ADVANCED TOPICS IN MACHINE LEARNING

Learning Disentangled and Structured representations: A Causal Perspective

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Main Message:

 $\hfill\square$ The importance of the interventional formulation

Motivation

It's made of things, atoms, information.

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When describing the world we provide models of it.

Model	Predict in i.i.d. setting	Predict under distr. shift/intervention	Answer counter- factual questions	Obtain physical insight	Learn from data
	setting	sintervenuon	factual questions	physical insight	uata
Mechanistic/physical	yes	yes	yes	yes	?
Structural causal	yes	yes	yes	?	?
Causal graphical	yes	yes	no	?	?
Statistical	yes	no	no	no	yes

Figure 1: Credits: Towards Causal Representation Learning - Schölkopf et al. (2021)

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- Physical: differential equations $i\hbar\partial_t\psi=\hat{H}\,\psi$

 $T_b \rightarrow T_t$

 T_b : bottom theory, fine-grained, referred to low-level objects T_t : top theory, coarse-grained, associated with high-level entities De Haro, *Towards a theory of emergence for the physical sciences* (2019)





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Our case study:

1. We consider high-level entities which originate a lower-level representation



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- 2. We require that such a map exists and can be inferred
- 3. We try to learn from data high-level entities/representations, but in cases where we have control



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Generative Models

A small dive into Generative Models



Figure 3: Credits: Dall'Asen N., SML-Journal Club presentation.

Our focus: Variational Autoencoders (VAEs)

Kingma and Welling, Autoencoding Variational Bayes (2014)

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$$p(\mathbf{x}) = \int p^*(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) \mathrm{d}\mathbf{z} = \mathbb{E}_{p(\mathbf{z})}[p^*(\mathbf{x}|\mathbf{z})] \quad ext{where} \ \ \mathbf{x} \in \mathbb{R}^D \ \ ext{and} \ \ \mathbf{z} \in \mathbb{R}^k$$

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$$\begin{split} \log p_{\theta}(\mathbf{x}) &= \log \int p_{\theta}(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) \mathrm{d}\mathbf{z} \\ &= \log \int p_{\theta}(\mathbf{x}|\mathbf{z}) p(\mathbf{z}) \frac{q_{\phi}(\mathbf{z}|\mathbf{x})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \mathrm{d}\mathbf{z} \\ &\geq \int q_{\phi}(\mathbf{z}|\mathbf{x}) \log p_{\theta}(\mathbf{x}|\mathbf{z}) \frac{p(\mathbf{x})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \mathrm{d}\mathbf{z} \\ &= \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [p_{\theta}(\mathbf{x}|\mathbf{z})] - \mathrm{KL}(q_{\phi}(\mathbf{z}|\mathbf{x})) || p(\mathbf{z})) \end{split}$$

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ELBO from likelihood:

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where $p_{\theta}(\mathbf{x}|\mathbf{z})$ is our generative ansatz, $q_{\phi}(\mathbf{z}|\mathbf{x})$ is the approximate posterior, and $p(\mathbf{z})$ is the prior for the model. Learning parameters θ and ϕ .

VAEs in Deep Learning



 \Box We can sample from $p(\mathbf{z})$ and create new examples.

 \Box ELBO only lower-bounds the log-likelihood, but it has good properties when $\mathbf{z} \in \mathbb{R}^D$ Reizinger: Embracing the gap: VAEs perform independent mechanisms analysis (2022)

 \Box Endless number of variants:

 β-VAEs 	 DIP-VAEs 	 HVAEs
 Info-VAEs 	 Regularized-AEs 	 JL1-VAEs
 Total-Correlation VAEs 	 Factor-VAE 	•

Disentangled mechanisms

$1.\ \mbox{Hypothesis}$ on the world

For each datum x, we can associate a set of elements g (even stochastic) which describe it in an approximate way.



Figure 4: Example of a datum to which we associate a sets of concepts which describe it.

binding :
$$i: \mathbf{X} \to \mathbf{G}$$

Achille and Soatto, On the Learnability of Physical Concepts: Can a Neural Network Understand What's Real? (2022).

2. The generative mechanism

In simple cases, all possible variations on ${\bf X}$ can be reconducted to changes on ${\bf G}$ + noise. E.g., synthetic datasets, robotic systems, virtual world, etc.



 $\mathrm{generative\ process:}\quad g:(G,N)\to X$

where ${\bf N}$ is a noise term (or $\mathit{nuissance}).$ ${\bf G}$ are called generative factors.

Independent Mechanisms

□ We ground our construction on a Causal Perspective - Schölkopf et al. (2021) We look at DAGs: $p(G) = \prod_i p(G_i | \mathbf{PA}_i)$

The decomposition of a DAG implies a structure of statistical independence among variables $(i \neq j)$:

 $P(G_i | \mathbf{PA}_i) \perp P(G_j | \mathbf{PA}_j)$

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- 1. no influence: changing one mechanism $P(G_i | \mathbf{PA}_i)$ does not change other mechanisms $P(G_i | \mathbf{PA}_i)$;
- 2. no information: knowing some other mechanisms $P(G_i | \mathbf{PA}_i)$ does not give us information about a mechanism $P(G_j | \mathbf{PA}_j)$.

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generative process : $\mathbf{C} \to \mathbf{G} \to X$

Credits: Suter et al., Robustly Disentangled Causal Mechanisms (2019)

What are the disentangled factors?

 \Box 3D-Shapes dataset.

 $G_1 =$ floor hue: 10 values linearly spaced in [0, 1] $G_2 =$ wall hue: 10 values linearly spaced in [0, 1] $G_3 =$ object hue: 10 values linearly spaced in [0, 1] $G_4 =$ scale: 8 values linearly spaced in [0, 1] $G_5 =$ shape: 4 values in [0, 1, 2, 3] $G_6 =$ orientation: 15 values linearly spaced in [-30, 30]



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 \Box SCM formulation:

$$\begin{split} \mathbf{C} &\leftarrow \mathbf{N}_c \\ G_i &\leftarrow f_i(\mathbf{PA}_i^C, N_i), \quad \mathbf{PA}_i^C \subset \{C_1, \dots, C_L\}, \ i = 1, \dots, K \\ \mathbf{X} &\leftarrow g(\mathbf{G}, N_x) \\ Z_j &\leftarrow e_j(\mathbf{X}, (N_z)_j) \end{split}$$



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- 2. In general, the latent factors can be dependent

 $G_i \perp G_j, i \neq j$

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3. There is no total causal effect from G_i to G_j , for $i \neq j$; i.e., intervening on G_j does not change G_i , i.e.,

$$\forall \boldsymbol{g}_j^{\bigtriangleup}, \ \boldsymbol{p}(\boldsymbol{g}_j | \mathrm{do}(\boldsymbol{G}_j \leftarrow \boldsymbol{g}_j^{\bigtriangleup})) = \boldsymbol{p}(\boldsymbol{g}_i) \ \left(\neq \boldsymbol{p}(\boldsymbol{g}_i | \boldsymbol{g}_j^{\bigtriangleup}) \right)$$

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4. The remaining components of \mathbf{G} , i.e. \mathbf{G}_{-j} , are a valid adjustment set to estimate interventional effects from G_j to \mathbf{X} based on observational data, i.e.,

$$p(\mathbf{x}|\mathrm{do}(G_{j}\leftarrow g_{j}^{\bigtriangleup}))=\int p(\mathbf{x}|g_{j}^{\bigtriangleup},\mathbf{g}_{-j})p(\mathbf{g}_{-j})\mathrm{d}\mathbf{g}_{-j}$$

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5. If there is no confounding, conditioning is sufficient to obtain the post-interventional distribution of \mathbf{X} :

$$p(\mathbf{x}|\mathrm{do}(G_j\leftarrow g_j^{\bigtriangleup}))=p(\mathbf{x}|g_j^{\bigtriangleup})$$

A remark on do-calculus

 $p(\mathbf{G}_{-j},\mathbf{C}|\mathrm{do}(\mathit{G}_{j}\leftarrow \mathit{g}_{j})) \neq p(\mathbf{G}_{-j},\mathbf{C}|\mathit{g}_{j})$



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We define the interventional effect of a group of generative factors G_I on the implied latent space encodings Z_J with proxy posterior $q_{\phi}(\mathbf{z}|\mathbf{x})$ from a VAE (or variant), where $I \subset \{1, \ldots, K\}$ and $J \subset \{1, \ldots, k\}$ as:

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Meaning of a disentangled representation:

Variations of a single latent factor Z_j depends on at most one generative factor G_i variations:

$$Z_j \leftarrow \alpha_j(g_{\pi(j)}, N_j)$$



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where α_j is a general (non-linear) function for $j = 1, \ldots, d$, $\pi : \{1, \ldots, d\} \rightarrow \{1, \ldots, K\} \cup \emptyset$ an element-wise correspondence, $\alpha_j(g_{\emptyset}, N_j) = \alpha_j(N_j)$, and N_j are independent noise terms.



Disentangled representations.

How to measure Disentanglement of the representations

There have been many proposals to measure it, but none of them is optimal Do and Tran, Theory and Evaluation for Learning Disentangled Representations (2020);

Carbonneau et al., Measuring Disentanglement: A Review of Metrics (2022).



Figure 5: Taxonomy of (some) known metrics.

A quick look at IRS (Interventional Robustness Score), from Suter et al. (2019):

$$\textit{PIDA}(l|i,j) := d\Big(\mathbb{E}[z_l | \text{do}(G_i \leftarrow g_i)], \mathbb{E}[z_l | \text{do}(G_i \leftarrow g_i), \text{do}(G_j \leftarrow g_j)]\Big)$$

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$$\textit{PIDA}(\textit{I}|i,j) := \textit{d} \left(\mathbb{E}[\textit{z}_l | \text{do}(\textit{G}_i \leftarrow \textit{g}_i)], \mathbb{E}[\textit{z}_l | \text{do}(\textit{G}_i \leftarrow \textit{g}_i), \text{do}(\textit{G}_j \leftarrow \textit{g}_j)] \right)$$

and when:

$$PIDA \rightarrow 0 \forall I \implies IRS \rightarrow 0$$

Learning Disentangled Representations

Can we learn disentangled representations in unsupervised settings? No, (i) without implicit bias or (ii) without supervision.

Locatello et al., Challenging Common Assumptions in the Unsupervised Learning of Disentangled Representations (2019)

Learning Disentangled Representations

Can we learn disentangled representations in unsupervised settings? No, (i) without implicit bias or (ii) without supervision.





Figure 6: Drastical variations of the obtained disentangled (a) upon changing the VAE variant and (b) the regularization strength.

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Hungry for Theorems? Check Shu et al., Weakly Supervised Disentanglement with Guarantees (2020).

Other formulations

Formal definitions of disentangled representations:

- ✓ Causal Disentanglement
- □ Identifiability in Non-linear Independent Component Analysis (ICA)
- □ Group-based Disentanglement

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Definition 1.(Identifiability) Independent component analysis in $(\mathcal{F}, \mathcal{P})$ is identifiable up to S if for functions $f, f' \in \mathcal{F}$ and distributions $\mathbb{P}, \mathbb{P}' \in \mathcal{P}$ the relation

 $f(s) = {}^{\mathcal{D}} f'(s') \quad ext{where} \ \ s \sim \mathbb{P} \ \ ext{and} \ \ s' \sim \mathbb{P}'$

implies that there is $h \in S$ that $h = f'^{-1} \circ f$ on the support of \mathbb{P} .

Buchholz et al., Function Classes for Identifiable Nonlinear Independent Component Analysis (2022).

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Causal Disentanglement and Identifiability in non-linear ICA have been reconciled:

 Theorem 11 in Wang and Jordan, Desiderata for Representation Learning: a Causal Perspective (2021). Identifiability up to permutations h ∈ S_{perm}. There exist a product group $\mathbb{G}=\mathbb{G}_1\times\ldots\times\mathbb{G}_{\mathcal{K}}$ acting on G. Condition for disentanglement:

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- There is a decomposition $\mathbf{Z} = Z_1 \oplus \ldots \oplus Z_d$ such that each Z_i is fixed by the action of all \mathbb{G}_k , $k \neq j$ and affected only by \mathbb{G}_j .

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 \Box The group acting on G_i can be complicated.

 \Box There is no statistical notion in this formulation (yet).

We proposed a definition of Interpretability as alignment between generative factors and the representations:

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where α_j is a **monotonic** function for j = 1, ..., d, $\pi : \{1, ..., d\} \rightarrow \{1, ..., K\} \cup \emptyset$ an element-wise correspondence, $\alpha_j(g_{\emptyset}) = 0$ and N_i are independent noise terms.

Marconato, Passerini, and Teso, Glancenets: Interpretable, Leak-proof Concept-based Models

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Identifiability (up to permutations) \implies Alignment \implies Disentanglement

Disentanglement in OOD scenarios: (1) combinationial generalization and (2) concept leakage.

Disentanglement in Real-World scenarios: ViT and stuff like that.

Learning Causal Mechanisms: integration of interventions in learning.

Equivariance in representations: Geometric Deep Learning.

Thank you for the attention!

Interested in a thesis?

- Project works in this field
- Connection between causal and group-based disentanglement
- Unsupervised discovery of concepts through Neuro-Symbolic integration

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