

Distributional Semantics

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Linear equation

A linear equation is an algebraic equation in which each term is either a constant or the *product of a constant and a single variable*. E.g. a two variables x and y is $y = mx + b$, where m and b designate constants.

The origin of the name “*linear*” comes from the fact that the set of solutions of such an equation forms a *straight line* in the plane.

The general linear equation in n variables is:

$$a_1x_1 + a_2x_2 + \cdots + a_nx_n = b$$

In this form, a_1, a_2, \dots, a_n are the coefficients, x_1, x_2, \dots, x_n are the variables, and b is the constant.

Such an equation will represent an $(n - 1)$ -dimensional hyperplane in n -dimensional Euclidean space (or in our case n -dimensional vector space)

Background: Vector and Matrix

Vector Space

A vector space is a mathematical structure formed by a collection of vectors: objects that may be added together and multiplied (“scaled”) by numbers, called scalars in this context.

Vector an n-dimensional vector is represented by a column:

$$\begin{bmatrix} v_1 \\ \dots \\ v_n \end{bmatrix}$$

or for short as $\vec{v} = (v_1, \dots, v_n)$.

Background: Vector and Matrix

Operations on vectors

Vector addition:

$$\vec{v} + \vec{w} = (v_1 + w_1, \dots, v_n + w_n)$$

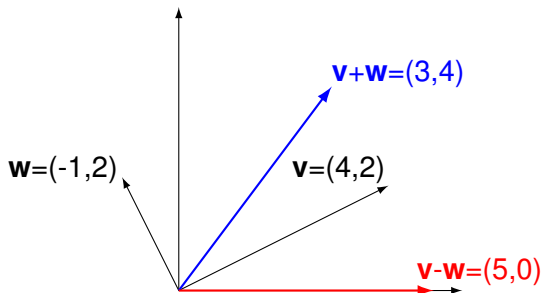
similarly for the $-$.

Scalar multiplication: $c\vec{v} = (cv_1, \dots, cv_n)$ where c is a “scalar”.

Background: Vector and Matrix

Vector visualization

Vectors are visualized by arrows. They correspond to points (the point where the arrow ends.)



vector addition produces the diagonal of a parallelogram.

Background: Vector

Length

$$\text{Length } \|\vec{v}\| = \sqrt{\vec{v} \cdot \vec{v}} = \sqrt{\sum_{i=1}^n v_i^2}$$

	d1,	d2,	d3,	d4,	d5,	d6,	d7,	d8	
w1	=	(3,	3,	3,	3,	0,	0,	0,	0)
w2	=	(1,	1,	1,	1,	0,	0,	0,	0)
w3	=	(0,	0,	0,	0,	1,	1,	1,	1)

$$\|\vec{w1}\| = \sqrt{9 + 9 + 9 + 9} = \sqrt{36} = 6$$

$$\|\vec{w2}\| = \sqrt{1 + 1 + 1 + 1} = \sqrt{4} = 2$$

$$\|\vec{w3}\| = \sqrt{1 + 1 + 1 + 1} = \sqrt{4} = 2$$

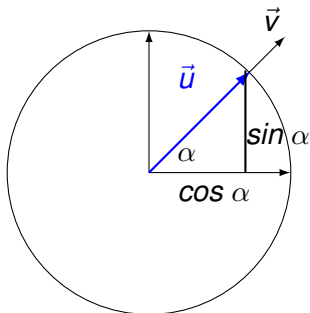
Background: Vector

Unit vector

Unit vector is a vector whose length equals one.

$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|}$$

is a unit vector in the same direction as \vec{v} . (normalized vector)



$$\vec{u} = \frac{\vec{v}}{\|\vec{v}\|} = (\cos \alpha, \sin \alpha)$$

Background: Vectors

Dot product or inner product

$$\vec{v} \cdot \vec{w} = (v_1 w_1 + \dots + v_n w_n) = \sum_{i=1}^n v_i w_i$$

Example We have three goods to buy and sell, their prices are (p_1, p_2, p_3) (price vector \vec{p}). The quantities we are buy or sell are (q_1, q_2, q_3) (quantity vector \vec{q} , their values are positive when we sell and negative when we buy.) Selling the quantity q_1 at price p_1 brings in $q_1 p_1$. The total income is the *dot product*:

$$\vec{q} \cdot \vec{p} = (q_1, q_2, q_3) \cdot (p_1, p_2, p_3) = q_1 p_1 + q_2 p_2 + q_3 p_3$$

Inner product: example

	d1,	d2,	d3,	d4,	d5,	d6,	d7,	d8
w1	3,	3,	3,	3,	0,	0,	0,	0
w2	1,	1,	1,	1,	0,	0,	0,	0

$$\vec{w1} \cdot \vec{w2} = \sum_i w1_i \times w2_i = (3 \times 1) + (3 \times 1) + (3 \times 1) + (3 \times 1) = 12$$

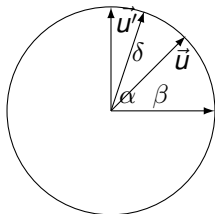
Background: Vector

Cosine formula

Given δ the angle formed by the two unit vectors \vec{u} and \vec{u}' , s.t.

$$\vec{u} = (\cos \beta, \sin \beta) \text{ and } \vec{u}' = (\cos \alpha, \sin \alpha)$$

$$\vec{u} \cdot \vec{u}' = (\cos \beta)(\cos \alpha) + (\sin \beta)(\sin \alpha) = \cos(\beta - \alpha) = \cos \delta$$



Given two arbitrary vectors v and w :

$$\cos \delta = \frac{\vec{v}}{\|\vec{v}\|} \cdot \frac{\vec{w}}{\|\vec{w}\|}$$

The bigger the angle δ , the smaller is $\cos \delta$; $\cos \delta$ is never bigger than 1 (since we used unit vectors) and never less than -1. It's 0 when the angle is 90°

Cosine Similarity

Example

$$\cos(\vec{x}, \vec{y}) = \frac{\vec{x} \cdot \vec{y}}{\|\vec{x}\| \|\vec{y}\|} = \frac{\sum_{i=1}^n x_i \times y_i}{\sqrt{\sum_{i=1}^n x_i^2} \times \sqrt{\sum_{i=1}^n y_i^2}}$$

	d1,	d2,	d3,	d4,	d5,	d6,	d7,	d9
w1 =	(3,	3,	3,	3,	0,	0,	0,	0)
w2 =	(1,	1,	1,	1,	0,	0,	0,	0)
w3 =	(0,	0,	0,	0,	1,	1,	1,	1)

$$\cos(\vec{w}_1, \vec{w}_2) = \frac{\vec{w}_1 \cdot \vec{w}_2}{\|\vec{w}_1\| \times \|\vec{w}_2\|} = \frac{(3 \times 1) + (3 \times 1) + (3 \times 1) + (3 \times 1)}{6 \times 2} = \frac{12}{12}$$

$$\cos(\vec{w}_1, \vec{w}_3) = \frac{\vec{w}_1 \cdot \vec{w}_3}{\|\vec{w}_1\| \times \|\vec{w}_3\|} = \frac{0}{6 \times 2} = \frac{0}{12} = 0$$

Background: Matrix

Matrices multiplication

A matrix is represented by [nr-rows x nr-columns].

Eg. for a 2 x 3 matrix, the notation is:

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix}$$

a_{ij} i stands for the row nr, and j stands for the column nr.

The multiplication of two matrices is obtained by

Rows of the 1st matrix x columns of the 2nd.

A matrix with m-columns can be multiplied only by a matrix of m-rows:

$$[n \times m] \times [m \times k] = [n \times k].$$

Background: Vector and Matrix

A matrix acts on a vector

Example of 2 x 2 matrix multiplied by a 2 x 1 matrix (viz. a vector). Take A and \vec{x} to be as below.

$$\begin{aligned} A\vec{x} &= \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} (1, 0) \cdot (x_1, x_2) \\ (-1, 1) \cdot (x_1, x_2) \end{bmatrix} = \begin{bmatrix} 1(x_1) + 0(x_2) \\ -1(x_1) + 1(x_2) \end{bmatrix} = \\ &= \begin{bmatrix} x_1 \\ x_2 - x_1 \end{bmatrix} = \vec{b} \end{aligned}$$

A is a “difference matrix”: the output vector \vec{b} contains differences of the input vector \vec{x} on which “the matrix has acted.”