# **MACHINE LEARNING**

## Vapnik-Chervonenkis (VC) Dimension

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# **Computational Learning Theory**

- The approach used in rectangular hypotheses is just one case:
  - Medium-built people
  - No general rule has been derived
- Is there any means to determine if a function is PAC learnable and derive the right bound?
- The answer is yes and it is based on theVapnik-Chervonenkis dimension (VC-dimension, [Vapnik 95])



# **VC-Dimension definition (1)**

Def.1: (*set shattering*): a subset S of instances of a set
 X is shattered by a collection of function F if ∀ S'⊆ S
 there is a function f ∈ F such data:

$$f(x) = \begin{cases} 1 & x \in S' \\ 0 & x \in S - S' \end{cases}$$



# **VC-Dimension definition (2)**

- Def. 2: the VC-dimension of a function set F (VC-dim(F)) is the cardinality of the largest dataset that can be shattered by F.
- Observation: the type of the functions used for shattering data determines the VC-dim



### **VC-Dim of linear functions (hyperplane)**

- In the plane (hyperplane = line):
  - VC(Hiperlpanes) is at least 3
  - VC(Hiperlpanes)< 4 since there is no set of 4 points, which can be shattered by a line.</li>
- $\Rightarrow$  VC(H)=3. In general, for a k-dimension space VC(H)=k+1
- NB: It is useless selecting a set of linealy independent points





#### **Upper Bound on Sample Complexity**

**Theorem 2.9** (upper bound on sample complexity, [Blumer et al., 1989]) Let H and F be two function classes such that  $F \subseteq H$  and let A an algorithm that derives a function  $h \in H$  consistent with m training examples. Then,  $\exists c_0$ such that  $\forall f \in F, \forall D$  distribution,  $\forall \epsilon > 0$  and  $\delta < 1$  if

$$m > \frac{c_0}{\epsilon} \Big( VC(H) \times ln \frac{1}{\epsilon} + \frac{1}{\delta} \Big)$$

then with a probability  $1 - \delta$ ,

 $error_D(h) \leq \epsilon$ ,

where VC(H) is the VC dimension of H and  $error_D(h)$  is the error of h according to the data distribution D.



### **Lower Bound on Sample Complexity**

**Theorem 2.10** (lower bound on sample complexity, [Blumer et al., 1989]) To learn a concept class F whose VC-dimension is d, any PAC algorithm requires  $m = O(\frac{1}{\epsilon}(\frac{1}{\delta} + d))$  examples.



# **Bound on the Classification error using VC-dimension**

**Theorem 2.11** (Vapnik and Chervonenkis, [Vapnik, 1995])

Let H be a hypothesis space having VC dimension d. For any probability distribution D on  $X \times \{-1, 1\}$ , with probability  $1-\delta$  over m random examples S, any hypothesis  $h \in H$  that is consistent with S has error no more than

$$error(h) \le \epsilon(m, H, \delta) = \frac{2}{m} \left( d \times ln \frac{2e \times m}{d} + ln \frac{2}{\delta} \right),$$

provided that  $d \leq m$  and  $m \geq 2/\epsilon$ .



#### **Example: Rectangles have VC-dim > 4**

- We must choose 4-point set, which can be shattered in all possible ways
- Given such 4 points, we assign them the {+,-} labels, in all possible ways.
- For each labeling it must exist a rectangle which produces such assignment, i.e. such classification



### Example (cont'd)

- Our classifier: inside the recatagle positive and outside negative examples, respectively
- Given 4 points (linearly independent), we have the following assignments:
- a) All points are "+"  $\Rightarrow$  use a rectangle that includes them
- b) All points are "-"  $\Rightarrow$  use a empty rectangle
- c) 3 points "-" and 1 "+" ⇒ use a rectangle centered on the "+" points



#### **Example (cont'd)**

- d) 3 points "+" and one "-" ⇒ we can always find a rectangle which exclude the "-" points
- e) 2 points "+" and 2 points "-" ⇒ we can define a rectangle which includes the 2 "+" and excludes the 2 "-".
- To show d) and e) we should check all possibilities



### For example, to prove e)





- For any 5-point set, we can define a rectangle which has the most extern points as vertices
- If we assign to such vertices the "+" label and to the internal point the "-" label, there will not be any rectangle which reproduces such assignent



### **Bound Comparison**

- $m > (4/\epsilon) \cdot \ln(4/\delta)$  (ad hoc bound)
- $m > (1/\epsilon) \cdot \ln(1/\delta) + 4/\epsilon =$  (lower bound based on VC-dim)
- $(4/\epsilon) \cdot \ln(4/\delta) > (1/\epsilon) \cdot \ln(1/\delta) + 4/\epsilon$
- $4 \cdot \ln(4/\delta) > \ln(1/\delta) + 4$
- $\ln(4/\delta) > \ln((1/\delta)1/4) + 1$
- $4/\delta > (1/\delta)1/4 \cdot e$
- $4 > \delta 3/4 \cdot e$
- $4 > (<1) \cdot (<3)$  verified



# References

- VC-dimension:
  - MY SLIDES: http://disi.unitn.it/moschitti/ teaching.html
  - MY BOOK:
    - Automatic text categorization: from information retrieval to support vector learning
    - o Roberto Basili and Alessandro Moschitti



# References

- A tutorial on Support Vector Machines for Pattern Recognition
   Downlodable from the web
- The Vapnik-Chervonenkis Dimension and the Learning Capability of Neural Nets
  - Downlodable from the web
- Computational Learning Theory

   (Sally A Goldman Washington University St. Louis Missouri)
   Downlodable from the web
- AN INTRODUCTION TO SUPPORT VECTOR MACHINES (and other kernel-based learning methods)
  - N. Cristianini and J. Shawe-Taylor Cambridge University Press
    - You can buy it also on line

