

Real-Time in the Real World

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From Theory...

❖ From Theory...

- ❖ ...To Practice
- ❖ The WCET
- ❖ Sensitivity Analysis
- ❖ Reservation-Based Scheduling
- ❖ Implementing Temporal Protection
- ❖ Aperiodic Servers
- ❖ Multiprocessor Scheduling

- Real-time system: $\{\tau_i\}$
 - ❖ $\tau_i : (C_i, T_i)$
 - ❖ Independent tasks
 - ❖ Periodic tasks, $D_i = T_i$
 - ❖ WCET???
- Theoretical schedule: function $t \rightarrow \tau_i$
- 1 CPU

...To Practice

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- Real-time system: $\{\tau_i\}, \{S_k\}$
- $\tau_i : (C_i, D_i, T_i)$
- Sporadic Tasks
 - ❖ Minimum Inter-Arrival Time???
- Still do be solved:
 - ❖ Do something about WCET and MIT knowledge
 - ❖ Scheduling for more than 1 CPU (example: SMP or multicore)
 - ❖ Take OS overhead (and practical issues) into account

The WCET

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- Schedulability analysis is based on the WCET
- But... How can I know it?
 - ❖ Today, my crystal ball is broken...
- Problem: a task τ_i executing for more than C_i can cause deadline misses in a different task τ_j
- Two possible solutions:
 - ❖ Analyse the effects of variations in the WCETs: Sensitivity Analysis
 - ❖ Limit the execution time in some way (enforcing a WCET): Resource Reservations

Sensitivity Analysis

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- WCETs are estimations. What happens if my WCET estimation is wrong?
 - ❖ A job $J_{i,j}$ can execute for a time $c_{i,j} > C_i!$
- What's the acceptable error in WCETs estimations?
- Formulate TDA or RTA as a sensitivity analysis problem
 - ❖ How sensible is the demanded time (or response time) to variations of the WCETs?
 - ❖ Example: What happens to R_i if C_h (with $p_h > p_i$) is increased by a small amount δ ?
 - ❖ $R_i = f(C_1, \dots, C_i, T_1, \dots, T_{i-1}); f()$ is not linear...
- Complex analysis, not explained here (see old slides if you are curious)

Reservation-Based Scheduling

❖ From Theory...

❖ ...To Practice

❖ The WCET

❖ Sensitivity
Analysis

❖ Reservation-
Based
Scheduling

❖ Implementing
Temporal Protection

❖ Aperiodic Servers

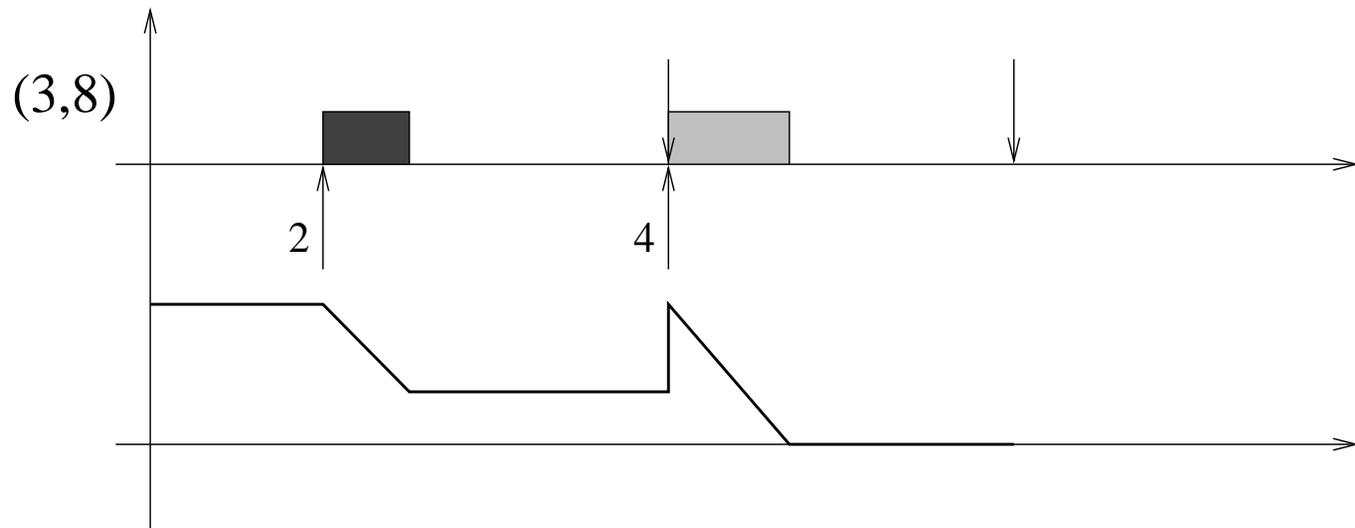
❖ Multiprocessor
Scheduling

- Force the task not to demand more time than a periodic (or sporadic!) (Q, T) task
- How to enforce this?
 - ❖ Measure the demanded time, and deschedule the task when it's too much
 - ❖ Similar to “traffic shaping used in networks”
- Temporal Protection!!!
 - ❖ If task τ_i executes for more than $Q_i = C_i$, it will be blocked...
 - ❖ ... τ_i will miss a deadline (not other tasks!!!)
 - ❖ Similar to memory protection...

Implementing Temporal Protection

- ❖ From Theory...
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- ❖ Reservation-Based Scheduling
- ❖ **Implementing Temporal Protection**
- ❖ Aperiodic Servers
- ❖ Multiprocessor Scheduling

- Budget q , consumed when the task executes
 - ❖ When the budget is 0 the task cannot be scheduled
- Budget
 - ❖ Accounting (Enforcement)
 - ❖ Replenishment



Aperiodic Servers

- ❖ From Theory...
- ❖ ...To Practice
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- ❖ Sensitivity Analysis
- ❖ Reservation-Based Scheduling
- ❖ Implementing Temporal Protection
- ❖ **Aperiodic Servers**
- ❖ Multiprocessor Scheduling

- How to cope with the MIT?
 - ❖ Aperiodic tasks: no particular structure (no knowledge about the MIT)
- Traditional solution: use a periodic (or sporadic) task to serve aperiodic requests...
- Aperiodic Servers
 - ❖ Polling Server, Deferrable Server, Sporadic Server, ...
- Implementation: use a budget...
 - ❖ We end up with resource reservations, again!!!

Multiprocessor Scheduling

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- ❖ Multiprocessor Scheduling

- Real-Time scheduling with more than 1 processor?
- Trivial solution: partitioned scheduling
 - ❖ Statically assign tasks to CPUs
 - ❖ Reduce the problem of scheduling on M CPUs to M instances of uniprocessor scheduling
 - ❖ Problem: system underutilisation
- Global scheduling
 - ❖ One single ready task queue
 - ❖ Select the first M tasks from the queue
 - ❖ Problem: migrations...