



UNIVERSITY
OF TRENTO - Italy

Information Engineering
and Computer Science Department

Physical Layer Architecture and Error Correction Codes

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Introduction - Goals

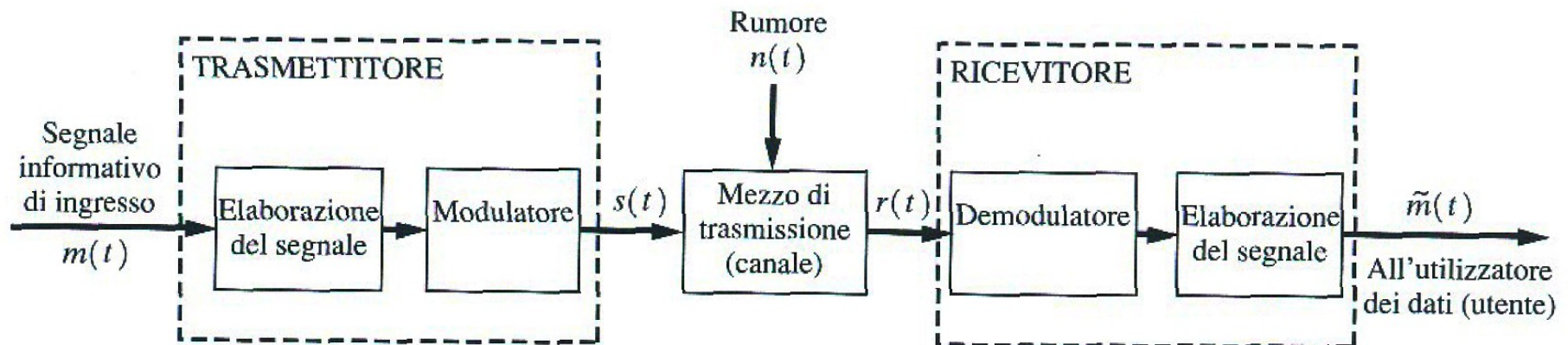
SEMINAR GOALS

- How a signal can be digitally transmitted over a network
- Which are the main problems that engineer must solve to have an efficient network to communicate
- Which are the techniques that permits error recovery when something goes wrong during communication

Let's Start!!

Introduction - Architecture of Communication System

- ***Communicate***: means information can pass from point A to point B using standard conventions
- This is the architecture which allows to communicate between two or many points

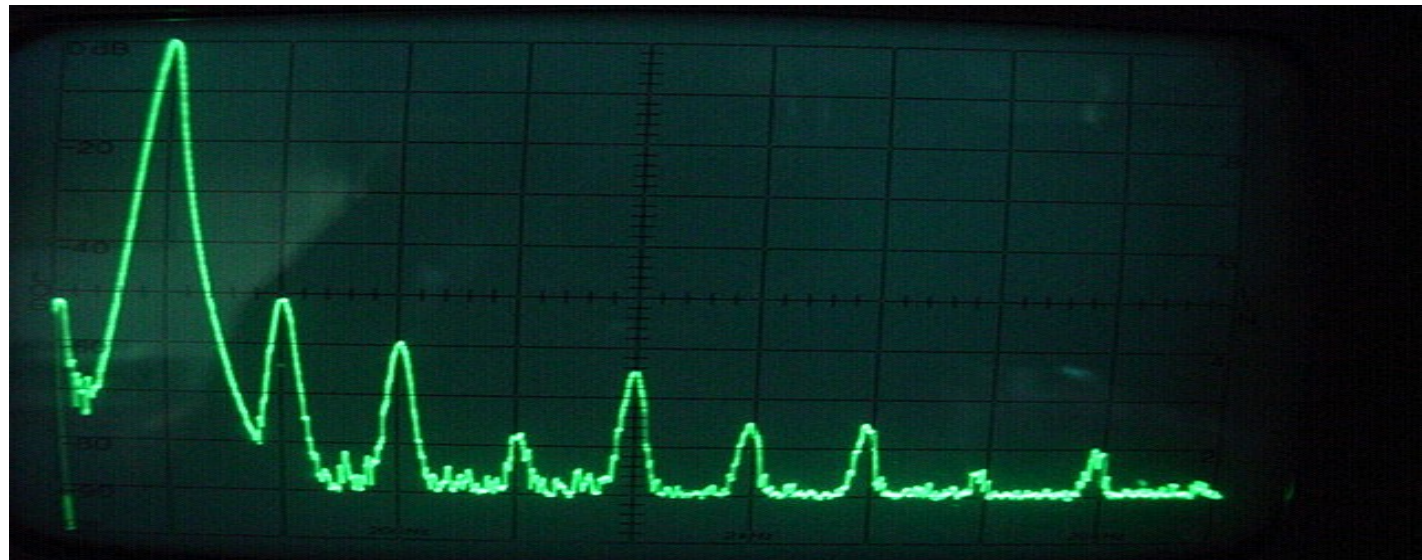




Chapter 1 - Signals

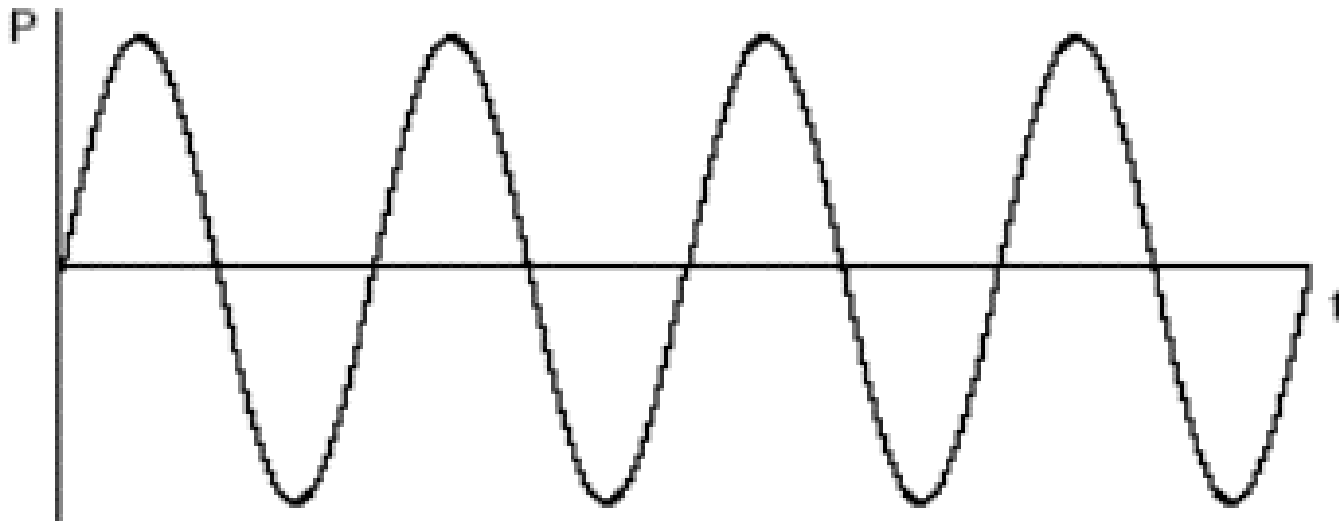
What is a Signal?

- Signal is a **physical quantity** which varies with respect to **time**, contains **information** and travels from source to destination
- The IEEE defines "signal" as follows: The term "signal" includes, among others, audio, video, speech, image, text, communication, etc.



Analog signal

- A signal that has a **continuous nature**, may vary in frequency, phase or amplitude in response to changes in physical phenomena
- Typically, for transmission purposes, we talk about a **sinusoidal signal** that has particular shape, see the figure:

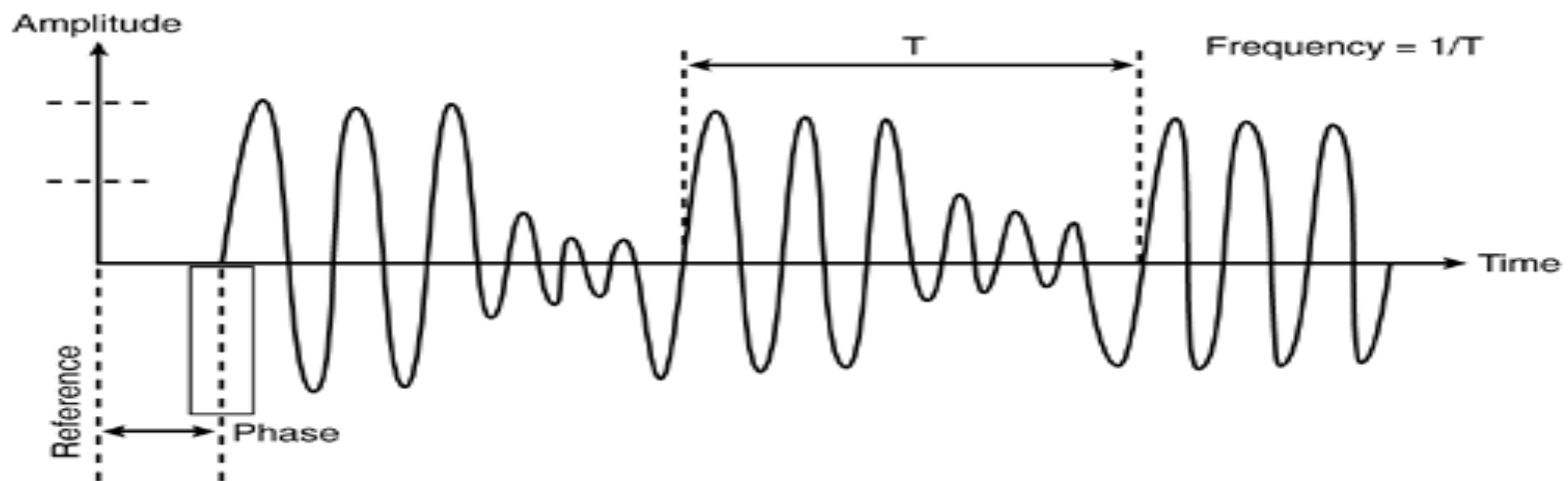


Properties of Sinusoidal Signal

- General formula for a continuous sinusoidal signal is:

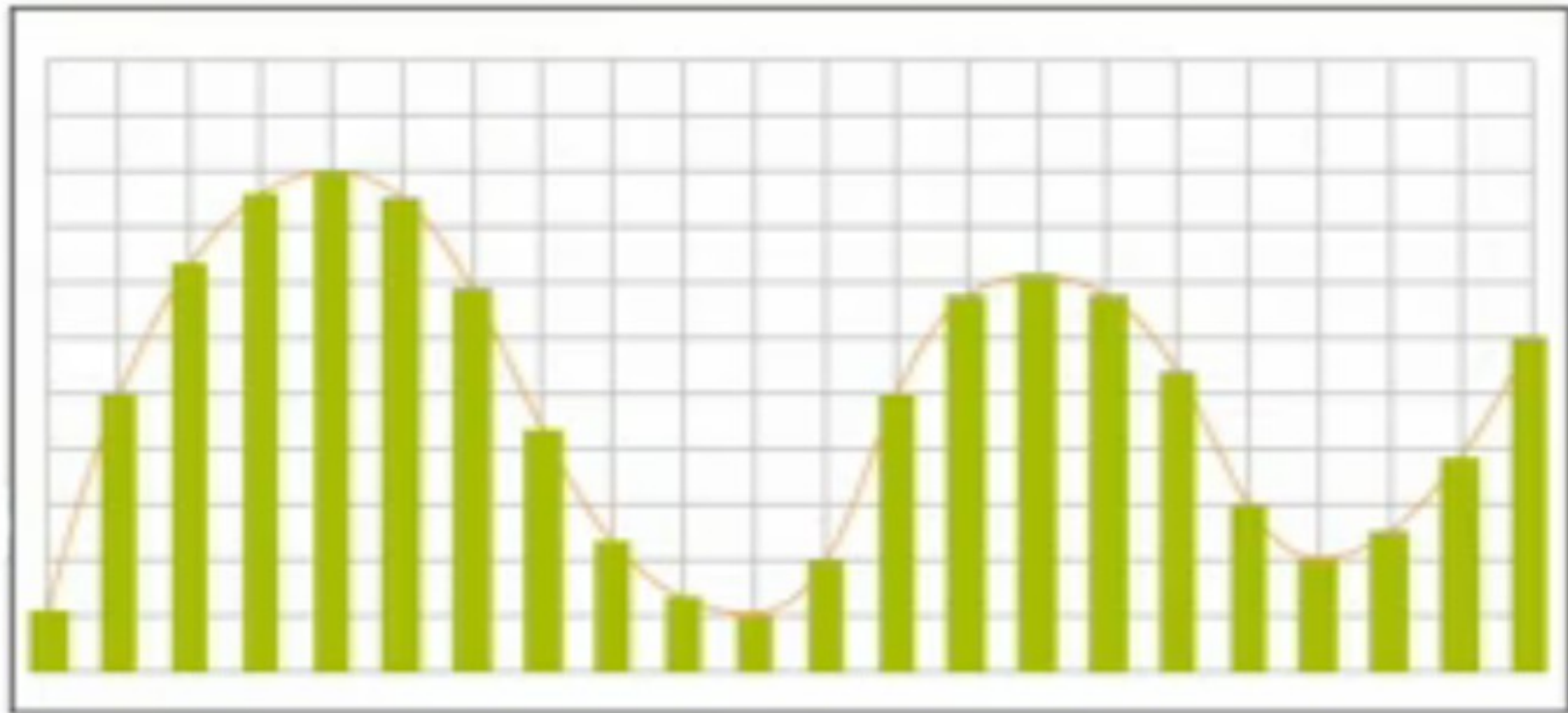
$$s(t) = A \sin(2\pi f t) + \Phi$$

- Amplitude (A) → measure intensity of the signal, substantially measure the height of the wave
- Frequency (f) → measure the number of occurrences of a wave repeating event in 1 sec
- Phase (Φ) → measure translation of the wave (along time axis)



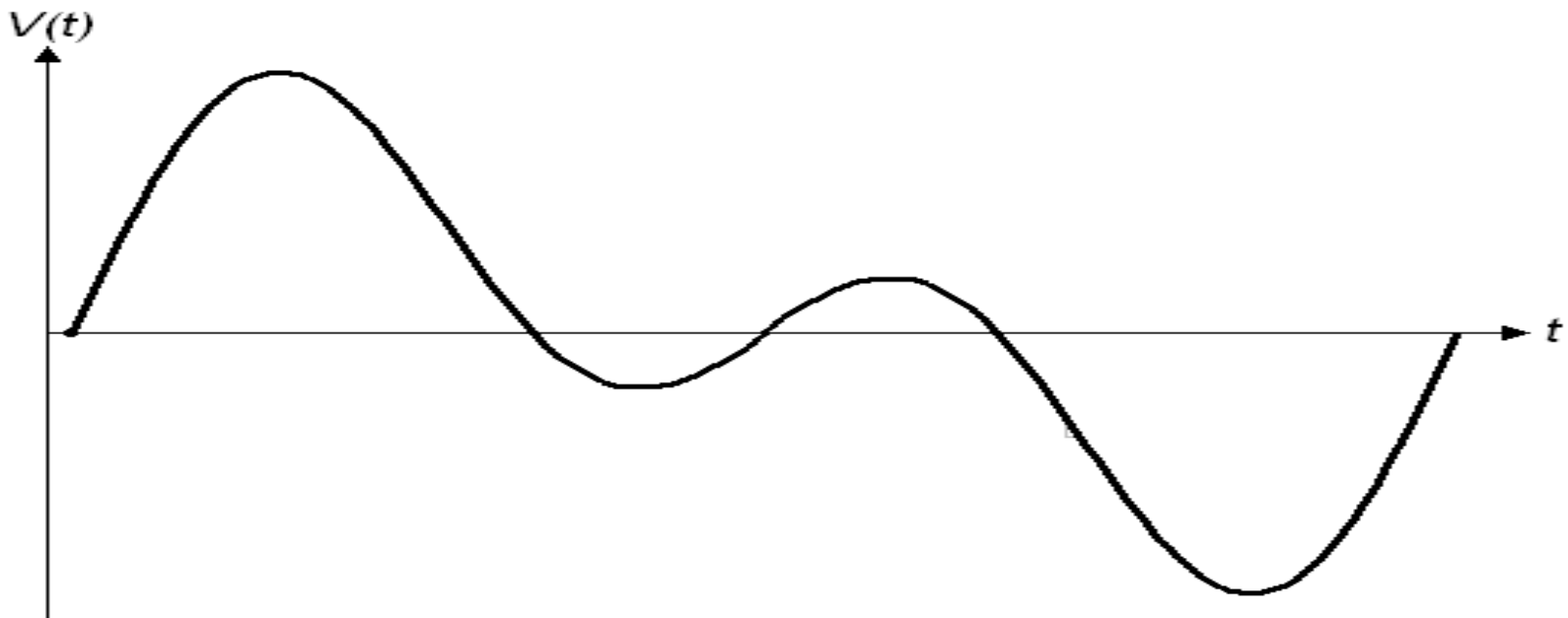
Digital Signal

- A digital signal has a **discrete value** measured at each sampling point.
- A digital signal can refer to an electrical signal that is converted into a pattern of bits by sampling



Sampling

- *Sampling*: is the reduction of a continuous signal to a discrete signal measuring its value at different moments
- This permits to **convert** an analog signal into a digital signal, making a well know: “digitalized analog signal”
- *Sampling Frequency*: (Sampling Rate) is the number of samples obtained in 1 second!

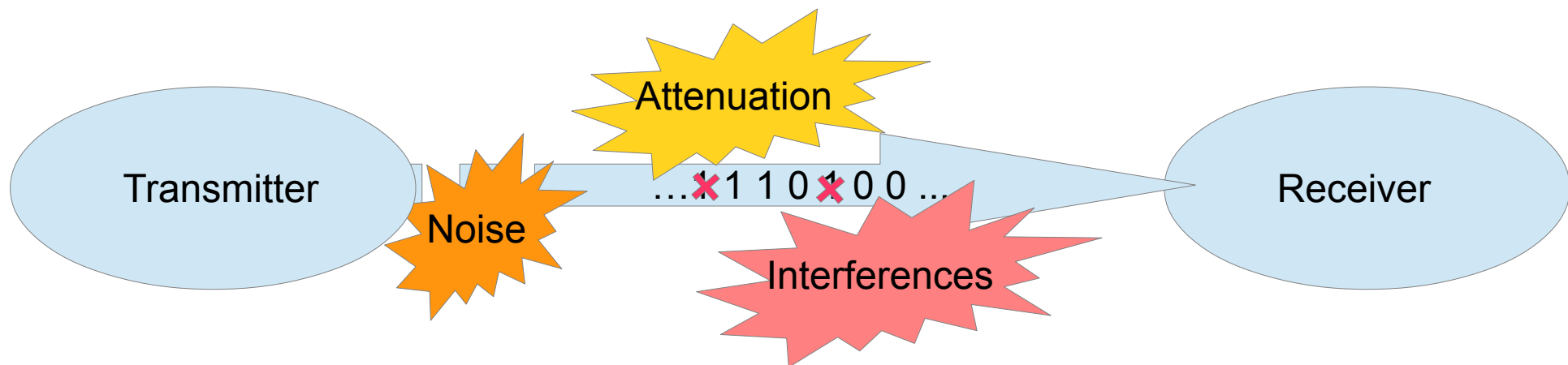




Chapter 2 – Transmission

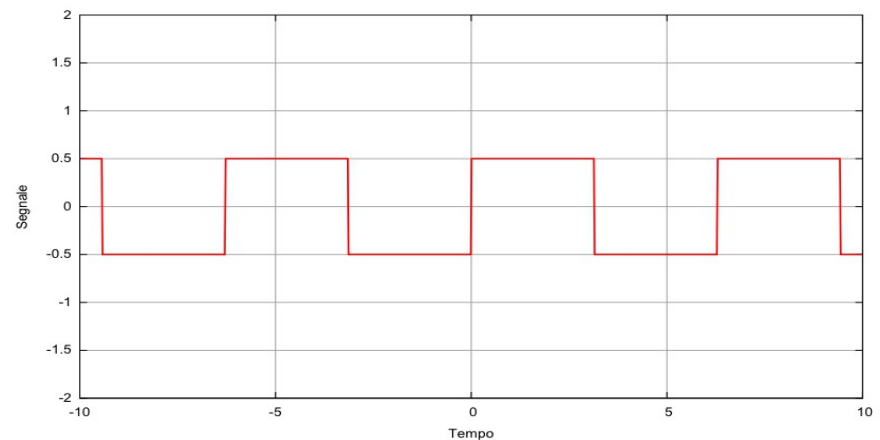
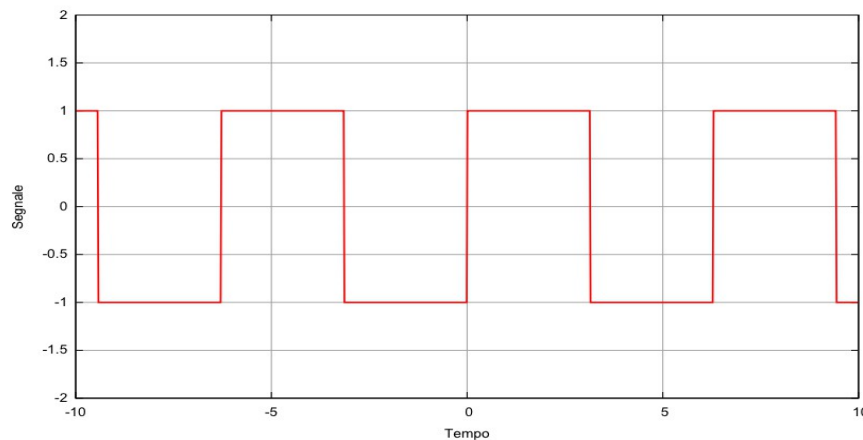
Transmission

- *Transmission*: is the process of sending and propagating an analogue or digital information signal over a physical point-to-point or multipoint transmission medium that can be wired or wireless
- *Data transmission*: (or digital communication) is the transmission of a **digital message** or of a **digitized analog signal**
- In all types of transmission, there are many **problems** that can make the transmission very difficult: attenuation, noise, etc.



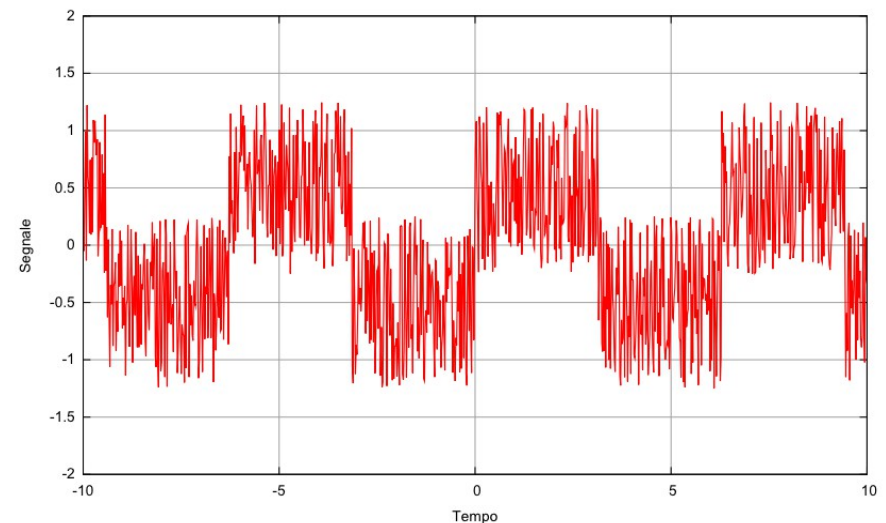
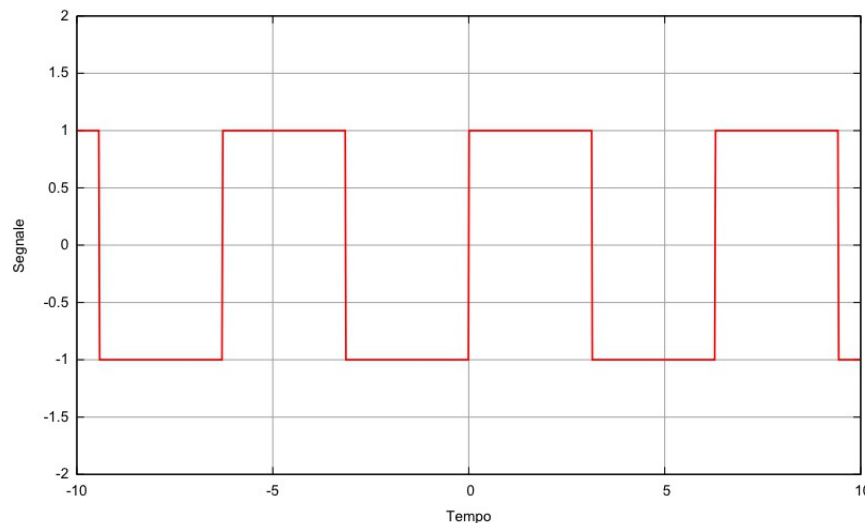
Attenuation

- Attenuation is the **gradual loss of intensity** of a wave through a medium.
- We can algebraically imagine attenuation as a multiplication of the signal to a coefficient $c \in [0,1]$
- Attenuation affects the propagation of waves and signals in electrical circuits, in optical fibers, as well as in air (radio waves)



Interference

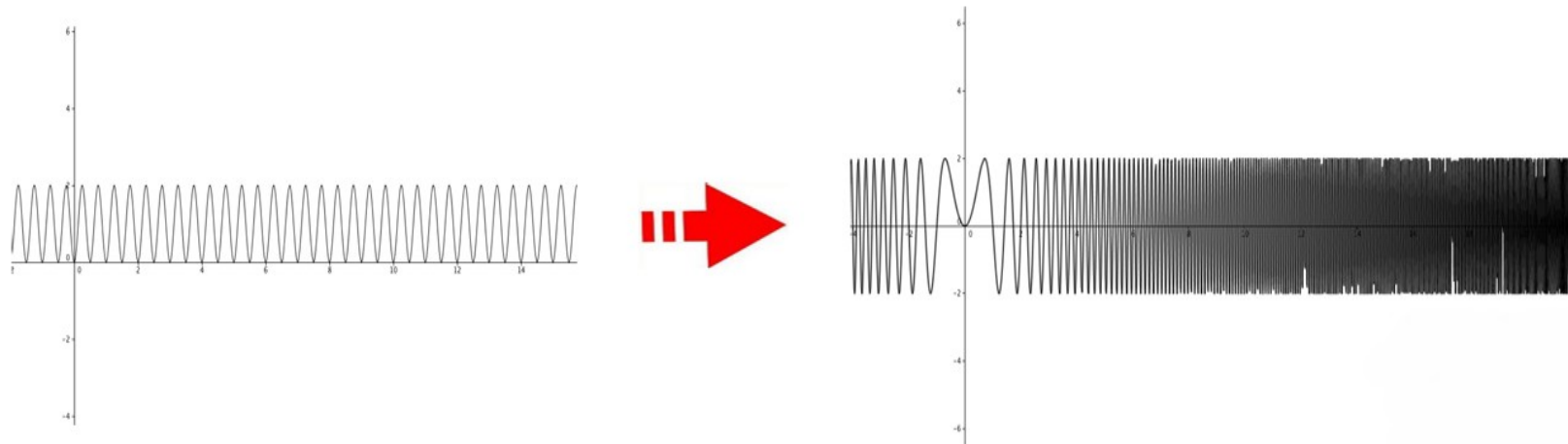
- Interference is a phenomenon in which **two waves overlap** to form a resultant wave of greater or lower amplitude
- We can algebraically imagine interferences as the result of **addition** of two or more waves
- Interference effects can be observed with all types of waves, for example, light, radio, acoustic, and surface water waves.
- Main causes of interference are nearby electromagnetic fields and energy from nearby wires



Distortion

- A distortion is the **alteration of the original shape** of a waveform
- Distortion occurs when the properties of waveform varying by a factor that is not always the same at all frequencies
- Is the only transmission problem that modify **not linearly** the waveform !

Frequency distortion

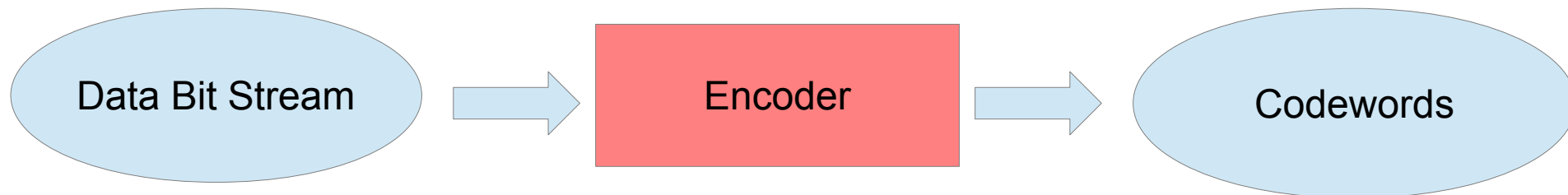




Chapter 3- Encoding

Encoding

- *Encoding*: is the process which bit informations are converted into codewords
- *Idea*: When codewords will be arrived at the receiver, it can understand if some **errors occurs**, even **correct** them
- *Encoder*: is a device, circuit, transducer, software program, algorithm, etc. that execute encoding



Decoding

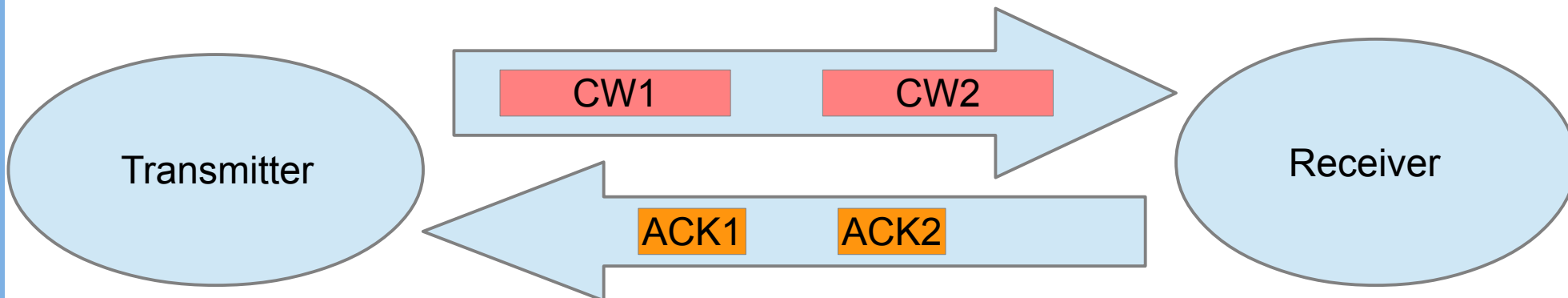
- *Decoding*: is the process that convert back codewords into a data bit stream
- Decoding process means also errors detection and correction
- If the decoding technique used can **only discover** wrong codewords then decoder typically use **ARQ** techniques to request for a **retransmission** of that wrong codeword
- *Decoder*: is a device, circuit, transducer, software program, algorithm which does the reverse operation of encoder



ARQ (Automatic Repeat Re-Quest)

- This technique uses **ACK** and **timeouts** to achieve reliable data transmission.
- If receiver detects some parity bit errors inside a packet then it can ask sender to retransmit this packet.
- Main ARQ techniques are:
 - *Stop and Wait*
 - *Go Back-N*
 - *Selective Repeat*

Same used by TCP to ask for retransmission

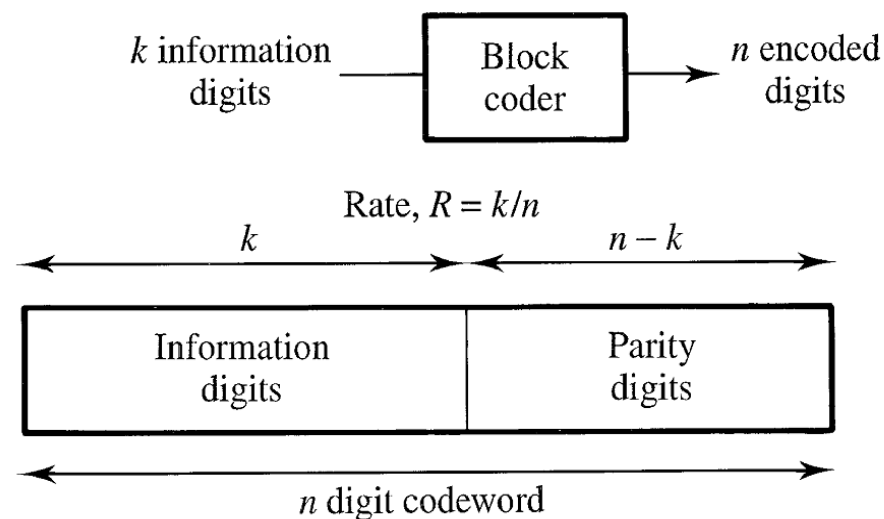


FEC (Forward Error Correction)

- FEC techniques are used to **find and correct** transmission errors over an unreliable and noisy communication channel **without asking for retransmission**
- Idea:
 - Transmitter encodes messages by adding some redundant bits
 - Receiver, using redundant bits, can find and correct errors
- FEC techniques are used:
 - Broadcast and Multicast: When it is not possible to send back ACK/NACK to the sender
 - Long Propagation Delay: To avoid long inactivity periods of sender for waiting ACK/NACK
 - High Bit Error Rates: If 20% of bit stream received is wrong, it is very difficult to communicate using only FEC techniques

Block Code

- Encoder takes k data bits as input and convert them into a codeword of n bits



- Binary logic of encoder works **like a function**

- Encoder has **NO memory**: this means that given as input always the same k bits, binary logic of encoder gives as output always the same n bits

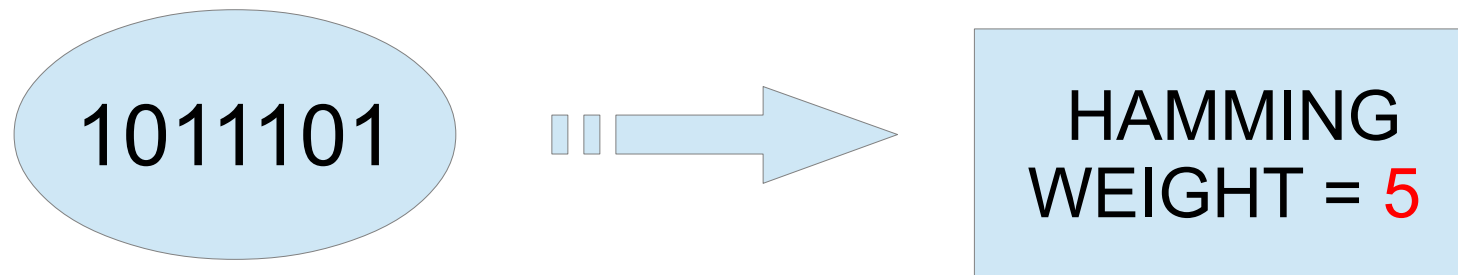
Hamming

- Hamming codes are a family of linear error-correcting codes invented by Richard Hamming in 1950
- A typical hamming code is written like this $H(n, k, n-k)$ where
 - n : # of bits in a codeword
 - k : # of data bits
 - $n-k$ = # parity bits
- To **DETECT** e errors we need $e+1$ parity bits
- To **CORRECT** e errors we need $2e+1$ parity bits

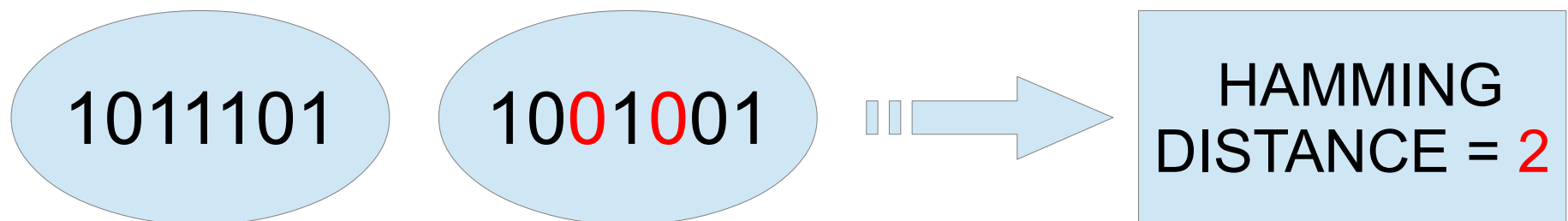


Hamming Definitions

- Hamming Weight (H_w): is the number of bits = 1 into a string



- Hamming Distance (H_d): measures the minimum number of substitutions required to change one string into another one. (# of errors)



Parity Bit Coverage

- All bit positions that are powers of two are **Parity Bits!**
All other bit positions are **Data Bits!**
- Each parity bit “protects” a subset of data bits
- Position 1: cover 1 bit, skip 1 bit, etc. (1,3,5,7,9,11,13,15,...)
- Position 2: cover 2 bits, skip 2 bits, etc. (2,3,6,7,10,11,14,15,...)
- Position 4: cover 4 bits, skip 4 bits, etc. (4,5,6,7,12,13,14,15,...)

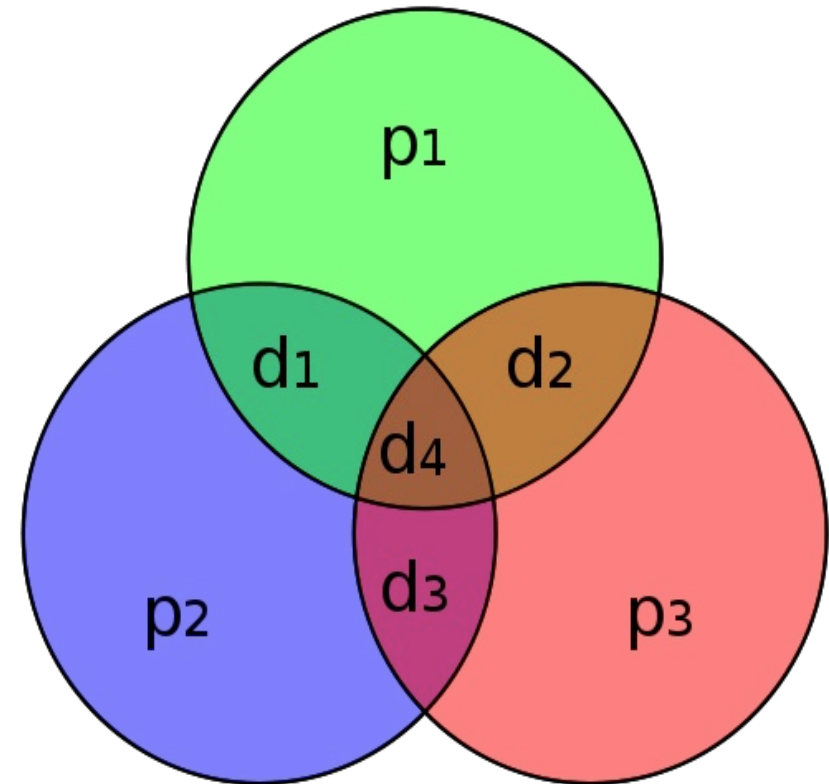
Bit position	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	
Encoded data bits	p1	p2	d1	p4	d2	d3	d4	p8	d5	d6	d7	d8	d9	d10	d11	p16	d12	d13	d14	d15	
Parity bit coverage	p1	X		X		X		X		X		X		X		X		X		X	
	p2		X	X			X	X			X	X			X	X			X	X	...
	p4				X	X	X	X					X	X	X	X					X
	p8								X	X	X	X	X	X	X						
	p16																X	X	X	X	X

Parity Bit Coverage

- This is an Hamming (7,4,3) codeword:

$p_1 p_2 d_1 p_3 d_2 d_3 d_4$

- A parity bit coverage can also be explained as an Eulero-Venn diagram like in this figure



- In a Hamming (7,4,3) code:

- p_1 cover $d_1 d_2 d_4$

- p_2 cover $d_1 d_3 d_4$

- p_3 cover $d_2 d_3 d_4$

- \forall Parity bit (p_x) | $x \in$ power of 2

If (H_w of data bits covered by p_x is odd)

$$p_x = 1$$

Else $p_x = 0$

Hamming (7,4,3) Example - Encoding

- Let's suppose that we want to send a bit stream $s = 1011$
- Hamming (7,4) codeword becomes: $p_1 p_2 1 p_3 0 1 1$
- $p_1 = H_w$ of its covered bits ($p_1 p_2 1 p_3 0 1 1$) is $2 \rightarrow \text{EVEN} \rightarrow 0$
- $p_2 = H_w$ of its covered bits ($p_1 p_2 1 p_3 0 1 1$) is $3 \rightarrow \text{ODD} \rightarrow 1$
- $p_3 = H_w$ of its covered bits ($p_1 p_2 1 p_3 0 1 1$) is $2 \rightarrow \text{EVEN} \rightarrow 0$
- Encoded codeword is: $0 1 1 0 0 1 1$



Hamming (7,4,3) Example – Error Correction Algorithm

- 1 – Set an int variable $sum = 0$
- 2 – Repeat encoding algorithm for **each parity bit e_i**
- 3 – If its value not correspond with **H_w** of its covered bits then add its index to variable sum
- 4 – If **$sum = 0$** means that all parity bits was corrected so there is nothing to do because received **codeword is correct**
- 5 – Otherwise something went wrong and the value of variable sum is the **index of wrong bit**, to correct that error, simply **negate** that bit

Hamming (7,4,3) Example – Error Correction

- If, during transmission, something goes wrong (noise, interferences, etc..) receiver will get something different than original bit stream
- Let's suppose receiver get wrong codeword where **fifth bit is wrong**: 0110**1**11
- Repeating encoding algorithm for each parity bit:
 - $p_1 = 0$ - H_w of its covered bits (0 1 1 0 1 1 1) is 3 → ODD → WRONG
 - $p_2 = 1$ - H_w of its covered bits (0 1 1 0 1 1 1) is 4 → EVEN → OK
 - $p_3 = 0$ - H_w of its covered bits (0 1 1 0 1 1 1) is 3 → ODD → WRONG
- Adding indexes of wrong parity bits 1 + 4, we get the index (5) of bit where error occurs!
- Receiver can then correct that error and get 0110**0**11, the correct codeword!

Hamming (7,4) Example - Decoding

- Finally, to get only data bits from codeword, decoder must only drop parity bits
- Drop every parity bits means drop every bit which have index that are powers of two
- After decoding, data bit stream can be passed up to application level



Galois Field

- A Galois field $GF(x)$: is a finite field that contains a **finite number** of elements, x specify cardinality of GF
- A GF has these properties:
 - Closing under Addition and Multiplication
 - Associativity, Commutativity and Distributivity
 - Existence of neutral element: 0 for addition and 1 for multiplication
 - Existence for each element u of its opposite $-u$
 - Existence for each element $u \neq 0$, the inverse element u^{-1}
- In **Addition and Subtraction** are executed with **XOR** operand
- In **Division**, dividend is divisible by divisor only if it is **composed by the same number of bits** of divisor otherwise not!
- In Multiplication the **result must be divided** by cardinality of Galois Field considered and take the **remainder** as right result!

Galois Field

- ADDITION

$$\begin{array}{r} 10110011 + \\ 10001101 = \\ \hline 00111110 \end{array}$$

← It's the same! →

- SUBTRACTION

$$\begin{array}{r} 10110011 - \\ 10001101 = \\ \hline 00111110 \end{array}$$

- MULTIPLICATION

$$\begin{array}{r} 111000 \times \\ 101 = \\ \hline 111000 \\ 000000- \\ 111000-- \\ \hline 11011000 \text{ mod } |GF(x)| \end{array}$$

- DIVISION

$$\begin{array}{r} 111000 : 101 = 1101 \\ \hline 101 \\ \hline 0100 \\ \hline 101 \\ \hline 0010 \\ \hline 00100 \\ \hline 101 \\ \hline 001 \end{array}$$

CRC (Cyclic Redundancy Code)

- CRC Code checks if transmission errors occurs but **not correct** them.
- A bit stream of k bits can be converted in a polynomial of degree $k-1$
- CRC uses Galois Field to encode messages
- Es. 100110 ($k = 6$) can be converted in a polynomial like this:
 $x^5 + x^2 + x$. **Degree = $k-1$**
- Generator Polynomial $g(x)$ is an algebraic polynomial of degree r (composed by $r+1$ bits) where **FIRST** and **LAST** bits = **1**;
- $g(x)$ is always known by transmitter and receiver

CRC – Encoding Algorithm

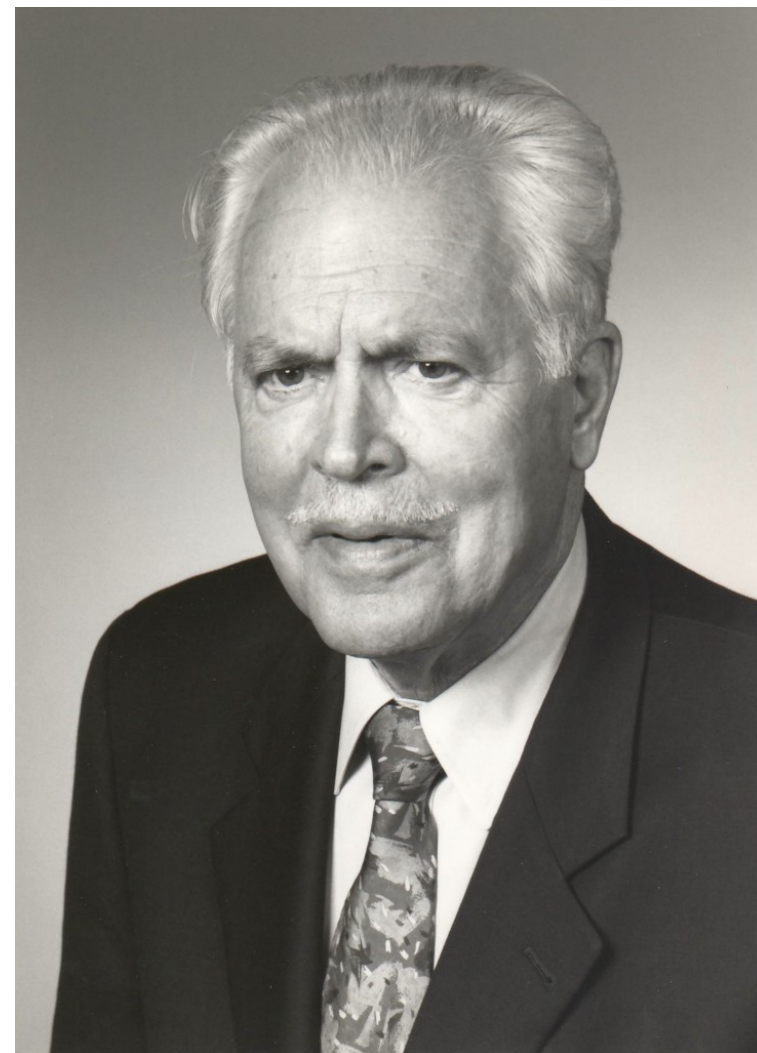
1. Let's suppose $m(x)$ is message that we want encode
2. Add r zero bits to $m(x)$ (r is degree of $g(x)$)
3. $r(x) = x^r m(x) \bmod g(x)$
4. $m(x) = x^r m(x) - r(x)$ (it is a **XOR** operation of last r bits)
5. Transmit this new polynomial $m(x)$ where first m bits, data bits, are **unchanged**

CRC (Cyclic Redundancy Code)

- Message is another polynomial $m(x)$ of degree $m-1$ where $m > r$
- **IDEA:** Append at $m(x)$ a control bit string of r bits to get a polynomial divisible by $g(x)$
- If transmission works, decoder divide $m(x)$ by $g(x)$ and get no rest. This means that codeword is correctly received
- To decode $m(x)$, decoder must **divide $m(x)$ by x^r** to get only data bits.
- Otherwise, if transmission errors occurs, with very high probability, that polynomial will not be more divisible by $g(x)$
- Decoder must ask for a retransmission of that wrong packet using ARQ

Reed Solomon – RS Code

- RS-codes are non-binary cyclic error-correcting codes invented by Irving S. Reed and Gustave Solomon
- Like CRC it see a bit stream like a polynomial
- RS-Code use algebraically properties of Galois Field to encoding
- RS-Code purpose is to find greater number of packets that contains errors.
- RS-Code are used in our Digital TV



Reed Solomon - RS Code

- RS-Code uses an alphabet of **q symbols** (not only 0 or 1)
- A **symbol** represent many bits (16 or more..)
- RS-Code are used to find **burst** of errors (multiple errors)
- Codeword contains n symbols, k are data symbols and n-k are redundancy symbols
- $0 < k < n < 2^m$
- RS-Code can **find and correct** until **$t = (n-k) / 2$ errors** in a codeword
- The most common form for RS-codes is RS($2^m-1, 2^m-1- 2t$) where: **2t** is the number of redundancy symbols

RS-Code – Encoding Algorithm

- Define a **generator polynomial $g(x)$** known by transmitter and receiver: $g(x) = (x + \alpha)(x + \alpha^2)\dots(x + \alpha^{2t})$ where α, α^2, \dots are roots

$$= g_0 + g_1x + g_2x^2 + \dots + g_{2t-1}x^{2t-1} + x^{2t}$$

- Convert a bit stream of k bits into a polynomial:

$$d(x) = d_0 + d_1x^1 + \dots + d_{k-1}x^{k-1}$$

- Multiply $d(x)$ with x^{2t-1}** ($2t = n-k$) to get a polynomial of n symbols and degree $n-1$

- $p(x) = x^{2t-1}d(x) \bmod g(x)$** , is the rest of division by $g(x)$

- $a(x) = x^{2t-1}d(x) / g(x)$** , is the result of division by $g(x)$

- Finally **$c(x) = x^{2t-1}d(x) + p(x)$** (it is a XOR operation)

- Now we get $c(x)$ that is a polynomial which is exactly divisible by $g(x)$

RS Code – Decoding

- Let's suppose some errors in transmission:
 $e(x) = r(x) - c(x)$, where $r(x)$ is the received codeword
- More generally $e(x)$ will be something like this:
$$e(x) = e_0 + e_1x + e_2x^2 + \dots + e_{n-1}x^{n-1}$$
- Codewords, where $c(x) \bmod g(x) \neq 0$, surely contains some errors, but we don't know in which **position** and what is the **right symbol** (because we are in a NON binary code)
- Firstly we must calculate the syndrome polynomial $s(x)$
$$s(x) = r(x) \bmod g(x) = (a(x)g(x) + e(x)) \bmod g(x)$$
- If syndrome **is null**, this means that **codeword is correctly** received
- Otherwise we have to calculate errors polynomial $e(x)$
 $e(x) = s(\alpha^i)$, where each α^i is a root of $g(x)$ at position i

RS Code – Decoding

- Otherwise we have to calculate errors polynomial $e(x)$:
 $e(x) = s(\alpha^i) \text{ } i=1..2t$, where each α^i is a root of $g(x)$ at position i
- Finally to get correct codeword $c(x)$ we simple:

$$c(x) = r(x) - e(x)$$

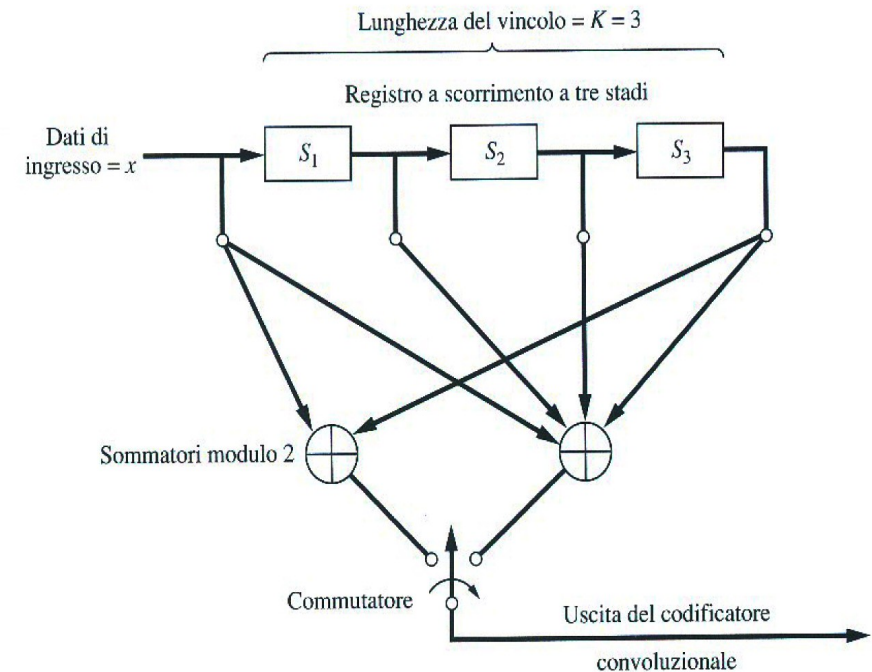
- *Important*: Some operations may seem very strange, it is correct because we are using properties of a Galois Field(2^x)
- To get more informations about RS Code visit:
 - Stefano Rinauro - Codifica RS (Italian)
 - Bernard Sklar (English)

Convolutional Code

- Encoder **has a little memory** to remind previous states
- Encoder use a scrolling register to store until K bit stream blocks past
- *Constraint Length*: Number of bit stream blocks (K) stored into the scrolling register
- From these K-1 blocks plus the new one, binary logic calculate the new codeword
- *Infinite Memory*: Because a convolutional encoder can remember K previous states, we say that it remember **infinite previous states** because each state depends by K before, and so on

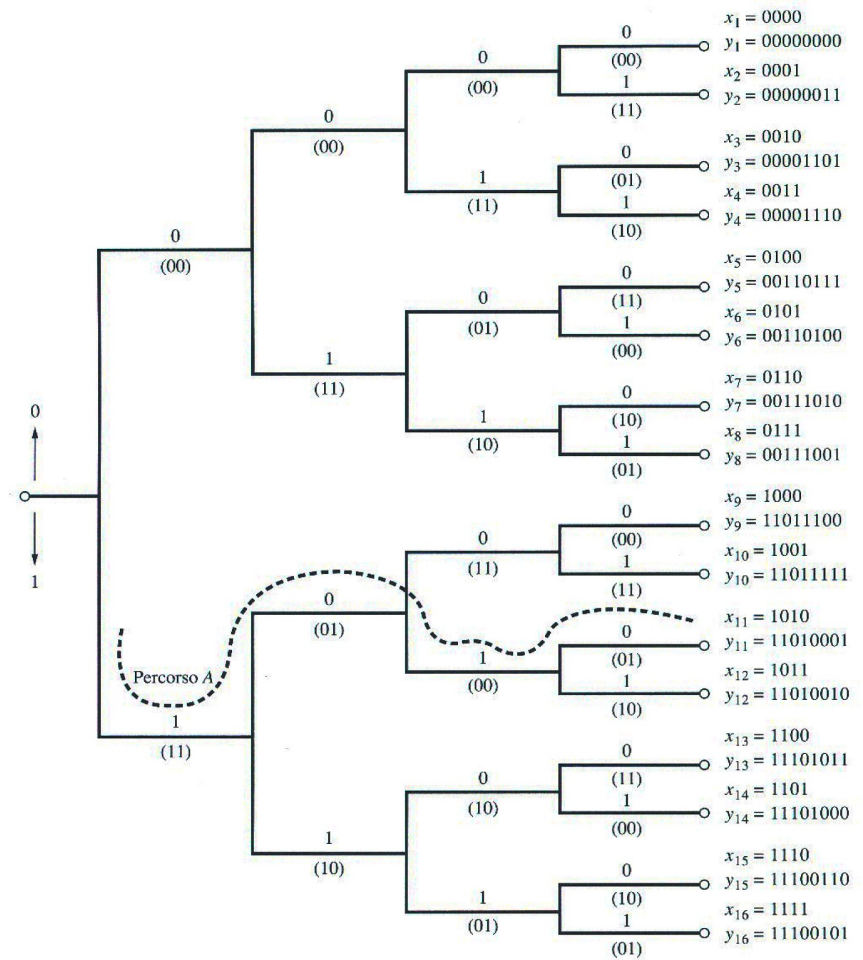
Convolutional Code – Encoding Example

- Example:
 - Constraint Length (K) = 3
 - #bits of codeword (n) = 2
 - #data bits as input (k) = 1
- To make a codeword, a **commutator rotate clockwise between some mod 2 adders** concatenating their output
- $R = \text{redundancy rate} = \frac{1}{2}$
because each 1 bits of data as input, we get 2 encoded bits as output



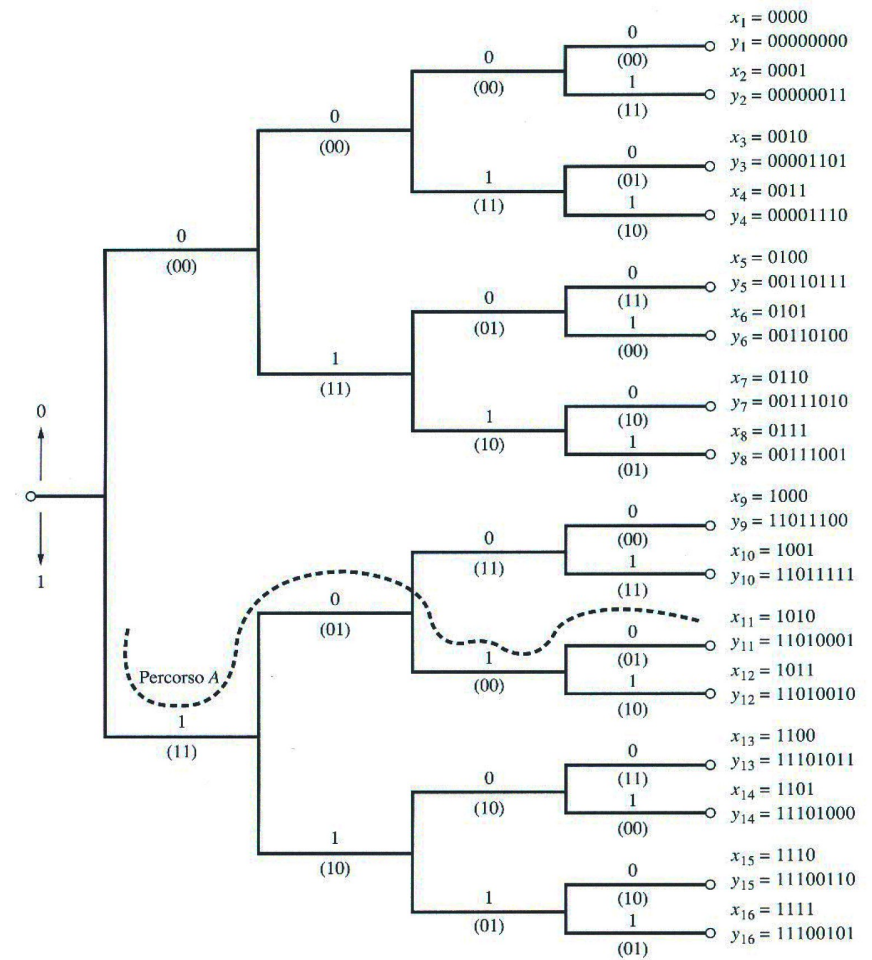
Convolutional Code – Encoding Example

- Encoder make a **code tree** like in this figure
- To move within a code tree, we have to move:
 - **Up** if source bit is 0
 - **Down** if source bit is 1
- Taking bits contents in each node which is crossed by our path, we get encoded string
- Let's suppose source bits are: $s = 1010$, following code tree, we get encoded string:
 $y_{11} = 11010001$



Convolutional Code – Decoding Example

- Using Viterbi's Algorithm decoder find a path which have **minimum Hamming distance** from received sequence to each possible sequence path in code tree
- Works only if there are almost 1 error for each codeword

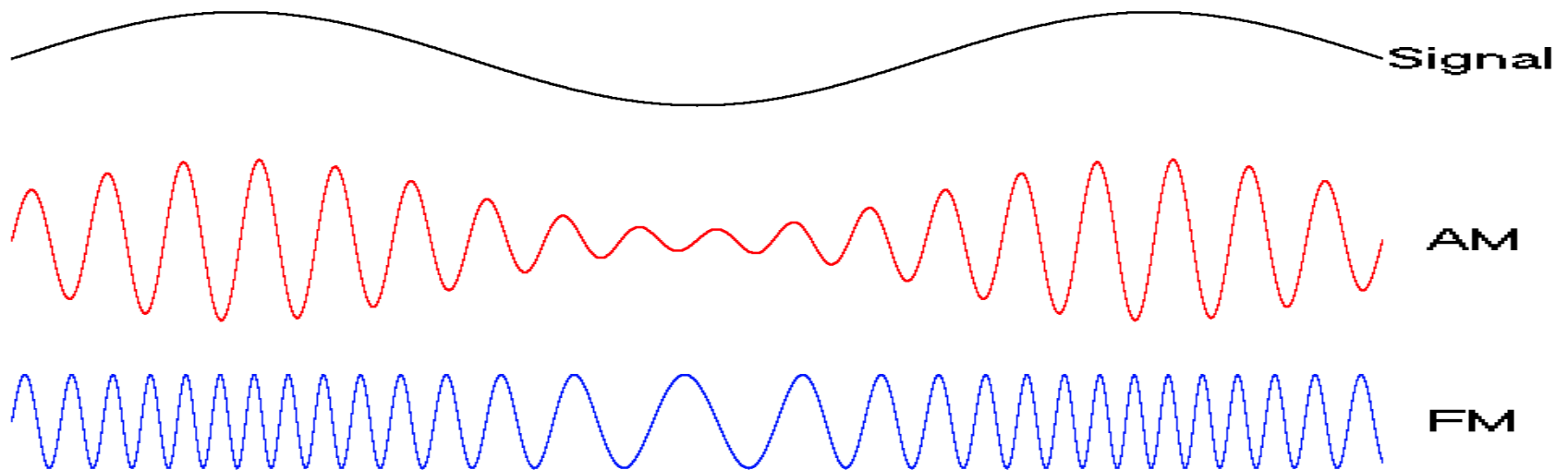




Chapter 4 – Modulation

Modulation

- *Modulation*: varying one or more properties of a high-frequency sinusoidal waveform, called the “**carrier**” signal, with a modulating signal which contains information to be transmitted.
- *Modulator*: is an hardware circuit that accept a sequence of data bits and applies modulation to a carrier wave according to the bits to transmit data over that carrier wave

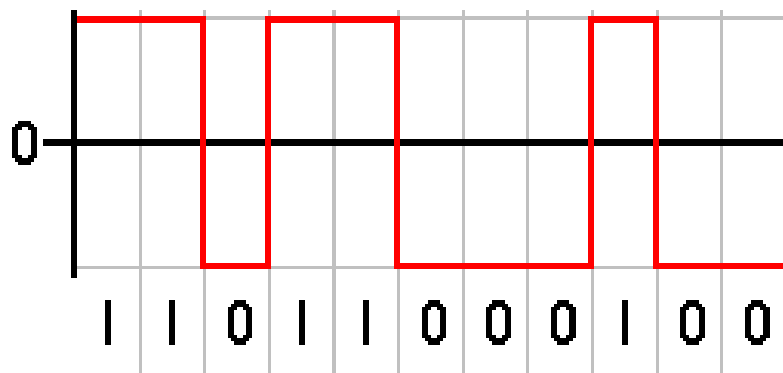


Demodulator

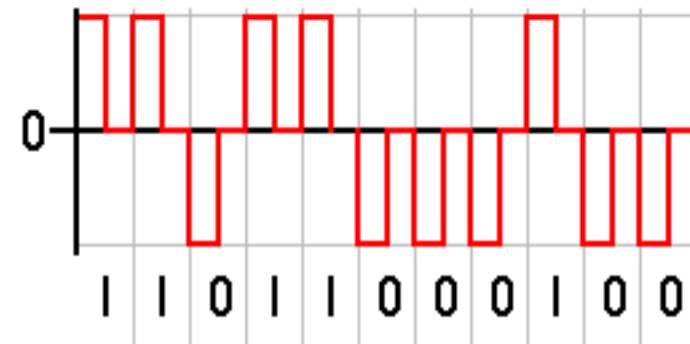
- *Demodulator*: Hardware circuit that accepts a modulated carrier wave and recreates the sequence of data bits that was used to modulate the carrier wave
- To support full-duplex communication each location need both modulator and demodulator
- Manufactures combine both circuits into a single device called MODEM (**MO**dulator-**DEM**odulator)

Baseband Modulation (Line Code)

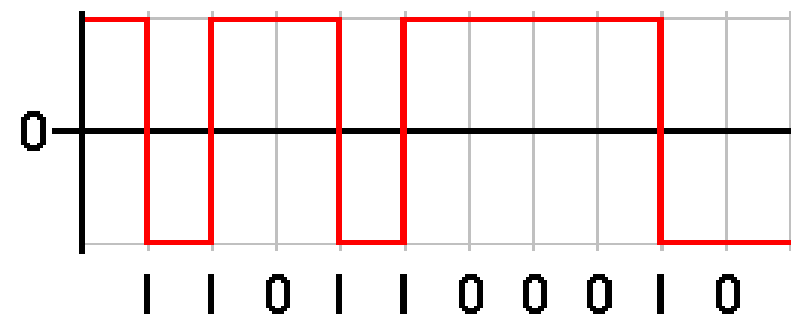
- Line coding is a representation of the digital signal by an **amplitude variation in time-discrete**
- Signal that is optimally tuned for the specific properties of the physical channel
- NRZ (Non Return to Zero)



- RZ (Return to Zero)



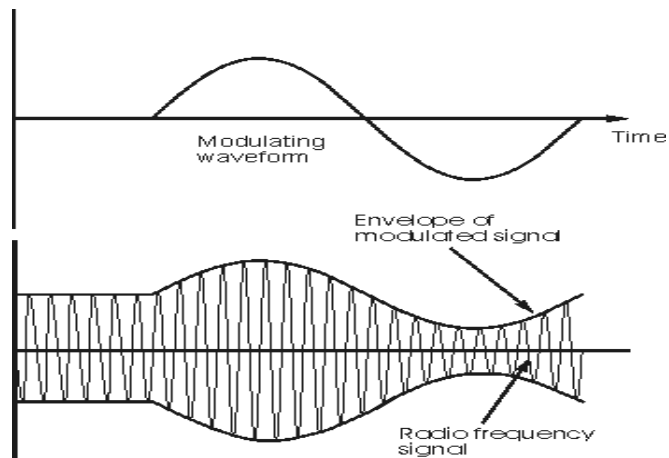
- NRZI (Non Return to Zero Inverted) – USB



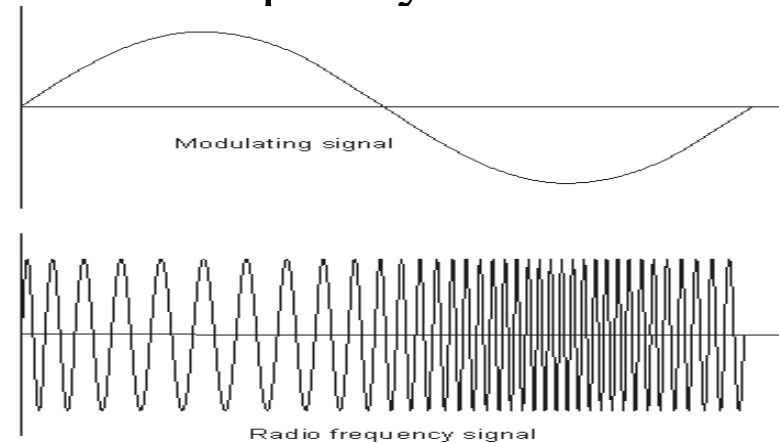
Typical Modulation

- Conveys information over a carrier wave by varying its **instantaneous** frequency, amplitude or phase
- In digital transmission that modulations are called respectively FSK, ASK, PSK

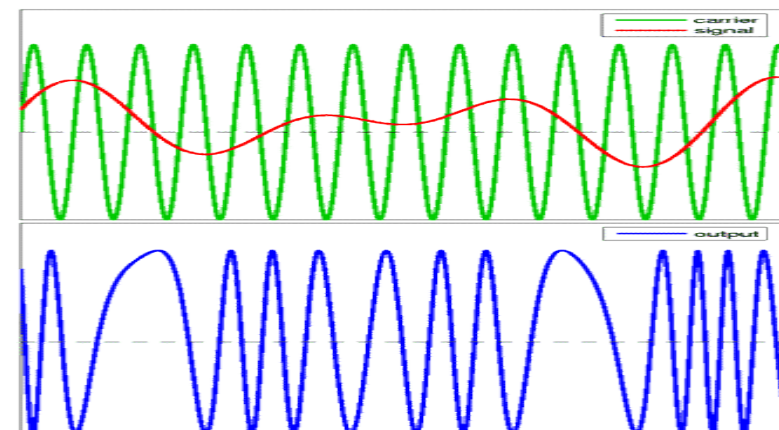
- AM: Amplitude modulation



- FM: Frequency modulation



- PM: Phase modulation



Q-AM Quadrature Amplitude Modulation

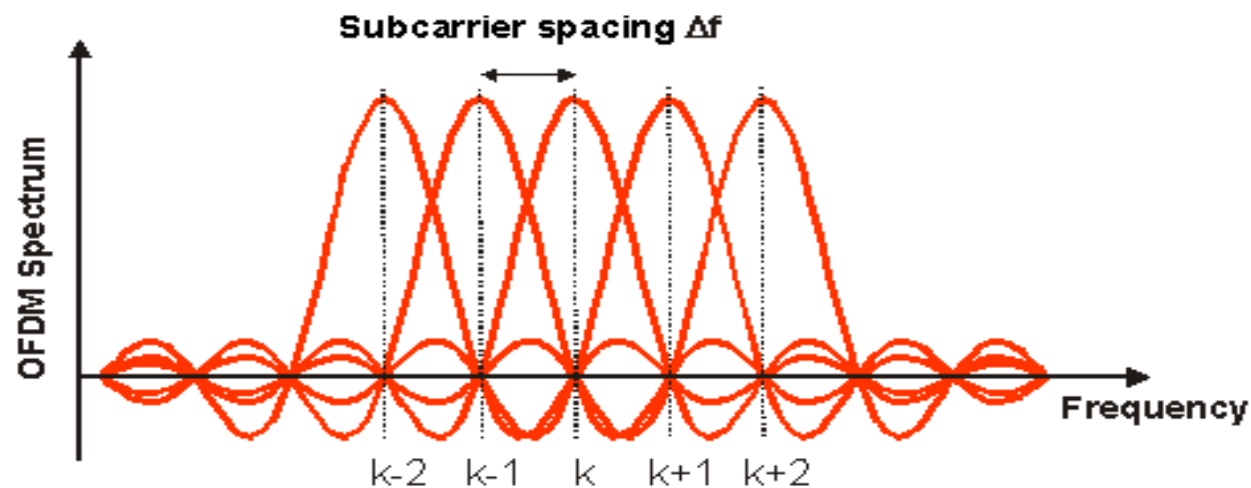
- Q-AM modulation permits to **transmit symbols** and not only a bit stream.
- Data Bits are modulated as symbol
- A Symbol is identified by:
 - **Amplitude** Value
 - **Phase** Value
- This means that it is possible to transmit a lot of bits with a single symbol
- In 16Q-AM (as in figure) each symbol transmitted conveys 4 data bits

OFDM

- OFDM (Orthogonal Frequency Division Multiplexing) is a modulation used in our digital television to transmit and receive tv channels
- OFDM is a multi carrier wave modulation, this means that uses a lot of carrier, each orthogonal with other
- OFDM main properties:
 - **Splits information** flow on multiple carriers
 - Each carrier is modulated using **QAM modulation**
 - In QAM modulation is used a **low symbol rate**

OFDM

- Maintain low symbol rate reduce interferences because permits to use **guard intervals of duration acceptable**
- OFDM can be used also in bad channel conditions because orthogonality of carriers and its properties permit **avoid transmission problems**





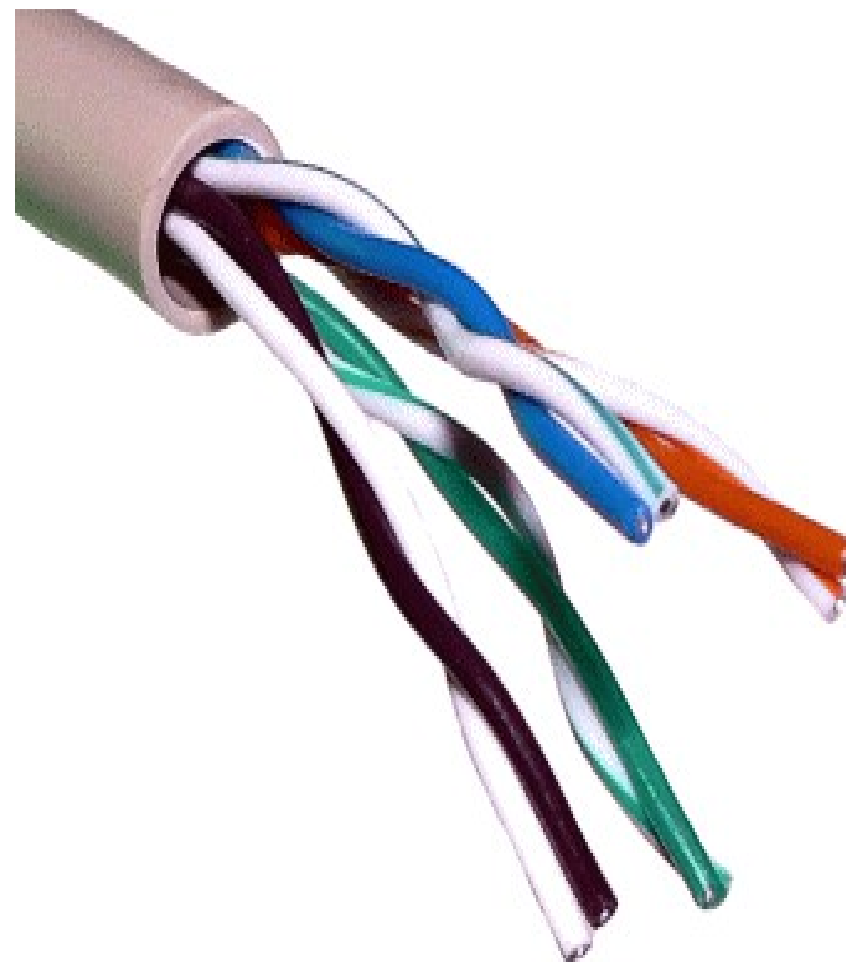
Chapter 5 - Channels

Channel

- *Channel*: refers either a physical transmission medium such as a wire, or to a logical connection over a multiplexed medium such as a radio channel
- A channel is used to convey an information signal from one or several **transmitters** to one or several **receivers**
- *Channel capacity*: is the maximum quantity of information that can be reliably transmitted measured in:
 - Bandwidth (Hz)
 - Data rate (bits / second)

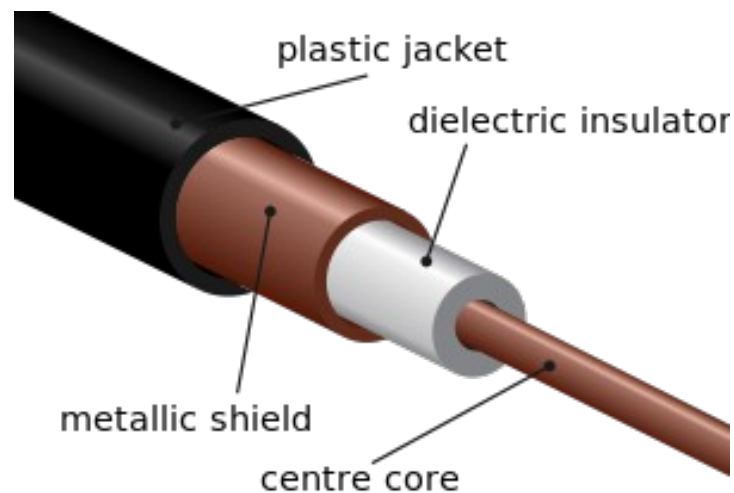
Copper Wires

- *Unshielded Twisted Pair (UTP)*: Primary medium to connect computers because it is **inexpensive** and **easy to install**
- **Twist limit interferences** emitted and prevent interferences from other wires
- Used for computer networks because it have a low resistance to electric current and **signals can travel farther**



Copper Wires

- Coaxial Cable: is single wire surrounded by a **heavy metal shield** that prevent interferences from itself and to other wires (better then UTP cable).
- Can be placed in parallel to other cables
- Shielded Twisted Pair (STP): is a twisted pair copper wires surrounded by a metal shield
- This shield avoid interferences



Glass Fiber

- This medium **uses light** to transport data.
- The glass fiber is **encased in a plastic jacket** which allows the fiber to bend without breaking.
- It is **more reliable** than copper wire, because it uses light, so:
 - It doesn't emit electrical interference
 - It is not susceptible to electrical interference
- Glass fiber can carry a pulse of light **much farther** than a copper wire because it is manufactured to reflect most of light inside of cable



Radio - Wireless

- Electromagnetic radiation can be used to transmit computer data
- Each participating computer **attaches to an antenna** which can both transmit and receive RF (Radio Frequency)
- Antenna may be large or small, depending on the range desired.
- Large to communicate at several miles or small within a building.

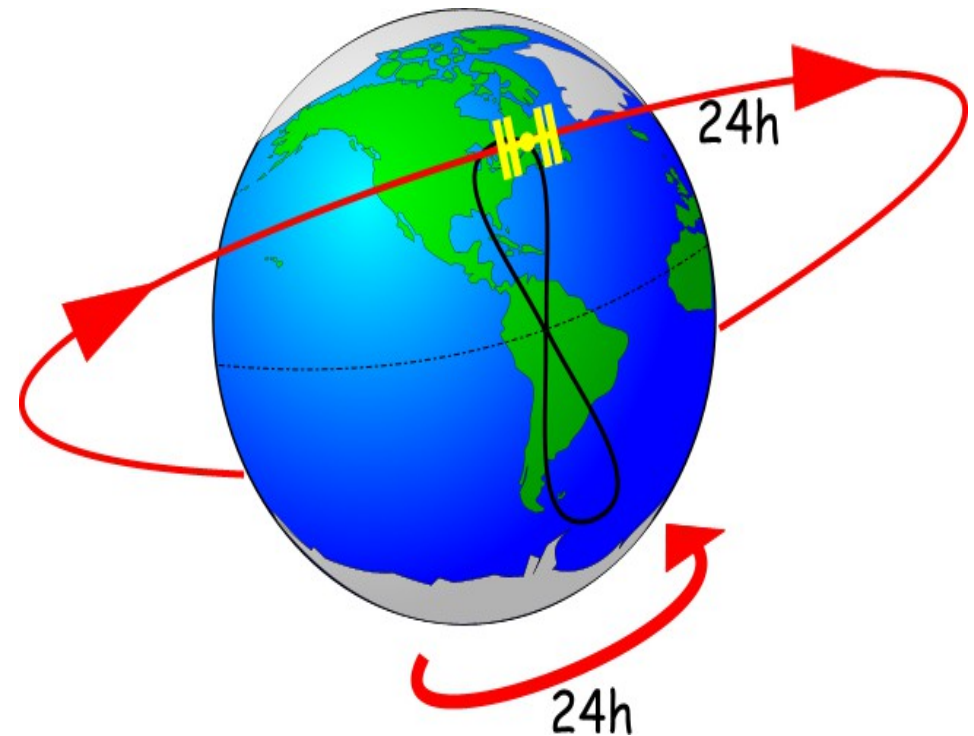


Satellite

- Satellite contains a **transponder** that consist of a radio receiver and transmitter
- Transponder accepts an incoming radio transmission, amplifies it, and re-transmits, amplified signal, back to the ground at a different angle than it arrived.
- A single satellite contains multiple transponders that operate independently because place a satellite in orbit it is very expensive

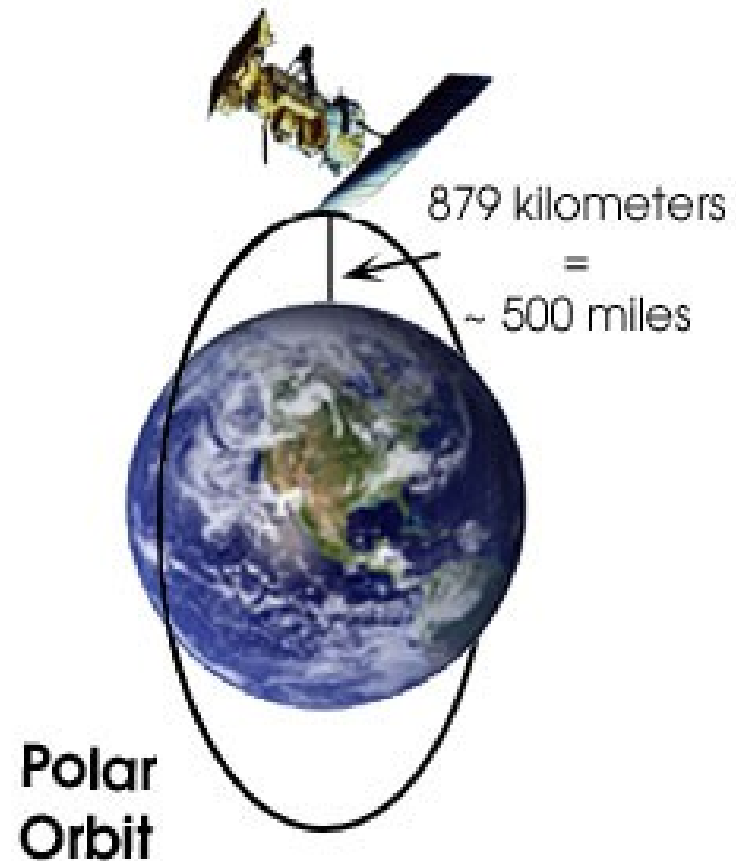
Geosynchronous Satellite (GEO)

- These satellites are placed in an orbit that is **exactly synchronized** with the rotation of the earth. (also called Geostationary satellites)
- From the ground these satellites appears to remain at exactly the same point in the sky at all times
- The distance required for a geosynchronous orbit is **35.785 km**

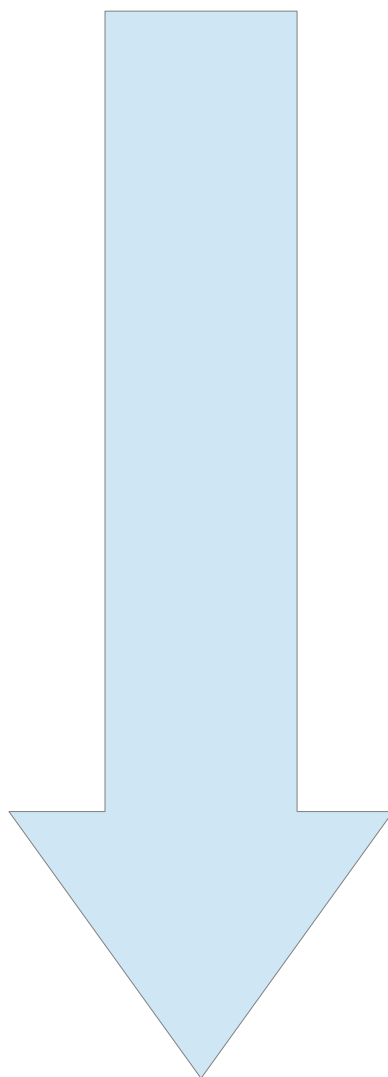


Low Earth Orbit Satellites (LEO)

- These satellites orbit a **few hundred miles** above the earth so their period of **rotation is faster** than the rotation of earth and they don't stay in a fixed point as geostationary.
- A satellite can only be used during the time that its orbit passes between two ground stations.
- Requires complex control system that continuously move the ground pointer to find new reachable satellites



Summary



- Signals
- Transmission
- Encoding
- Hamming Codes and Example
- CRC Codes
- RS - Codes
- Modulation
- Channels



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Thanks!

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