  byte super;
  bool result;
  bool justcreated, exists;
  bool justfulfilled, fulfilled;
DoRequestType DoRequest[2];
proctype DoRequestProc(byte id) {
.../* life cycle of class instance */
.../* encoded as a Promela process */
```



proctype ClassProc(byte id) {

The life-cycle of a Class instance:

}



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The life-cycle of a Class instance:

- NotExists: The initial status of class instances (only for actors).
 - It can stay in this state or go to next state.
 - Transition to next state only if conditions for creation hold.



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- NotExists: The initial status of class instances (only for actors).
 - It can stay in this state or go to next state.
 - Transition to next state only if conditions for creation hold.
- **Exists**: The class instance exists.
 - It can stay in this state or go to next state.



```
proctype ClassProc(byte id) {
  NotExists:
     do
        /* Initial status for class instance */
     od
  Exists:
     do
        /* start child sub classes */
     od
  Fulfilled:
     do
        /* stay here forever */
     od
```

The life-cycle of a Class instance:

- NotExists: The initial status of class instances (only for actors).
 - It can stay in this state or go to next state.
 - Transition to next state only if conditions for creation hold.
- **Exists**: The class instance exists.
 - It can stay in this state or go to next state.
- **Fulfilled**: The class instance is fulfilled (only for tasks, goals, dep.)
 - It stay in this state.

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```
proctype DoRequestProc(byte id) {
Exists:
  do :: atomic /* if the child subtask is not started yet,
               assign relevant attributes and start it */
        \{(!InitialRequest[0].exists) \rightarrow system_step();
         InitialRequest[0].super = id;
         InitialRequest[0].actor = DoRequest[id].actor;
         InitialRequest[0].exists = true;
         InitialRequest[0].justcreated = true;
         run InitialRequestProc(0);};
      .../* other child subtask may be started here */
     :: atomic /* Modify non-constant attributes */
        {system_step();
         if :: DoRequest[id].result = true;
           :: DoRequest[id].result = false;
         fi; /* The instance is fulfilled nondeterministically */
         if :: DoRequest[id].fulfilled = false;
           :: DoRequest[id].fulfilled = true;
             DoRequest[id].justfulfilled = true; goto Fulfilled;
         fi; }
  od:
```

The DoRequestProc instance: Exists

- Transition from **NotExists** to **Exists** only if conditions hold.
 - Class attributes initialized.
 - justcreated and exists set to true.
- Class can nondeterministically create child goals, tasks, dependencies, ...
 - Child attributes are initialized.
 - Child corresponding processes started.
 - In this phase the process nondeterministically modifies values of nonconstant attributes.



```
proctype DoRequestProc(byte id) {
Exists:
    :: atomic /* Modify non-constant attributes */
       {system_step();
       if :: DoRequest[id].result = true;
          :: DoRequest[id].result = false;
       fi; /* The instance is fulfilled nondeterministically */
        if :: DoRequest[id].fulfilled = false;
          :: DoRequest[id].fulfilled = true;
            DoRequest[id].justfulfilled = true; goto Fulfilled;
        fi; }
 od:
Fulfilled:
 do :: atomic /* Modify non-constant attributes */
       {system_step();
        if :: DoRequest[id].result = true;
          :: DoRequest[id].result = false;
       fi;}
 od;
```

The DoRequestProc instance: Fulfilled

- Transition from Exists to Fulfilled nondeterministic.
 - justfulfilled and fulfilled set to true.
- In this phase the process nondeterministically modifies values of nonconstant attributes.

Encoding Formal Tropos in Promela: Remarks

```
proctype DoRequestProc(byte id) {
Exists:
  do :: atomic
         /* if the child subtask is not started yet,
          assign relevant attributes and start it */
        \{(!InitialRequest[0].exists) \rightarrow system\_step();
      :: atomic /* Modify non-constant attributes */
        {system_step();
  od:
Fulfilled:
  do :: atomic /* Modify non-constant attributes */
        {system_step();
           od:
```

- All transitions from life-cycles performed within an **atomic** statement to preserve FT semantics.
- system_step() invoked each time a process performs a step.
 - reset all attributes justcreated and justfulfilled.
 - other activities related to the verification

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FT logic specifications C_i (creation, invariant, fulfillment constraints) exploited to verify assertions and possibilities.



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- For assertions

$$\bigwedge_{i \in I} C_i \to A$$

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must be valid



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For possibilities

$$\bigwedge_{i \in I} C_i \wedge P$$

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must be satisfiable



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must be satisfiable

Build a *never claim* for the formula to verify and submit it to SPIN.



- \blacksquare FT logic specifications C_i (creation, invariant, fulfillment constraints) exploited to verify assertions and possibilities.
- For assertions

$$\bigwedge_{i \in I} C_i \to A$$

must be valid

For possibilities

$$\bigwedge_{i \in I} C_i \wedge P$$

must be satisfiable

- Build a never claim for the formula to verify and submit it to SPIN.
 - Problem: on small cases the size of the formula prevents possibility to verify the never claim.
 - A reduced FT specification with 3 simple constraints and 5 classes generated a file whose size was not manageable by the C compiler.

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- \blacksquare Encode each FT constraint C_i as a separate automata.
- Generate a new process constraint_verifier() where all automata are executed in parallel.
- Add the constraint_verifier() to the final Promela specification.
- Enforce execution of constraint_verifier() after each system step.
- Restrict the verification to *valid execution paths* i.e. to those execution sequences where all constraints holds.



```
if
                                           /* label[n] preserves position reached at previous step */
                              :: label[n]==0 \rightarrow goto Cn_accept_init
                              :: label[n]==1 \rightarrow goto Cn_T0_S2
                              fi:
/*G(p \rightarrow Fq) */
                             /*G(p \rightarrow Fq) */
                         Cn accept init:
accept init:
  if
                                if
                                :: (\neg p)||q \rightarrow label[n] = 0;
  :: (\neg p)||q \rightarrow
     goto accept_init
                                   accepted[n] = true:
  :: (1) \rightarrow
                                :: (1) \rightarrow label[n] = 1;
     goto TO S2
                                   accepted[n] = false; all_accepted = false;
  fi;
                                fi; goto Cn_checked;
T0 S2:
                              Cn T0 S2:
  if
                                :: q \rightarrow label[n] = 0;
  :: q \rightarrow
     goto accept_init
                                   accepted[n] = true;
  :: (1) \rightarrow
                                :: (1) \rightarrow label[n] = 1;
     goto T0_S2
                                   accepted[n] = false; all accepted = false;
  fi:
                                fi; goto Cn_checked;
                              Cn checked:
```



```
proctype constraint verifier() {
                                                                           inline system step() {
  byte label[n] = 0; bool accepted[n] = false; byte next = 0;
                                                                             if :: constraints done \rightarrow constraints done = false;
  do :: constraints done \rightarrow break;
                                                                                :: else valid step = false;
     :: else atomic
                                                                             fi:
        {all_accepted = true; valid_step = false;
                                                                             next accepted = false;
         ... /* All constraints automata go here */
                                                                             ... /* Reset justcreated and justfulfilled flags */
         valid step = true; constraints done = true;
                                                                             DoRequest[0].justcreated = false;
         if :: accepted[next] \rightarrow /* Look for acceptance again */
                                                                             DoRequest[0].justfulfilled = false;
              next\_accepted = true; next = (next+1) \% n;
           :: else
         fi:}
  od;}
```

constraints_done is set to true each time process constraint_verifier() evolves, to false each time the system_step() evolves.



```
proctype constraint verifier() {
                                                                           inline system step() {
  byte label[n] = 0; bool accepted[n] = false; byte next = 0;
                                                                             if :: constraints done \rightarrow constraints done = false;
  do :: constraints done \rightarrow break;
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     :: else atomic
                                                                             fi:
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         valid step = true; constraints done = true;
                                                                             DoRequest[0].justcreated = false;
         if :: accepted[next] \rightarrow /* Look for acceptance again */
                                                                             DoRequest[0].justfulfilled = false;
              next accepted = true; next = (next+1) \% n;
           :: else
         fi:}
  od;}
```

valid_step is true if each system step is followed by exactly one step of process constraint_verifier() and if the execution is not blocked.



```
proctype constraint verifier() {
                                                                           inline system step() {
  byte label[n] = 0; bool accepted[n] = false; byte next = 0;
                                                                             if :: constraints done \rightarrow constraints done = false;
  do :: constraints done \rightarrow break;
                                                                                :: else valid step = false;
     :: else atomic
                                                                             fi:
        {all_accepted = true; valid_step = false;
                                                                             next accepted = false;
         ... /* All constraints automata go here */
                                                                             ... /* Reset justcreated and justfulfilled flags */
         valid step = true; constraints done = true;
                                                                             DoRequest[0].justcreated = false;
         if :: accepted[next] \rightarrow /* Look for acceptance again */
                                                                             DoRequest[0].justfulfilled = false;
              next accepted = true; next = (next+1) \% n;
           :: else
         fi:}
  od;}
```

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all_accepted store information whether all automata are visiting an acceptance state simultaneously.

```
proctype constraint verifier() {
                                                                           inline system step() {
  byte label[n] = 0; bool accepted[n] = false; byte next = 0;
                                                                             if :: constraints done \rightarrow constraints done = false;
  do :: constraints done \rightarrow break;
                                                                                :: else valid step = false;
     :: else atomic
                                                                             fi:
        {all_accepted = true; valid_step = false;
                                                                             next accepted = false;
         ... /* All constraints automata go here */
                                                                             ... /* Reset justcreated and justfulfilled flags */
         valid step = true; constraints done = true;
                                                                             DoRequest[0].justcreated = false;
         if :: accepted[next] \rightarrow /* Look for acceptance again */
                                                                             DoRequest[0].justfulfilled = false;
              next accepted = true; next = (next+1) \% n;
           :: else
         fi:}
  od;}
```

next_accepted is set to true if accepted[next] is set to true. It is used to check that all constraint automata visit acceptance states.

```
proctype constraint verifier() {
                                                                           inline system step() {
  byte label[n] = 0; bool accepted[n] = false; byte next = 0;
                                                                             if :: constraints done \rightarrow constraints done = false;
  do :: constraints done \rightarrow break;
                                                                                :: else valid step = false;
     :: else atomic
                                                                             fi:
        {all_accepted = true; valid_step = false;
                                                                             next accepted = false;
         ... /* All constraints automata go here */
                                                                              ... /* Reset justcreated and justfulfilled flags */
         valid step = true; constraints done = true;
                                                                             DoRequest[0].justcreated = false;
         if :: accepted[next] \rightarrow /* Look for acceptance again */
                                                                             DoRequest[0].justfulfilled = false;
              next\_accepted = true; next = (next+1) \% n;
           :: else
         fi;}
  od;}
```

next is updated such that all constraints are considered in turn.



The restriction of the verification to the valid execution paths is captured by the following formula:

```
\mathbf{G}(\mathtt{valid\_step} \wedge \mathbf{F} \ \mathtt{next\_accepted} \ \land
    G(\text{next\_accepted} \rightarrow G \text{ all\_accepted}))
```

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- It states that...
 - the constraint automata are not blocked,
 - they visit acceptance states infinitely often,
 - if variable next_accepted stay true forever (execution over finite paths) then variable all_accepted will stay true forever.



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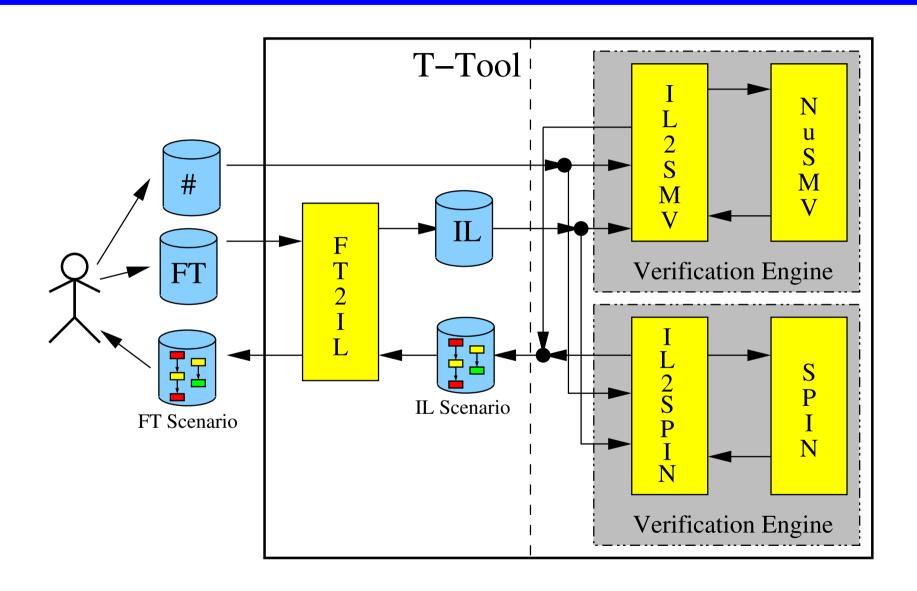
- ullet It checks whether all the valid execution paths satisfy the assertion A.
- lacksquare for a possibility P we verify:

$$\mathbf{G}(\mathtt{valid_step} \land \mathtt{next_accepted} \land \\ \mathbf{G}(\mathtt{next_accepted} \to \mathbf{G} \mathtt{ all_accepted})) \\ \to \neg P$$

• If a counter-example is found for such formula, it is a witness for P.

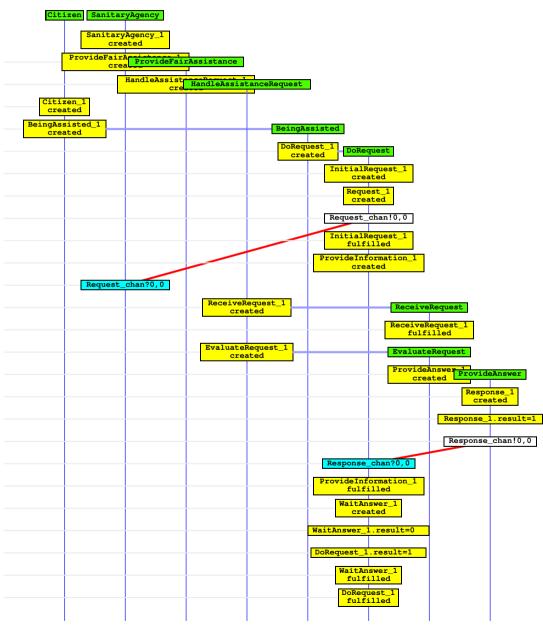


The T-TOOL





A counter-example produced by T-TOOL





Logic specification translation

	Direct Translation		Compositional Translation	
	1 instance	12 instances	1 instance	12 instances
1 constraint	0,01sec	0,01sec	0,01sec	0,01sec
3 constraints	0,03sec	3,01sec	0,03sec	0,09sec
5 constraints	0,11sec	MO	0,04sec	0,14sec
10 constraints	10,65sec	SF	0,04sec	0,16sec
30 constraints	MO	SF	0,07sec	0,20sec
45 constraints	SF	SF	0,15sec	0,41sec



Property verification results

SPIN results					
		1 instance	12 instances		
A1	HC4	TO - 1284steps - 1382Mb	TO - 2857steps - 362Mb		
	BITSTATE	$Valid^{(a)}$ - 21sec - 61Mb	TO - 3244steps - 1028Mb		
	3SPIN	$Valid^{(b)}$ - 23sec - 69Mb	TO - 3207steps - 1178Mb		
A2	HC4	TO - 1393steps - 1382Mb	TO - 2857steps - 362Mb		
	BITSTATE	Invalid - 21sec - 52Mb	TO - 3244steps - 1058Mb		
	3SPIN	Invalid - 24sec - 64Mb	TO - 3417steps - 1173Mb		
P1	HC4	Valid - 27sec - 68Mb	TO - 2857steps - 362Mb		
	BITSTATE	Valid - 14sec - 41Mb	TO - 3099steps - 956Mb		
	3SPIN	Valid - 19sec - 56Mb	TO - 3312steps - 1143Mb		

Hash factors: (a) 1.97 – (b) 3.35



Property verification results

NUSMV results					
		1 instance	12 instances		
A1	BDD	Valid - 9sec - 6,0Mb	TO - 235Mb		
	BMC	Undec.(*) - 7sec - 20,4Mb	Undec.(*) - 106sec - 61,2Mb		
A2	BDD	Invalid - 11sec - 6,9Mb	TO - 235Mb		
	BMC	Invalid - 0,6sec - 3,8Mb	Invalid - 2sec - 11,3Mb		
P1	BDD	Valid - 10sec - 5,8Mb	TO - 235Mb		
	BMC	Valid ^(**) - 0,7sec - 5,3Mb	Valid ^(**) - 2sec - 16,0Mb		

^(*) No counter-example found up to bound length 10



^(**) Found example of length 4 satisfying P1

Implementation verification result

		1 instance	12 instances
A1	HC4	TO - 516steps - 1442Mb	TO - 341steps - 1282Mb
	BITSTATE	$Valid^{(a)}$ - 32sec - 83Mb	Valid ^(b) - 169sec - 316Mb
	3SPIN	$Valid^{(c)}$ - 14sec - 35Mb	$Valid^{(d)}$ - 74sec - 171Mb
A2	HC4	Invalid - 125sec - 206Mb	TO - 341steps - 1162Mb
	BITSTATE	Invalid - 32sec - 71Mb	Invalid - 1285sec - 2003Mb
	3SPIN	Invalid - 15sec - 32Mb	MO - 673steps - 1141sec
P1	HC4	Valid - 2sec - 9,1Mb	TO - 341steps - 1282Mb
	BITSTATE	Valid - 3sec - 10,1Mb	Valid - 167sec - 306Mb
	3SPIN	Valid - 3sec - 12,0Mb	Valid - 59sec - 148Mb
C	HC4	Invalid - 2sec - 9,1Mb	TO - 341steps - 1282Mb
	BITSTATE	Invalid - 3sec - 11,4Mb	Invalid - 166sec - 306Mb
	3SPIN	Invalid - 3sec - 12,0Mb	Invalid - 62sec - 151Mb

Hash factors: (a) 2.44 – (b) 1.66 – (c) 6.06 – (d) 1.61



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- We have proposed a novel, compositional encoding of the LTL constraints that define the valid behaviors of the requirements model in the verification tasks.
- The preliminary experiments show that the approach is viable, even if the performance is currently a rather serious limit for its applicability.
- Future work
 - Optimize the model generator by integrating advanced abstraction techniques that exploit, for instance, possible symmetries in the specification.
 - Deeper investigation of the compositional approach for the verification of complex LTL specifications.



The End

